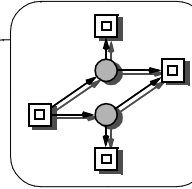


# (INFORMAL) INTRODUCTION INTO PETRI NETS MODELLING



## PETRI NETS, BASICS 1

### (1) NODES

places



“passive elements”  
conditions  
states  
“chem. compounds”

transitions

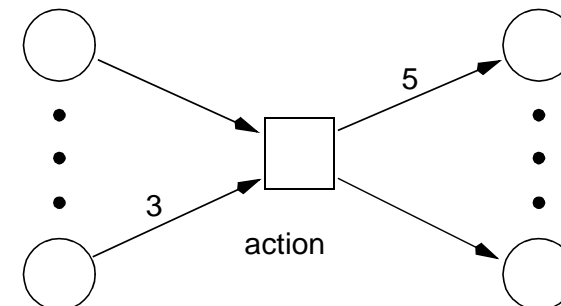


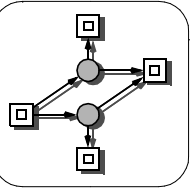
“active elements”  
events  
actions  
“chem. reactions”

### (2) ARCS

preconditions

postconditions








## PETRI NETS, BASICS 2

### (3) TOKENS

(moving objects,  
vehicles, work pieces, control flow pointer,  
dates,..., *units of substances* (e. g. *Mol*), ...)

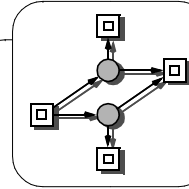
-  condition is not fulfilled
-  condition is (one times) fulfilled
-  condition is n times fulfilled

### (4) MARKING

(system state, *substance distribution*)

How many tokens are on each place?

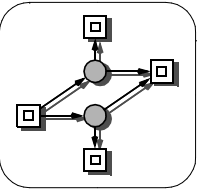
-> initial marking



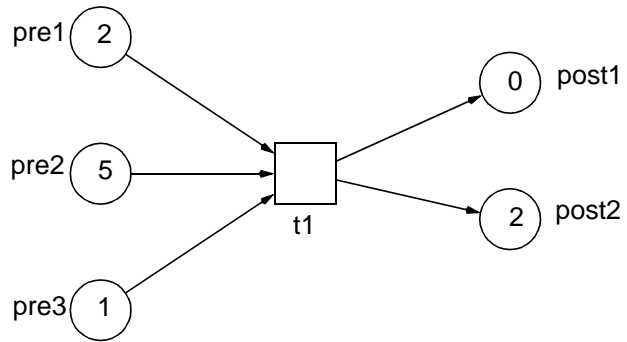
## PETRI NETS, BASICS 3

### (5) FLOW OF TOKENS

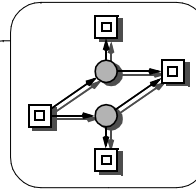
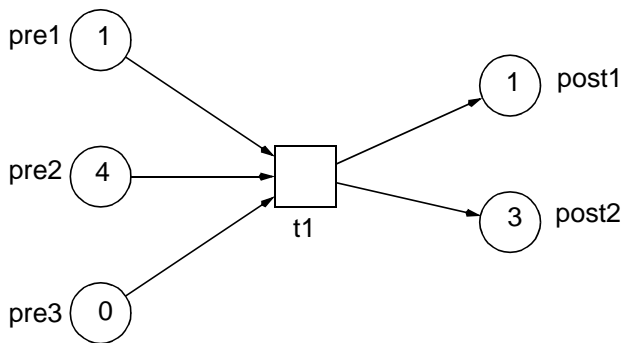
- an action **may** happen, if
  - > all preconditions  
are fulfilled  
(corresponding to the arc weights);
- if** an action happens, **then**
  - > tokens are removed  
from all preconditions  
(corresponding to the arc weights), and
  - > tokens are added  
to all postconditions  
(corresponding to the arc weights);
- an action happens  
(firing of a transition)
  - > atomic
  - > time-less



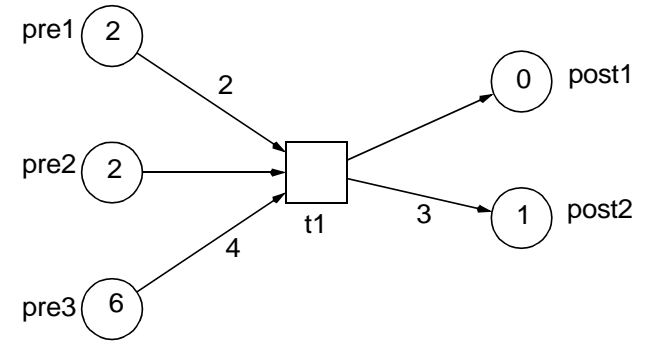
### FIRING RULE, EXAMPLE 1



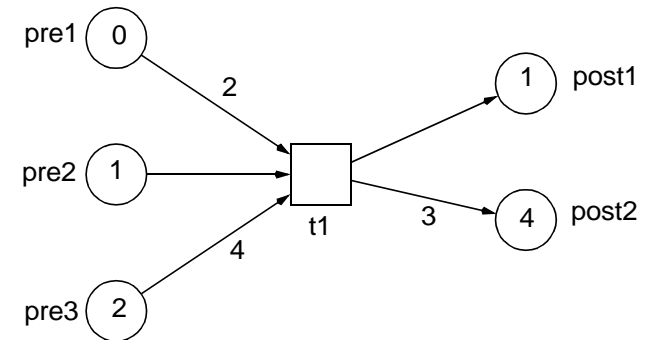
t1 fires

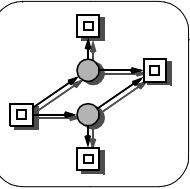


### FIRING RULE, EXAMPLE 2



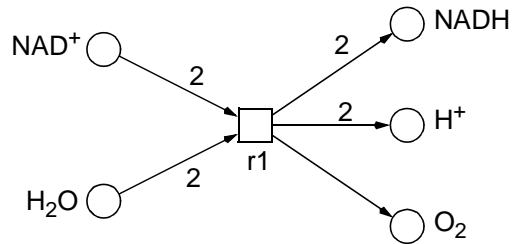
t1 fires



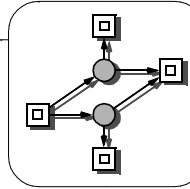
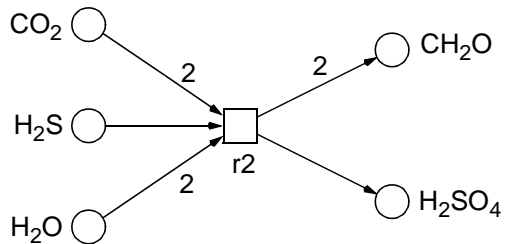


### EXAMPLE 1, CHEMICAL REACTION EQUATIONS

- FOR LIGHT-INDUCED PHOSPHORYLATION  
 $2 \text{NAD}^+ + 2 \text{H}_2\text{O} \rightarrow 2 \text{NADH} + 2 \text{H}^+ + \text{O}_2$

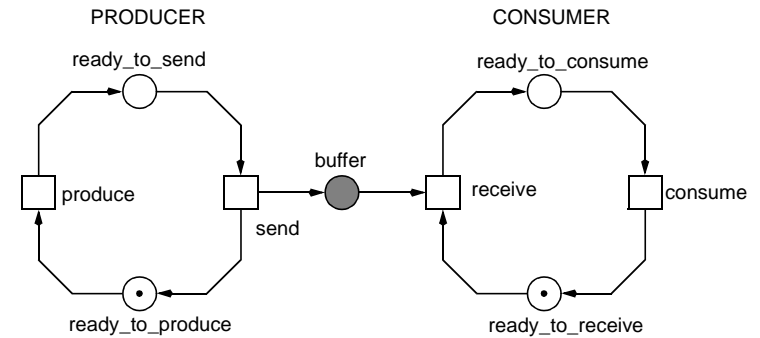


- FROM THE PHOTOSYNTHESIS  
 $2 \text{CO}_2 + \text{H}_2\text{S} + 2 \text{H}_2\text{O} \rightarrow 2 (\text{CH}_2\text{O}) + \text{H}_2\text{SO}_4$

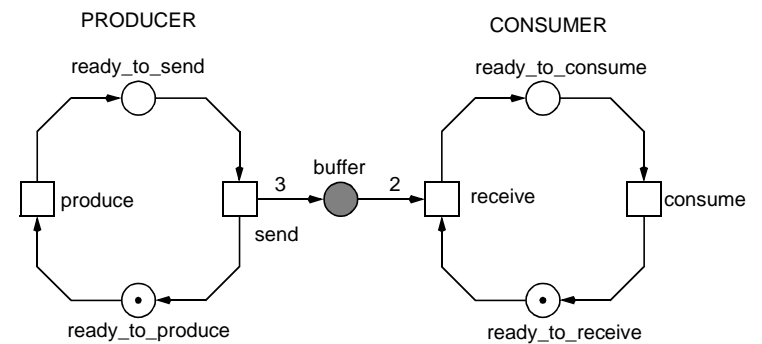


### EXAMPLE 2, PRODUCER/CONSUMER, UNBOUNDED

- SYSTEM WITHOUT ARC WEIGHTS

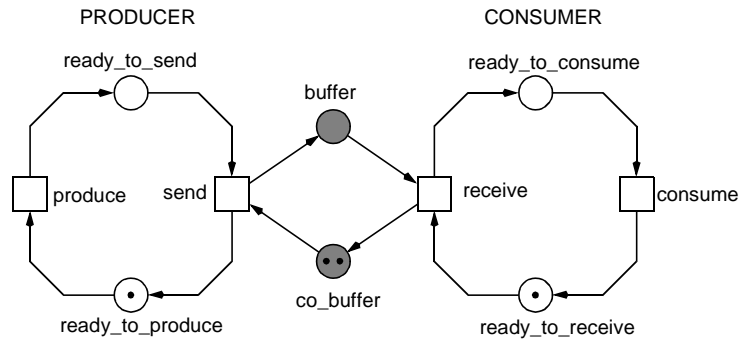


- SYSTEM WITH ARC WEIGHTS

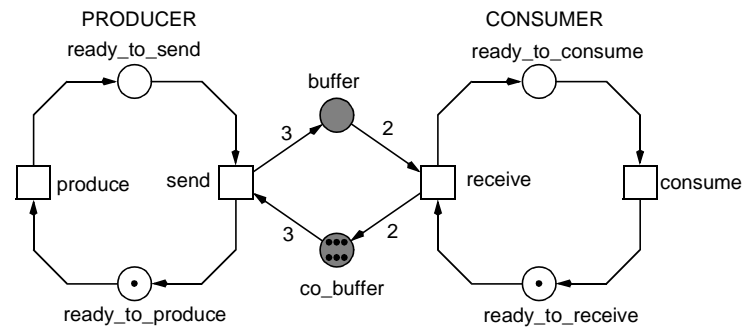


### EXAMPLE 3, PRODUCER/CONSUMER, BOUNDED

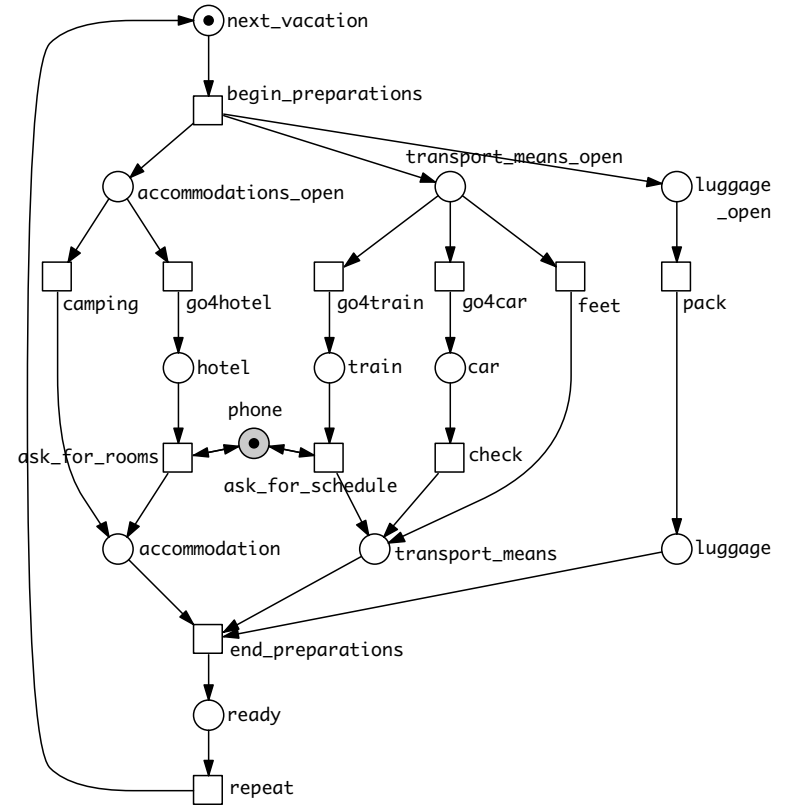
#### SYSTEM WITHOUT ARC WEIGHTS

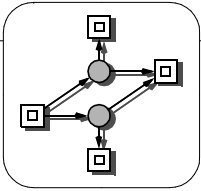


#### SYSTEM WITH ARC WEIGHTS



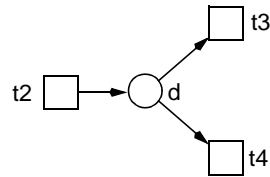
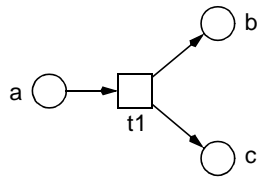
### EXAMPLE 4, TRAVEL PREPARATION



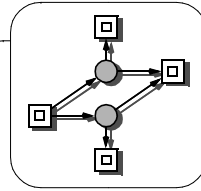
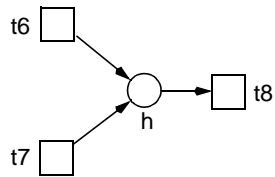
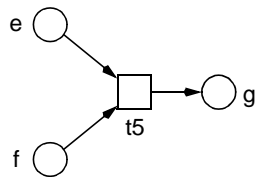


### TYPICAL BASIC STRUCTURES 0

#### FORWARD BRANCHING

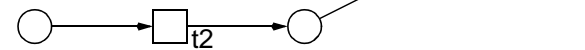
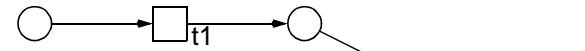
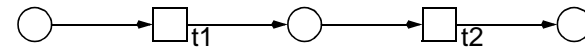


#### BACKWARD BRANCHING



### TYPICAL BASIC STRUCTURES 1

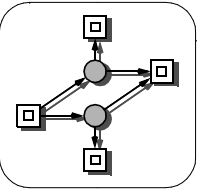
#### NECESSARY CONDITION



#### SUFFICIENT CONDITION

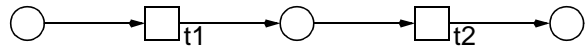


-> CAUSAL RELATION  
"X HAS TO HAPPEN BEFORE Y"

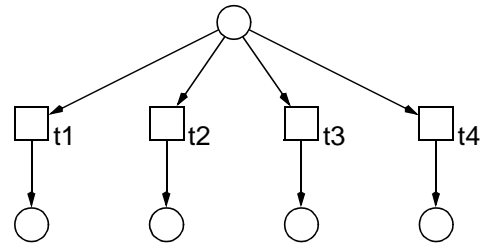


### TYPICAL BASIC STRUCTURES 2

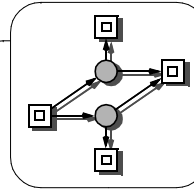
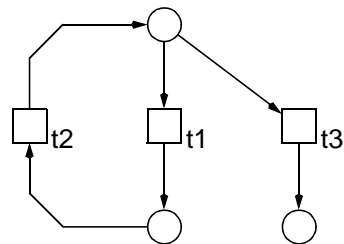
#### SEQUENCE OF ACTIONS



#### BRANCHING / ALTERNATIVES

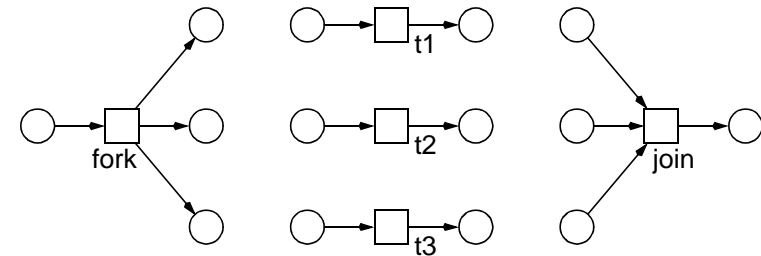


#### REPETITION

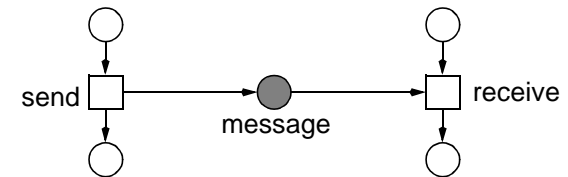


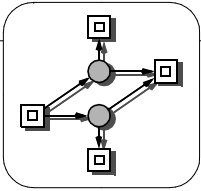
### TYPICAL BASIC STRUCTURES 3

#### CONCURRENCY



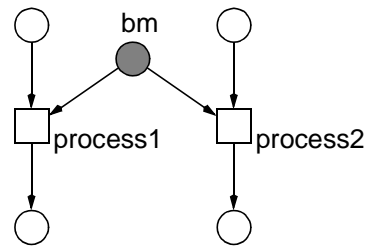
#### COMMUNICATION / SYNCHRONISATION



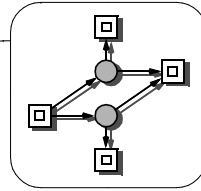
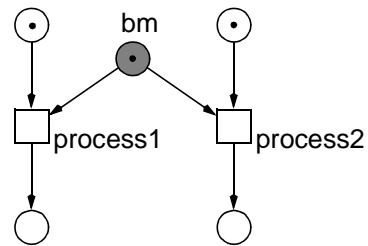


### TYPICAL BASIC STRUCTURES 4

#### STATIC CONFLICT

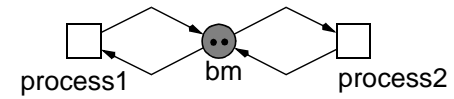


#### DYNAMIC CONFLICT

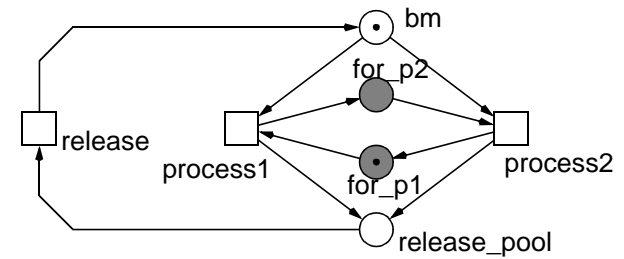


### TYPICAL BASIC STRUCTURES 5

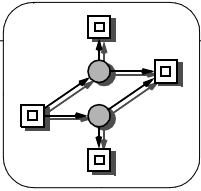
#### FREE OF DYNAMIC CONFLICTS, EX. 1



#### FREE OF DYNAMIC CONFLICTS, EX. 2

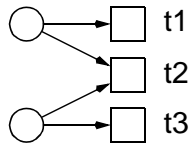






## TYPICAL BASIC STRUCTURES 6

### ❑ CONFUSION



### ❑ concurrency and conflict overlap

->  $t1 \# t2$  and  $t2 \# t3$ ,  
but  $t1$  concurrent to  $t3$

### ❑ case 1: $t1 < t3$

-> *conflict  $t2 \# t3$  disappears,*  
*firing of  $t3$  does not involve a conflict decision*

### ❑ case 2: $t3 < t1$

-> *conflict  $t2 \# t3$  exists,*  
*firing of  $t3$  involves a conflict decision*

### ❑ the interleaving sequences of concurrency may encounter different amount of decisions

### ❑ an observer outside of the system does not know whether a decision took place or not