### NoPain – Meeting

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### Work Packages









### Efficient simulation of $\mathcal{HPN}^{\mathcal{C}}$

- a. Predecessor WPs: BTU-WP1, OvGUM-WP1
- b. Successor WPs: BTU-WP4
  - Examination of the Petri net models with regard to parallelisation potential
  - Investigation of optimisation possibilities and performance comparisons with alternative tools, i.e. StochKit2, Cain...

## Tool comparison



- Starting point: How many stochastic simulation tools are available?
- SBML Software Summary: > 100 tools related to simulation.
- Selection criteria needed!

### Tool comparison



#### Selection criteria

- Stochastic simulation tool. There are different approaches to simulate biochemical reaction networks, such as deterministic or hybrid simulation, but we are only interested in stochastic simulation tools.
- **2** Algorithms used by the Simulator. There are a couple of algorithms for stochastic simulation, such as *direct method* [Gillespie 1977], first reaction method [Gillespie 1976], next reaction method [Gibson et al. 2000] and  $\tau$ -leaping [Gillespie 2001]. The stochastic simulation tool must support at least the Gillespie's direct method.
- **3** *License type.* The use of the simulation tool must be free of charge.
- SBML support. The tool must support SBML (Level 2), either directly, or indirectly by connection to a tool supporting SBML.





- 1 Cain
- 2 Copasi
- 3 Dizzy
- 4 Marcie
- 5 Snoopy
- 6 StochKit2
- 7 StochPy
- $\rightarrow$  may be extended



### Cain

- Cain performs stochastic and deterministic simulations of chemical reactions.
- Caltech Center for Advanced Computing Research, Pasadena, California, US.
- Modelling paradigms: stochastic, deterministic.
- Simulation algorithm: direct method, next reaction method, *τ*-leaping.
- Interface: graphical user interface tool.
- File formats: SBML.

http://cain.sourceforge.net/

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### Copasi

- COPASI is a software application for simulation and analysis of biochemical networks and their dynamics.
- Virginia Bioinformatics Institute, University of Heidelberg, University of Manchester.
- Modelling paradigms: stochastic, deterministic.
- Simulation algorithm: direct method, next reaction method, *τ*-leaping.
- Interface: GUI & CL tool.
- File formats: SBML L2.

🖌 🖬 😽 **v** Model HICT kinetics HK CLCI + ATP - C6P + ADI HK kinetics PCI CTP = FEF PCI kinetic PER F6P + ATP -> F16hP + ADP AMP F26h PEK kinetics ALD F166P - DHAP + GAP -Bearings ALD kinetics DHAP - GAP Mass action (reversible Mathe matical CAP + NAD = BPG + NADH PCK BPC + ADP - P3C + ATP PCK kinetics PCM P3G = P2G **RCM kinetics** Fixed Metabolite Symbol ENO P2C = PEP ENO kinetics Metabolite Symbols PO PEP + ADP = PVR + ATP Differential Equation PDC PYR -> AcAld + CO2 **PDC kinetics** ADH EtOH + NAD = AcAJd + NADH ADH kinetics ATPase ATP -> ADP w Saaichiomean AK 2 \* AD7 - AT7 + AM7 Mass action (reversible **Elementary Moder** Mass Conservation 15 C3POH DHAP + NADH -> Givernl + NAG G320H kinetics Time Course Clycopen Branch G6P + ATP -> ADP + Clycopen **Clycogen synthesis kinetics** Trehalose Branch 2 \* C6P + ATP -> ADP + Trehalose Succinate Branch 2 \* AcAld + 3 \* NAD -> Succinate + 3 \* NADH Succinate kinetic **H**Fitting In Functions Preferences ( Delete/Undelete ) ( New

COTASI (4.0 Build 8

http://www.copasi.org

....



### Dizzy

- Dizzy is a chemical kinetics stochastic simulation software package written in Java.
- Institute for System Biology, Seattle, Washington, US.
- Modelling paradigms: stochastic, deterministic.
- Simulation algorithm: direct method, next reaction method, *τ*-leaping.
- Interface: graphical user interface tool.
- File formats: SBML L1V2.

http://magnet.systemsbiology.net/software/Dizzy/





#### Marcie

- Marcie is a tool for qualitative and quantitative analysis of Generalized Stochastic Petri nets with extended arcs.
- BTU Cottbus, Germany.
- Modelling paradigms: stochastic.
- Simulation algorithm: direct method, next reaction method, *τ*-leaping.
- Interface: command line tool.
- File formats: ANDL, PNML.

http://www-dssz.informatik.tu-cottbus.de/DSSZ/Software/Marcie





### Snoopy

- Snoopy is a software tool to design, animate and simulate hierarchical graphs, among others Petri nets.
- BTU Cottbus, Germany.
- Modelling paradigms: stochastic, deterministic and hybrid.
- Simulation algorithm: direct method.
- Interface: graphical user interface tool.
- File formats: SBML L2, ANDL.

http://www-dssz.informatik.tu-cottbus.de/DSSZ/Software/Snoopy





### StochKit2

- StochKit is an extensible stochastic simulation framework developed in C++.
- University of California, Santa Barbara, US.
- Modelling paradigms: stochastic.
- Simulation algorithm: direct method, next reaction method, *τ*-leaping.
- Interface: command line tool.
- File formats: SBML L2.

http://engineering.ucsb.edu/~cse/StochKit





### StochPy

- StochPy is a versatile modeling package for stochastic simulation.
- VU University Amsterdam, NL.
- Modelling paradigms: stochastic.
- Simulation algorithm: direct method, next reaction method, *τ*-leaping.
- Interface: command line tool.
- File formats: SBML L2.

http://stochpy.sourceforge.net/





- (colored) stochastic Petri net
- standard arcs, no read, inhibitor, modifier arcs
- mass-action kinetics
- scalable

stochastic Petri nets

- RKIP inhibited ERK Pathway
- Mitogen-activated Protein Kinase

Angiogenesis

colored stochastic Petri nets

- Prey Predator
- Gradient
- Repressilator

 $\rightarrow$  may be extended



### RKIP inhibited ERK Pathway [Gilbert et al. 2006]

- # places: 11
- # transitions: 11
- # arcs: 34
- scalable in N the initial number of tokens on the places ERK, MEKPP, Raf1Star, RKIP and RP





### Mitogen-activated Protein Kinase [Levchenko et al. 2000], [Heiner et al. 2008]

- # places: 22
- # transitions: 30
- # arcs: 90
- scalable in N the multiplier of initial number of tokens on the places Raf, RasGTP, RafP\_Phase1, MEKP\_Phase2, ERk, ERKP\_Phase3





### Angiogenesis [Napione et al. 2009]

- # places: 39
- # transitions: 64
- # arcs: 185
- scalable in N the initial number of tokens on the places Gab1, KdStar, P3k,Pg, Pip2, DAG, Enz and Akt

dead states





#### **Prey Predator**

- # places: 2 \* N
- # transitions: 3 \* N
- # arcs: 6 \* N
- scalable by # of places, transitions and arcs
- unbounded





### Gradient [Gilbert et al. 2013]

- # places:  $N^2$
- # transitions:  $8 * N^2 - 12 * N + 4$
- # arcs: 2 \* |T|
- scalable by # of places, transitions and arcs





### Repressilator [Liu 2012]

- # places: 3 \* N
- # transitions: 4 \* N
- # arcs: 10 \* N
- scalable by # of places, transitions and arcs







### Simulation parameters



The assumptions and constraints while performing simulation are:

- Simulation algorithm: direct method.
- Simulation results: mean token value of the places (species).
- Simulation time: from 0 time units to t time units (model specific).
- Simulation runs: 1; 100; 10 000; 1 000 000
- Threshold: max. 1h run time
- *Threads:* 1 and 4 threads
- Model parameter: 4 different values of N
- Experiment: a particular value of N, number of runs and threads
  - $\rightarrow$  each experiment performed 10 times
  - $\rightarrow$  320 experiments per model and tool
  - $\rightarrow$  worst case 320h, usually 12h

### Comparison criteria



#### Performance measures

- average run time per experiment
- peak memory consumption per experiment
- simulation results
- multi-threading coefficient





- Dell Precision T7400
- CPU: Intel<sup>®</sup> Xeon<sup>®</sup> CPU E5440 @ 2.83GHz
- RAM: 4x1024MB DDR2 FB-DIMM @ 667MHz
- OS: CentOS release 6.5 (64bit)





#### **RKIP** inhibited ERK Pathway

- Model parameter:  $N \in \{1, 100, 10000, 1000000\}$
- Tools: Cain, Marcie, Snoopy, StochKit2

### Results - ERK





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### Snoopy, average runtime (in sec) for ERK.

N	threads		1	runs			
		1	100	10,000	1,000,000		
1	1	0.0002	0.0018	0.1658	16.8030		
T	4	1.0003	1.0014	1.0079	4.9084		
100	1	0.0009	0.0989 8.9830		884.4062		
100	4	1.0005	1.0084	3.0072	233.9180		
10 000	1	0.0898	8.8005	875.7929	†		
10,000	4	1.0004	3.0085	231.8182	t		
1 000 000	1	9.0178	889.899	†	†		
1,000,000	4	9.4008	243.3228	t	†		





### Snoopy, peak memory consumption (in KB) for ERK.

_	Ν	threads		r	runs	
			1	100	10,000	1,000,000
_	1	1	37,576	37,752	37,904	37,988
	T	4	37,512	37,767	37,824	39,604
	100	1	37,580	39,748	39,507	39,968
	100	4	40,196	40,160	39,900	39,932
	10 000	1	39,980	39,752	41,928	†
	10,000	4	40,032	40,112	39,568	t
	1 000 000	1	39,600	39,460	†	†
	1,000,000	4	39,796	39,004	†	†





#### Marcie, average runtime (in sec) for ERK.

N	threads			runs	
		1	100	10,000	1,000,000
1	1	0.0	0.0	0.0	13.0
I	4	0.0	0.0	0.0	3.0
100	1	0.0	0.0	6.0	617.6
100	4	0.0	0.0	1.0	162.5
10 000	1	0.0	6.0	620.3	†
10,000	4	0.0	1.0	161.8	t
1 000 000	1	6.0	621.2	ť	t
1,000,000	4	6.0	163.5	†	†





### Marcie, peak memory consumption (in KB) for ERK.

N	threads	runs						
		1	100	10,000	1,000,000			
1	1	0,000	0,000	5,172	3,128			
I	4	3,126	0,000	5,324	5,324			
100	1	0,000	5,172	3,132	3,156			
100	4	0,000	5,324	5,328	5,360			
10 000	1	3,124	3,152	3,156	†			
10,000	4	3,128	5,328	5,356	†			
1 000 000	1	3,148	3,160	†	†			
1,000,000	4	3,128	5,364	†	t			





### CAIN, average runtime (in sec) for ERK.

N	threads		1		
		1	100	10,000	1,000,000
1	1	0.0222	0.1160	8.1655	*
T	4	0.0231	0.0231 0.0943 4.2285		*
100	1	1 0.0231		10.9276	*
100	4	0.0239	239 0.1048 5.1622		*
10 000	1	0.0315	1.8656	183.8095	*
10,000	4	0.0338	0.6837	60.1041	*
1 000 000	1	1.7569	173.7179	t	*
1,000,000	4	1.7658	56.9456	†	*

 $\dagger$  runtime > 1h

\* tool crash while performing simulation





### CAIN, peak memory consumption (in KB) for ERK.

N	threads	runs						
		1	100	10,000	1,000,000			
1	1	110,048	113,544	201,795	*			
I	4	110,520	117,912	109,125	*			
100	1	112,196	112,960	199,904	*			
100	4	110,944	117,316	203,208	*			
10 000	1	110,080	114,324	199,728	*			
10,000	4	110,468	118,568	202,600	*			
1 000 000	1	111,200	115,408	t	*			
1,000,000	4	111,792	118,192	t	*			

Table: CAIN peak memory consumption (in KB) for ERK.

 $\dagger$  runtime > 1h

\* tool crash while performing simulation





### StochKit2, average runtime (in sec) for ERK.

N	threads		runs					
		1	100	10,000	1,000,000			
1	1	0.0080	0.0134	0.4421	42.7381			
T	4	0.0080	0.0172	0.1284	11.5534			
100	1	0.0080	0.0425	3.3970	338.0346			
100	4	0.0083	0.0276 0.9099		88.4614			
10.000	1 0.0380		2.9934 294.4733		†			
10,000	4	0.0381	0.8301	77.7298	t			
1 000 000	1	2.9665	296.6058	ť	†			
1,000,000	4	2.9649	80.5857	ť	t			





### StochKit2, peak memory consumption (in KB) for ERK.

N	N threads		runs						
		1	100	10,000	1,000,000				
1	1	2,748	2,752	9,904	9,924				
T	4	2,748	2,748	20,560	24,800				
100	1	2,748	2,748	9,982	9,924				
100	4	2,748	2,748	24,786	26,832				
10.000	1	2,748	9,904	9,932	†				
10,000	4	2,748	24,800	24,876	t				
1 000 000	1	9,964	9,968	t	t				
1,000,000	4	9,916	24,920	†	†				



### Comparison: average run time





#### Comparison: average run time



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### Multithreading Coefficient

Tool	Threading Coefficient	Variation
CAIN	3.0544	0.01
MARCIE	3.8112	0.02
SNOOPY	3.7387	0.07
STOCHKIT	3.7474	0.07

## Conclusions



#### So far

- **1** CAIN fastest, highest memory consumption (leak?)
- 2 StochKit2 very fast
- 3 Marcie fast, lowest memory consumption
- 4 Snoopy

## Milestones



	2013					2014			2015			
	Q1	Q2	Q3	Q4	Q1	Q2	Q3	Q4	Q1	Q2	Q3	Q4
WP1		M1										
WP2				M2								
WP3						M3						
WP4								M4				
WP5								M4				
WP6												M5
WP7												M6





finish tool comparison

■ go on with WP 4 & 5



# Thank you for your attention!