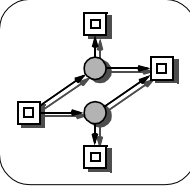
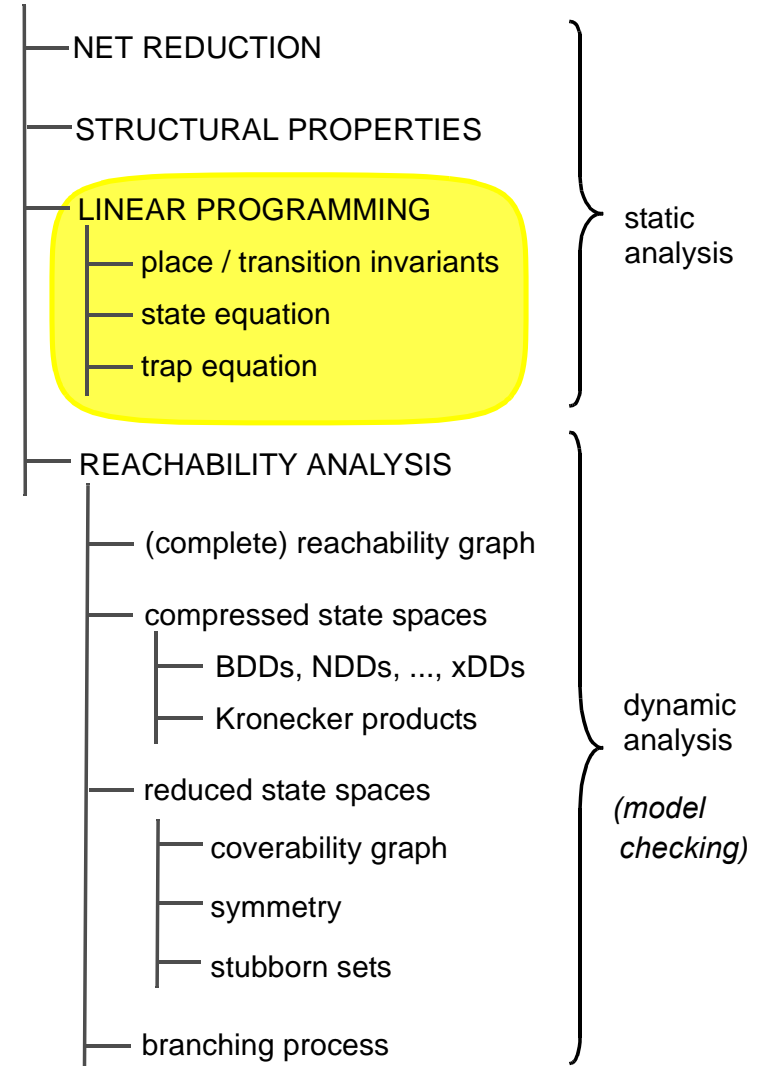
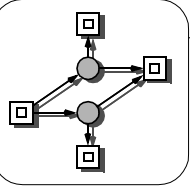


THE MUTEX PATTERN - DIFFERENT ANALYSIS APPROACHES



QUALITATIVE ANALYSIS METHODS, OVERVIEW





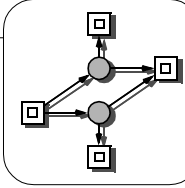
SEMAPHORE AS ADT

```
public class Semaphore {
    private int value;

    public Semaphore (int initial) {
        if (initial<0) {
            System.exit(1); // out of range error
        } else {
            value = initial;
        } // if
    } // Semaphore

    synchronized public void up() {
        ++value;
        notify();
    } // up

    synchronized public void down() {
        try {
            while (value==0) wait();
            --value;
        } catch (InterruptedException e){}
    } // down
} // class Semaphore
```



PATTERN OF BEHAVIOUR

```
class MutexLoop extends Thread {
    private Semaphore mutex;
    private char ch;

    MutexLoop (Semaphore sema, char toPrint) {
        mutex=sema;
        ch = toPrint;
    } // MutexLoop

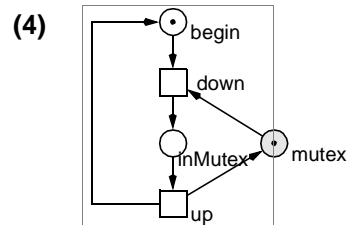
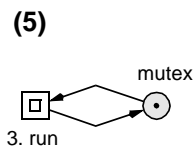
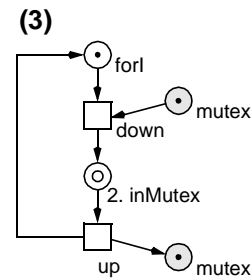
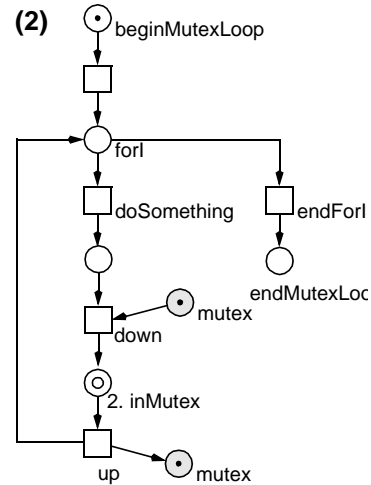
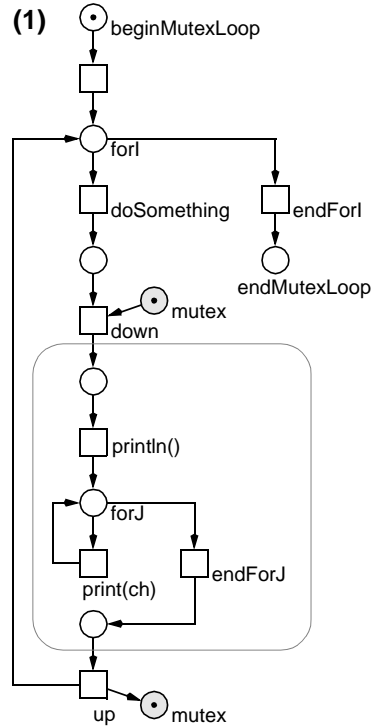
    public void run() {
        for (int i=0;i<MutexDemo.LENGTH;i++) {
            Simulate.doSomething();// pre action

            mutex.down();// get mutual exclusion
            System.out.println();
            for (int j=0;j<MutexDemo.MAX;j++) {
                System.out.print(ch);
            } // for
            mutex.up(); //release mutual exclusion

            Simulate.doSomething();// post action
        } // for

    } // run
} // class MutexLoop
```

PETRI NET MODEL, PATTERN OF BEHAVIOUR



APPLICATION MUTEXDEMO

```
public class MutexDemo {

    static final int MAX = 30; // line width to weave
    static final int LENGTH = 50; // number of lines

    public static void main (String[] argv) {

        Semaphore mutex = new Semaphore(1);

        Thread a = new MutexLoop(mutex, 'a');
        Thread b = new MutexLoop(mutex, 'b');
        // Thread c = new MutexLoop(mutex, 'c');

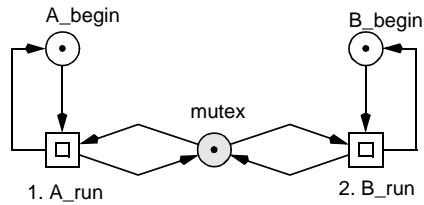
        System.out.println(" -- begin of MutexDemo -- ");

        a.start();
        b.start();
        // c.start();

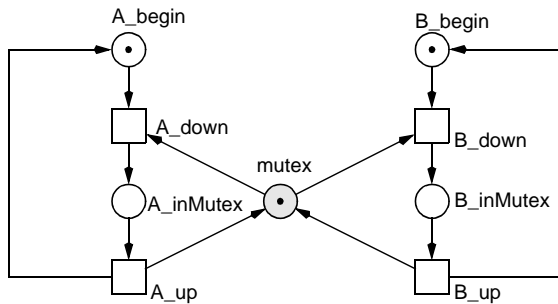
    } // main
} // class MutexDemo
```

PETRI NET MODEL, MUTEXDEMO

SYNCHRONIZATION SKELETON

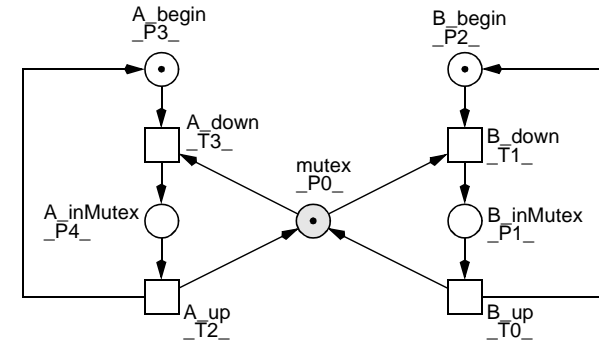


FLATTEN



ORD	HOM	NBM	PUR	CSV	SCF	CON	SC	Ft0	tF0	Fp0	pF0	MG	SM	FC	EFC	ES
Y	Y	Y	Y	N	N	Y	Y	N	N	N	N	N	N	N	N	Y
DTP	SMC	SMD	SMA	CPI	CTI	B	SB	REV	DSt	BSt	DTr	DCF	L	LV	L&S	
Y	Y	Y	Y	Y	Y	Y	Y	Y	N	?	N	N	Y	Y	Y	

MUTEXDEMO, ANALYSIS



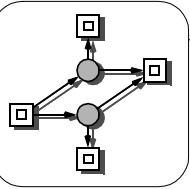
REQUIRED SAFETY PROPERTY

forever, there is at most one process in the mutex section (critical section)

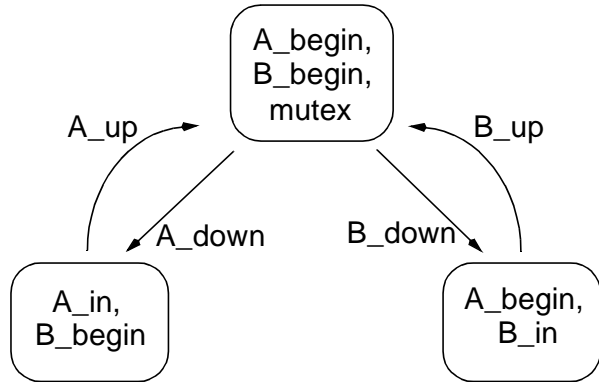
HOW TO ANALYZE IT ?

- (1) reachability graph
- (2) state equation
- (3) p-invariants, non-reachability check
- (4) p-invariants, reasoning

-
- (5) model checking of temporal formulae

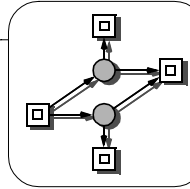


ANALYSIS OF MUTEXDEMO (1), REACHABILITY GRAPH



- > RG is finite
- > BND
- > 1 SC component, containing all transitions
- > LIVE & REV
- > no state with (A_in = 1 and B_in = 1) reachable
- > safety property is valid

in temporal logics:
 not EF (A_in and B_in)
 AG (not(A_in and B_in))



INCIDENCE MATRIX C- A REPRESENTATION OF THE NET STRUCTURE

	P+T	p1	card(P)	t1	card(T)
P+T					
p1		\emptyset			- PRE
card(P)					
t1			+ POST		\emptyset
card(T)					

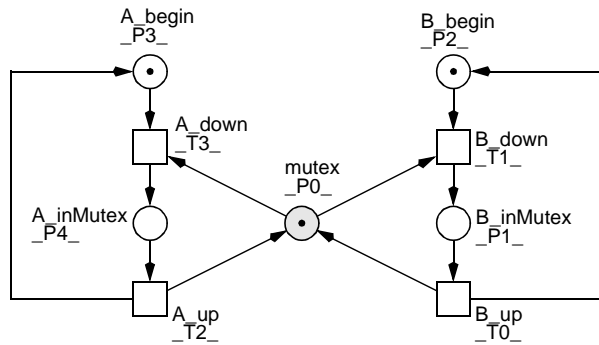
POST - PRE

	P	T	t1	...	tj	...	tm
P							
T							
p1							
:							
:							
pi					cij		
:							
pn							

$$c_{ij} = (p_i, t_j) = F(t_j, p_i) - F(p_i, t_j) = \Delta t_j(p_i)$$

-> token change
 in place p_i by firing of transition t_j

MUTEXDEMO, INCIDENCE MATRIX



P \ T	B_up	B_down	A_up	A_down
mutex	+1	-1	+1	-1
B_inMutex	-1	+1	0	0
B_begin	+1	-1	0	0
A_begin	0	0	+1	-1
A_inMutex	0	0	-1	+1

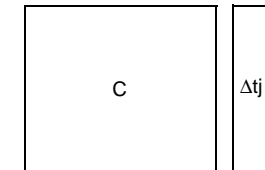
STATE EQUATION 1

incidence matrix C

P \ T	t1	tj	tm
p1		Δt_j	
pi		Δt_j	
pn		Δt_j	

PARIKH VECTOR
parikh(tj)

:	0	tj
:	1	
:	0	
:	0	
:	0	



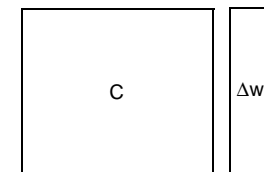
Δt_j - vector describing the change of the whole marking by firing of tj

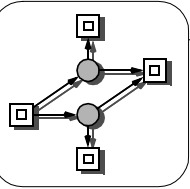
Let the word $w = t1-t0-t1-\dots$ be a sequence of firing transitions;

PARIKH VECTOR
parikh(w)

1	t0
2	
:	
:	
0	

The change of the marking Δw by firing that sequence can be computed by multiplying the incidence matrix C with the Parikh vector **parikh(w)** of that transition sequence.





STATE EQUATION 2

The new marking reached by firing the given transition sequence can then be computed by adding Δw to the current marking.

$$\begin{matrix} 1 & t_0 \\ 2 & t_1 \\ \cdot & \\ \cdot & \\ 0 & \\ \cdot & \\ \cdot & \end{matrix}$$

$$m = m_0 + C \Delta w$$

m_0 - initial marking
 m - new marking reached by firing of w

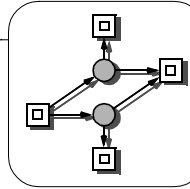
STATE EQUATION -> linear programming problem

$$\begin{matrix} m = m_0 + C x, & x \text{ - T-vector} \\ x \geq 0 \end{matrix}$$

There exists an integer solution for every reachable marking m (the Parikh vector of the transition sequence going to m).

-> the integer solvability is a necessary condition for the reachability of a marking;

-> **NON-REACHABILITY CHECK**
 if there is no integer solution, then the marking is not reachable.

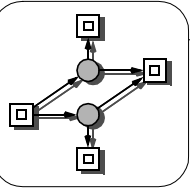


ANALYSIS OF MUTEXDEMO (2), STATE EQUATION

$$m = m_0 + C \cdot x$$

x_0
x_1
x_2
x_3

$$\begin{matrix} -1 = & +x_0 & -x_1 & +x_2 & -x_3 \\ 1 = & -x_0 & +x_1 & & \\ -1 = & +x_0 & -x_1 & & \\ -1 = & & & +x_2 & -x_3 \\ 1 = & & & -x_2 & +x_3 \end{matrix}$$



T-INVARIANTS

- Lautenbach, 1973

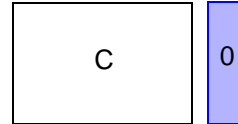
- T-invariants

-> *integer solutions x of*

$$Cx = 0, x \neq 0, x \geq 0$$

-> *Parikh vector*

-> *exponential complexity*



- **minimal** T-invariants

-> *there is no T-invariant with a smaller support*

-> *greatest common divisor (gcd) of all entries is 1*

- support

-> *set of transitions belonging to the T-invariant*

- any T-invariant is a non-negative linear combination of minimal ones

-> *multiplication with a positive integer*

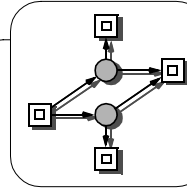
-> *addition*

-> *division by gcd*

$$kx = \sum_i a_i x_i$$

- Covered by T-Invariants (CTI)

-> *each transition belongs to a T-invariant*



T-INVARIANTS, INTERPRETATION

- T-invariants = (multi-) sets of transitions

-> *zero effect on marking*

-> *reproducing a marking / system state*

-> *steady state substance flows*

-> *elementary modes, Schuster 1993*

- the T-invariant corresponds to cycles in the RG, if the T-invariant is realizable

- in the RG, concurrency of transitions is described by all transitions' interleaving sequences

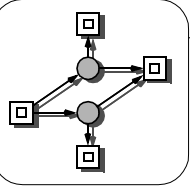
- if there are concurrent transitions in a realizable T-invariant, then there is a RG cycle for each interleaving sequence

-> *T-inv3, T-inv4*

- pre-sets of supports = post-sets of supports

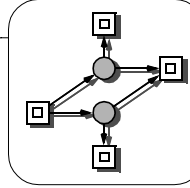
- a T-invariant defines a connected subnet

-> *the T-invariant's transitions (the support),
+ all their pre- and post-places
+ the arcs in between*



T-INVARIANTS, THEOREMS

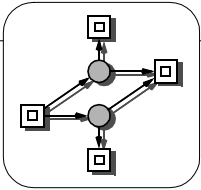
- **If a bounded net is live, then it is CTI.**
-> *NECESSARY CONDITION FOR well-formedness*



T-INVARIANTS, MUTEXDEMO

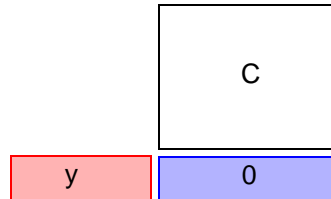
- INA, session protocol

1	0.B_up	:	1,
	1.B_down	:	1
2	2.A_up	:	1,
	3.A_down	:	1
- interpretation:
 - T-invariant1*
reproduces m_0 by a cyclic run of process B
 - T-invariant2*
reproduces m_0 by a cyclic run of process A
 - > *both T-invariants*
are cycles in the reachability graph
 - > *both T-invariants are realizable*
- CTI

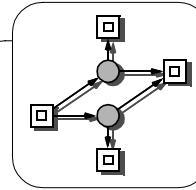


P-INVARIANTS

- ❑ Lautenbach, 1973
- ❑ P-invariants
 - > **integer solutions y of**
 $yC = 0, y \neq 0, y \geq 0$
- ❑ **minimal** P-invariants
 - > *there is no P-invariant with a smaller support*
 - > *gcd of all entries is 1*
- ❑ support
 - > *set of places belonging to the P-invariant*
- ❑ any P-invariant is a non-negative linear combination of minimal ones
 - > *multiplication with a positive integer*
 - > *addition*
 - > *division by gcd*
- ❑ Covered by P-Invariants (CPI)
 - > *each place belongs to a P-invariant*

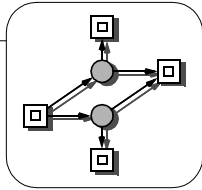


$$ky = \sum_i a_i y_i$$



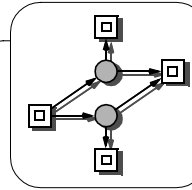
P-INVARIANTS, INTERPRETATION

- ❑ set of places with
 - > *a constant weighted sum of tokens*
 $ym = ym_0$
 - > *token / compound preservation*
- ❑ a place belonging to a P-invariant is bounded
 - > *CPI - sufficient condition for BND*
- ❑ the firing of any transition has no influence on the weighted sum of tokens on the P-invariant's places
 - > *for all transition t :*
the effect of the arcs,
removing tokens from a P-invariant's place
is equal to the effect of the arcs,
adding tokens to a P-invariant's place
- ❑ pre-sets of supports = post-sets of supports
- ❑ a P-invariant defines a connected subnet
 - > *the P-invariant's places (the support),*
+ all their pre- and post-transitions
+ the arcs in between



P-INVARIANTS, THEOREMS

- a place belonging to a P-invariant is bounded
- a net is **covered** by P-invariants (CPI)
 - > each place belongs to a P-invariant
 - > **SUFFICIENT CONDITION FOR BND**
- non-reachability check of m
 - > if there is a P-invariant y with $ym_0 \neq ym$, then m is not reachable from m_0 .
 - > **SUFFICIENT CONDITION FOR NON-REACHABILITY OF M**
- sub-P-invariants
 - > $yC \leq 0, y \neq 0, y \geq 0$
 - > *covered by sub-P-invariants*
 - > **NECESSARY AND SUFFICIENT CONDITION FOR STRUCTURALLY BND**



ANALYSIS OF MUTEXDEMO (3), NON-REACHABILITY CHECK

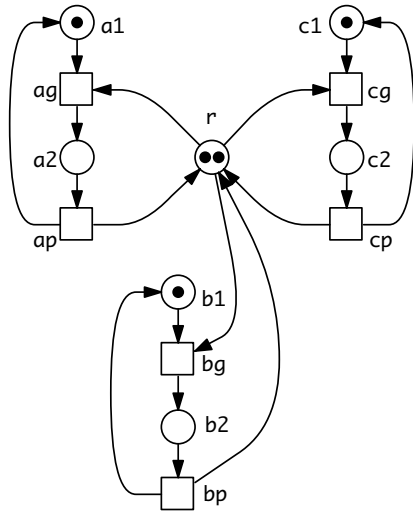
- P-Invariants/ Charlie (INA) session protocol

1	1.B_inMutex	: 1,
	2.B_begin	: 1
2		
3	A_begin	: 1,
	4.A_inMutex	: 1
3		
0	mutex	: 1,
	1.B_inMutex	: 1,
	4.A_inMutex	: 1
- $m_0 = (A_begin, B_begin, mutex),$
 $m = (A_inMutex, B_inMutex)$
 $m_0 * y3 = m * y3 ?$

$$m_0 * y3 = 1$$

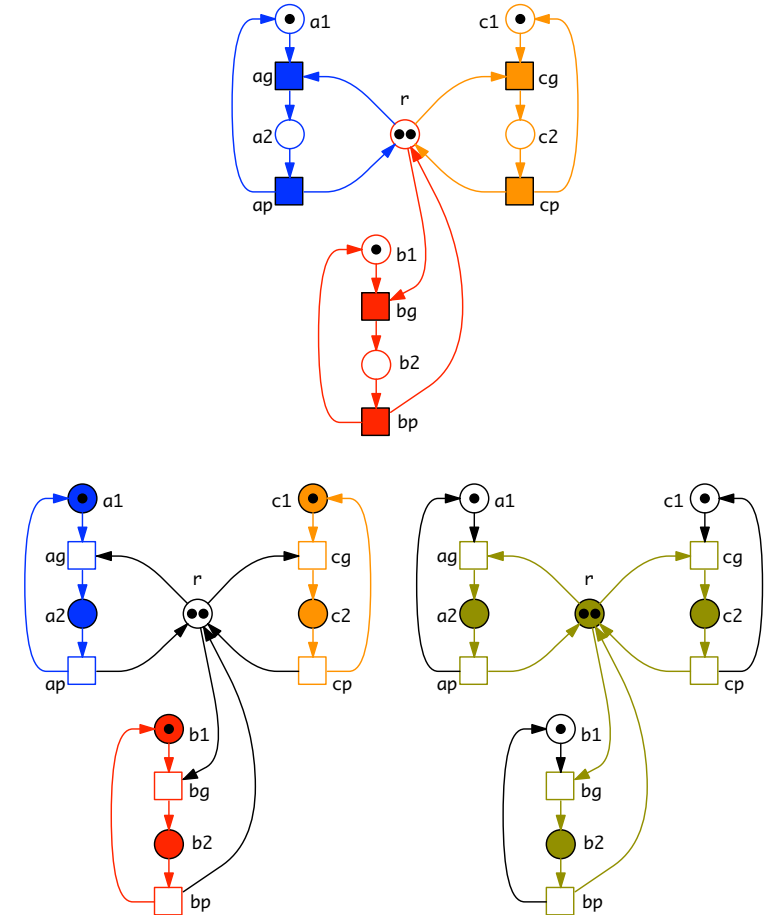
$$m * y3 = 2$$
 - > the marking m is not reachable
- **NOTE:**
 If the equation is fulfilled for all P-invariants, we know **NOTHING** concerning the reachability of the marking!

ALL MINIMAL (POSITIVE) P/ T- INVARIANTS

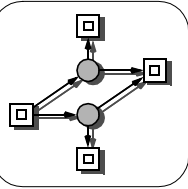


- T - invariants
 (ag, ap), (bg, bp), (cg, cp)
 -> local process cycles reproducing m_0
- P - invariants
 (a1, a2), (b1, b2), (c1, c2)
 -> possible local process states
 (a2, b2, c2, r)
 -> a resource is either free or occupied

ALL MINIMAL (POSITIVE) P/ T- INVARIANTS

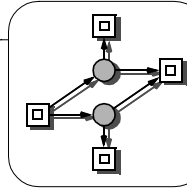


remark:
 invariants computed with Charlie can be visualised with Snoopy



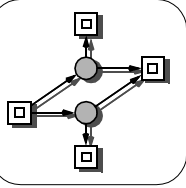
ZANALYSIS OF MUTEXDEMO (4), REASONING WITH P-INVARIANTS

- sometimes it is possible to use P-invariants for logical reasoning to prove a property in question;
- example:
 y_3 is a so-called **1-P-invariant**
 (the constant token sum is 1)
 because $y_3 * m_0 = 1$,
 $y_3 = (\text{mutex}, B_inMutex, A_inMutex)$
 $m_0 = (A_begin, B_begin, \text{mutex})$
- consequently,
either mutex **xor** A_inMutex **xor** B_inMutex
 can carry a token at any time;
 -> they can never carry a token at the same time
 -> the mutex property is fulfilled



UNREACHABILITY ANALYSIS, COMPARISON

- reachability graph
*pros: necessary & sufficient condition,
 rg allows also the decision of other properties,
 also sub-markings may be checked;*
*cons: uncontrolled growth
 (potentially beyond exponential growth)*
- state equation
*pros: static analysis technique
 (size of the state space does not matter);*
*cons: only sufficient condition,
 no sub-markings can be checked;*
- p-invariants, token conservation
pro/cons: see above
- p-invariants, reasoning
*pros: logical faults/hints for the reachability
 may be found*
*cons: limited by human skills in reasoning,
 not applicable for larger nets with larger invariants*



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