

Spatial Encoding of Systems Using Coloured Petri Nets

George Assaf and Monika Heiner

Computer Science Institute, Faculty 1 Brandenburg University of Technology,
Cottbus, Germany

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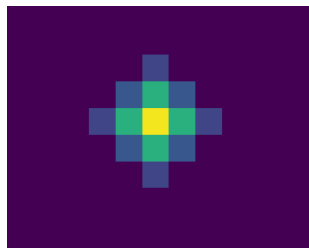
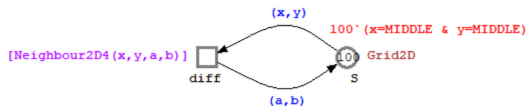
1 The Problem

2 Coloured Petri nets

3 First encoding scheme

4 Second encoding scheme

5 Comparison

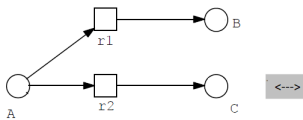




- The explicit notion of space is a crucial point for many systems.
 - Biochemical diffusion which develops over space.
 - A moving Robot which occupies a certain size in space.
- Modelling such systems requires taking location information into consideration
 - e.g, in biochemical diffusion, diffusion can only be happened between two neighbouring-grid positions.
- Colored Petri nets (\mathcal{PN}^C) are an excellent formalism for modeling and analysing such systems.
- We introduce two space-encoding principles using coloured Petri nets to address this issue.

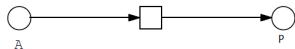
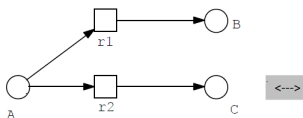


- No colours.





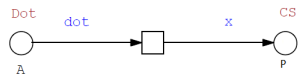
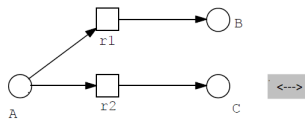
■ Coloured version.



```
Declarations:  
colorset Dot= dot;  
colorset CS= enum with B, C;  
var      x : CS;
```



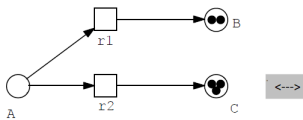
■ Coloure definitions.



```
Declarations:  
colorset Dot= dot;  
colorset CS= enum with B, C;  
var      x : CS;
```

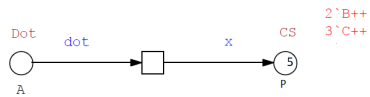
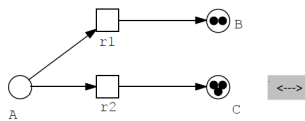


- With tokens.





- With tokens.

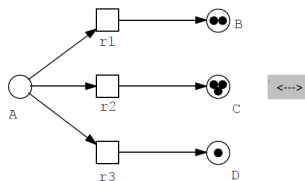


```
Declarations:  
colorset Dot= dot;  
colorset CS= enum with B, C;  
var      x : CS;
```

2`B++
3`C++

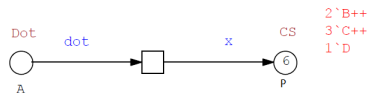
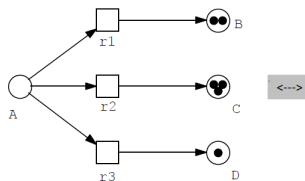


- More complex structure.





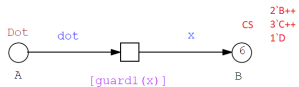
- Adjust colour definitions.



```
Declarations:  
colorset Dot= dot;  
colorset CS= enum with B, C, D;  
var      x : CS;
```

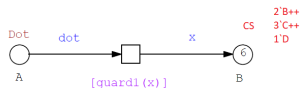


- with Guard.





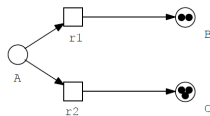
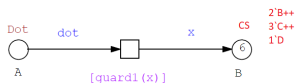
- with Guard.



```
bool fun1(CS ARG){  
  (ARG=B | ARG=C)  
};
```



■ with Guard.



```
bool fun1(CS ARG){
  (ARG=B | ARG=C)
};
```




- Coloured stochastic Petri nets (\mathcal{SPN}^c)
 - discrete number of tokens on its places \rightarrow non-negative integer.
 - stochastic firing rate is associated with each transition.

- Coloured continuous Petri nets (\mathcal{CPN}^c)
 - continuous amount of tokens on its places \rightarrow real value.
 - deterministic firing rate is associated with each transition.

- Both stochastic and continuous Petri nets transitions follow firing rates specified by arbitrary mathematical function.

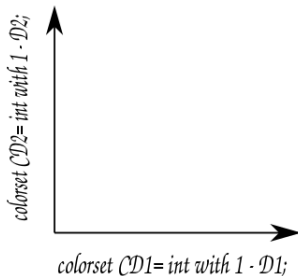


- First Dimension.


colorset $\mathcal{CD}1 = \text{int with } 1 \cdot D1;$

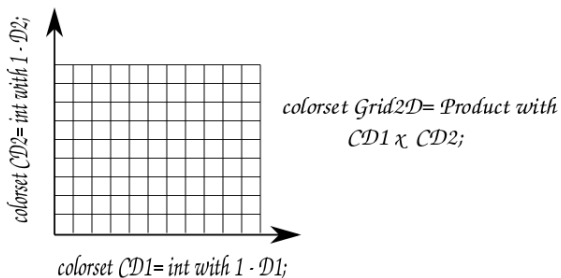


- Second Dimension.

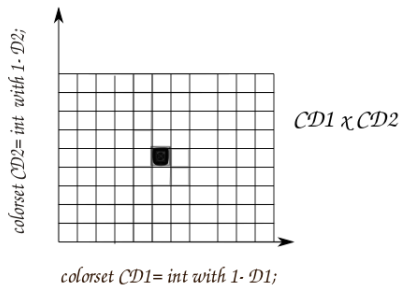




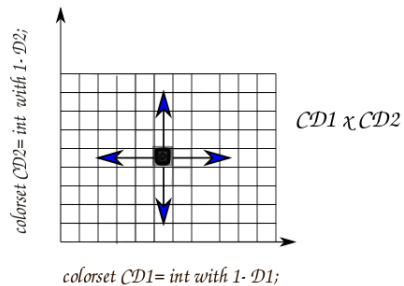
- Grid 2D.



Example: 2D Biochemical Diffusion



Example: 2D Biochemical Diffusion





- Constants definition:
 - **const** D1 = **int** with 15;
 - **const** D2 = D1;
 - **const** MIDDLE = **int** D1/2+1;

- Required colour sets:
 - **colorset** CD1 = **int** with 1 – D1;
 - **colorset** CD2 = **int** with 1 – D2;
 - **colorset** Grid2D = **Product** with CD1 x CD2;

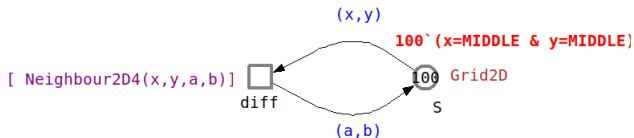
- Variables declaration:
 - **var** x,a : CD1;
 - **var** y,b : CD2;



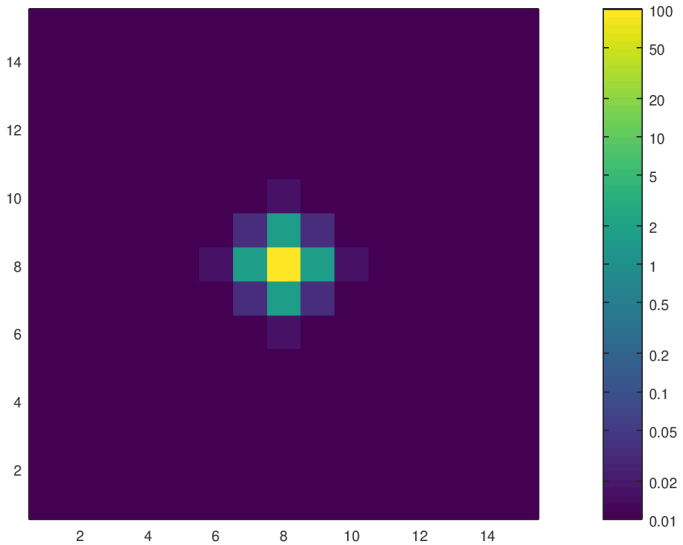
- Neighbourhood function (four-neighbour relation)

```
fun bool Neighbour2D4 (CD1 x , CD2 y , CD1 xn , CD2 yn ) {  
  // ( xn , yn ) is one of the up to four neighbours of ( x , y )  
  ( xn=x & yn=y- 1) | ( xn=x & yn=y+1)  
  | ( yn=y & xn=x- 1) | ( yn=y & xn=x+1)  
  & (1<=xn & xn<=D1) & (1<=yn & yn<=D2) } ;
```

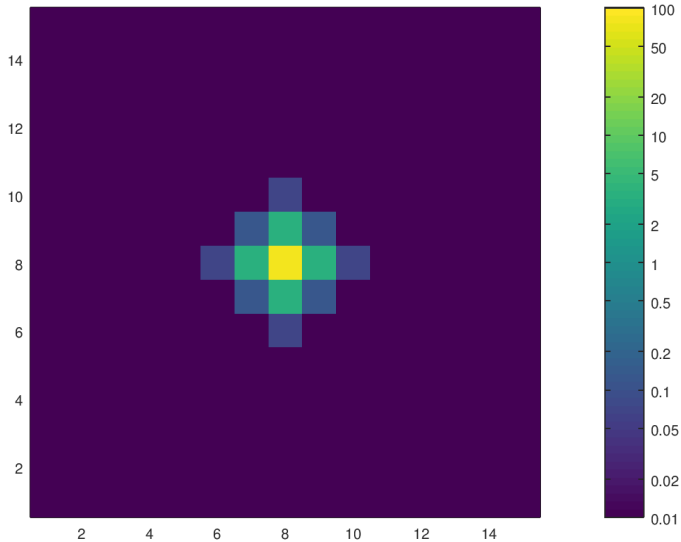
- Model



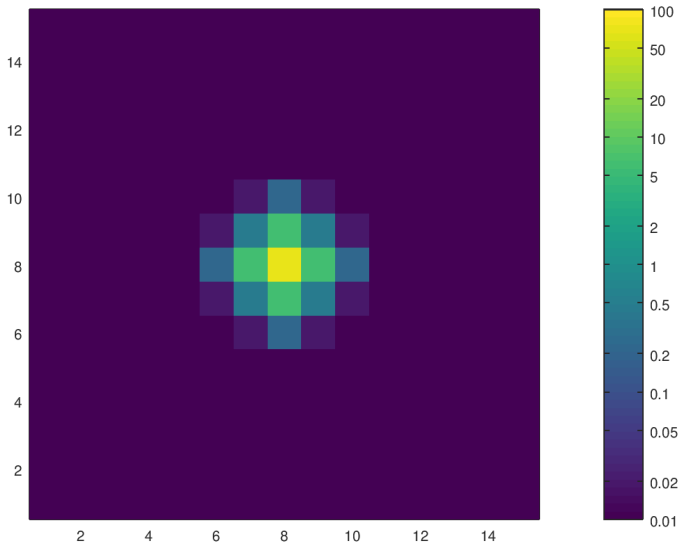
Example: 2D Biochemical Diffusion - Simulation $t=20$



Example: 2D Biochemical Diffusion - Simulation $t=40$



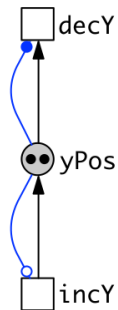
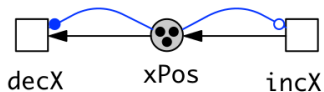
Example: 2D Biochemical Diffusion - Simulation $t=80$





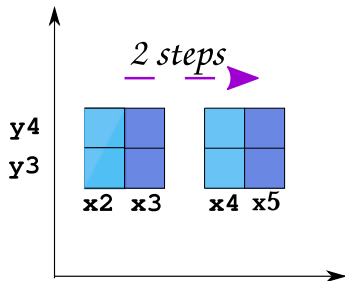
- In this encoding principle, space is modeled by discretisation into a grid and having one subnet per grid position.
- If the entities that are moving around have internal structure (state) which has to move around as well, this leads to some issues on modelling and simulation (space explosion).

Second spatial encoding scheme





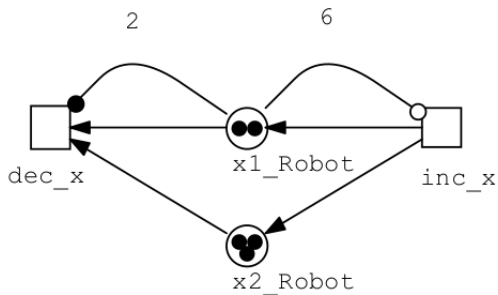
- The Robot has a size of up to 2×2 (units). It moves on a straight line in the center of the room covering a distance of 7 meters.
- Since Robot arrives the first end, it moves back in the opposite direction and so on.
- Robot initially occupies the positions $x=2$ and $x=3$ on the X-Axis and $y=3$ and $y=4$ on Y-Axis.



Example: Moving Robot- space encoding



- No colours.





■ Constants

- **const** SIZE = int with 2; // size of Robot on each dimension
- **const** X1MAX = int with 6;
- **const** X2MAX = int with 7;
- **const** X1MIN = int with 2;
- **const** X2MIN = int with 3;
- **const** Y1 = int with 3;
- **const** Y2 = int with 4;

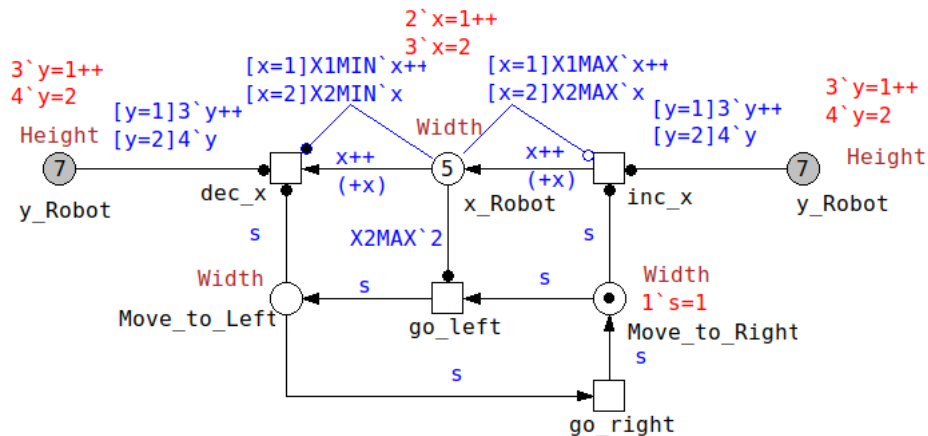
■ Required colour sets

- **colorset** Width = int with 1–SIZE; // number of occupied positions on x-axis
- **colorset** Height = int with 1–SIZE; // number of occupied positions on y-axis

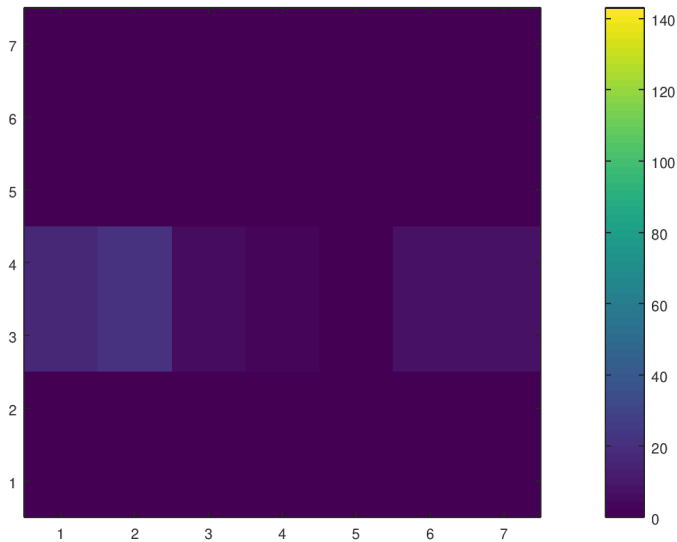
■ Required Variables

- **var** x : Width; // row index
- **var** y : Height; // column index
- **var** s : Width; // switching movement from right to left and vice versa

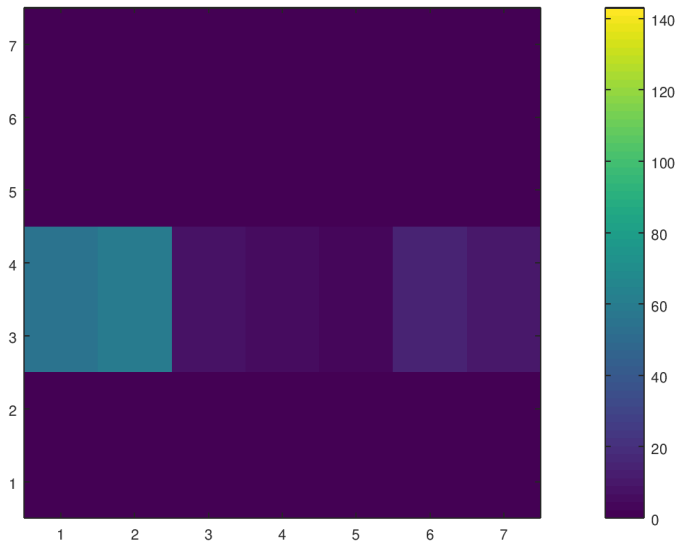
Example: Moving Robot - Model



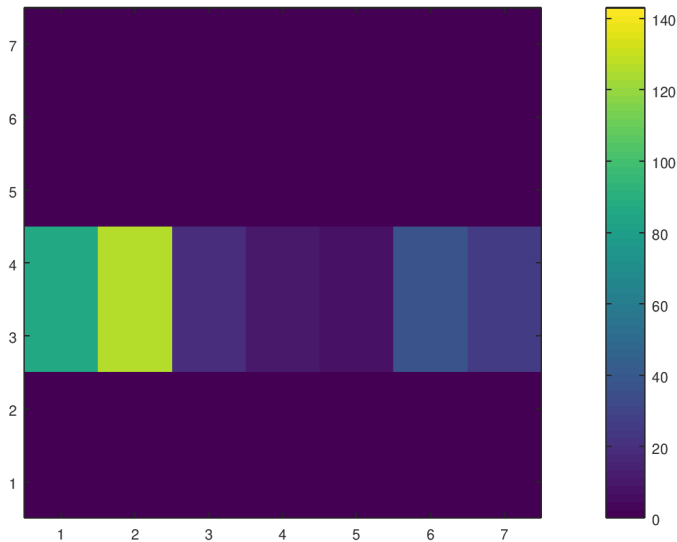
Example: Moving Robot - Model Simulation $t=20s$



Example: Moving Robot - Model Simulation $t=40s$



Example: Moving Robot - Model Simulation $t=80s$





Scheme 1:

- Discretising space using finite colour sets \Rightarrow finite universe.

Scheme 2:

- Space is represented using coordinate places.



Scheme 1:

- Discretising space using finite colour sets \Rightarrow finite universe.
- The unfolded model increases extremely as the size of space increases.

Scheme 2:

- Space is represented using coordinate places.
- Size of the unfolded model does not depend on size of the finite universe.



Scheme 1:

- Discretising space using finite colour sets \Rightarrow finite universe.
- The unfolded model increases extremely as the size of space increases.
- Local states of moving objects is not possible.

Scheme 2:

- Space is represented using coordinate places.
- Size of the unfolded model does not depend on size of the finite universe.
- Local state of moving objects is possible.



Thank
you