

Part IV

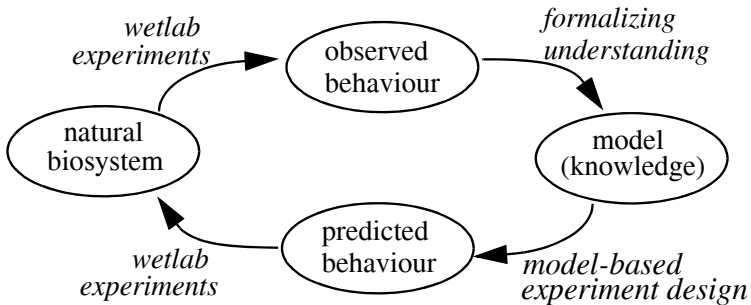
PN-Based Model Checking of Biochemical Networks

Monika Heiner

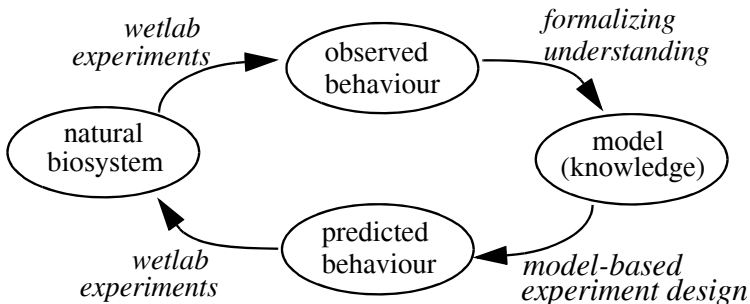
*joint work with David Gilbert (London/UK),
Robin Donaldson (Glasgow/UK)*

University of Zaragoza, February 23, 2010

- *modelling as formal knowledge representation*

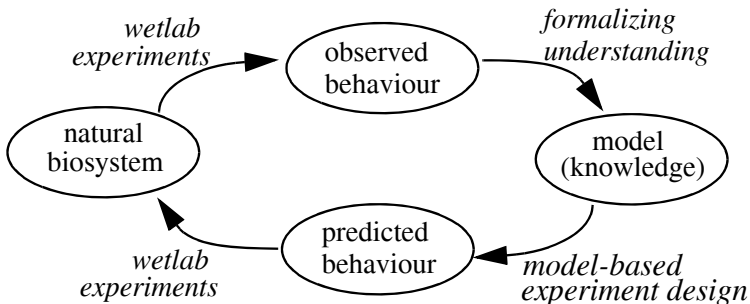


- *modelling as formal knowledge representation*



many assumptions, fuzzy/changing/growing knowledge

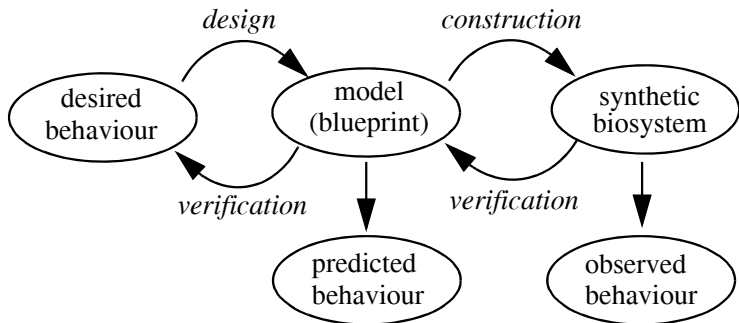
- *modelling as formal knowledge representation*



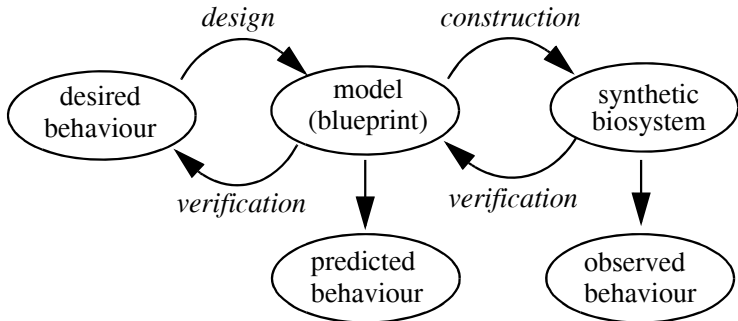
many assumptions, fuzzy/changing/growing knowledge

model needs to be validated

- *modelling for system construction*

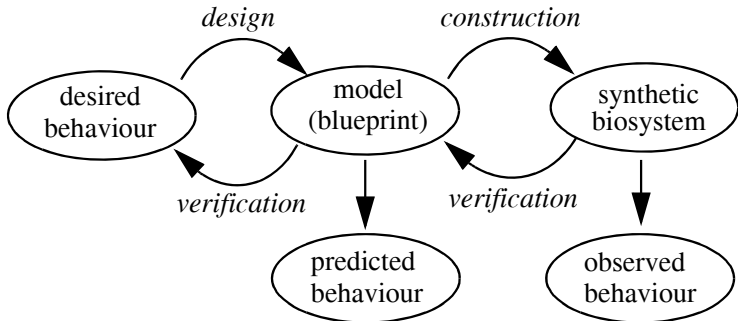


- *modelling for system construction*



reliable and robust engineering

- *modelling for system construction*



reliable and robust engineering

models serve as blueprint, need to be verified

In a sentence :

- "Formally check whether a model of a biochemical system does what we want"

Components :

- a model
 - the current description of a biochemical system of interest
- a property
 - a property which we think the system should have
- a model checker
 - a program to test whether the model has the property

What can we do with Model Checking?

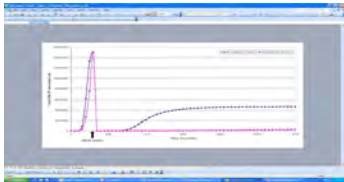
- *model validation*
 - Show that our model of the pathway matches the (stochastic) lab data.
- *model analysis*
 - In a collection of variants of a model (e.g., in silico gene knock-outs), which models show a certain behaviour (loss of oscillations ...)?
- *model development*
 - If the model doesn't do what we want, change the model automatically until it does! (parameters, structures, ...)
- *model finding*
 - Many models in a database; can use model checking to query the database :
"Give me all the models in the database which oscillate."
- *biosystem verification - synthetic biology*
 - Does the constructed system do what we intended?

Biologists will often talk in qualitative or semi-quantitative language (trends).

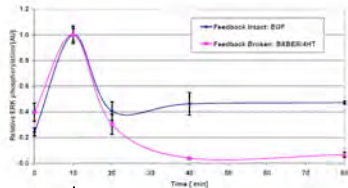
- "This protein peaks after 5 minutes, then falls to half concentration."
- Often quite certain about time,
- but not about concentrations.

Lab data versus simulations

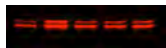
Simulation



Experiment



U0126 added



pERK1/2, +EGF



pERK1/2, + BXBBER/4HT

0 10 20 40 80 min stimulation

Examples :

- after 100 seconds the concentration of Protein1 is stable
- protein1 peaks and falls
- protein1 peaks and stays constant
- protein1 peaks before Protein2
- protein1 oscillates 4 times in 5,000 seconds
- molecules of protein2 are required for molecules of protein1 to be created

Various logics each with different expressivity :

- *Branching-time logics* consider all branching time lines
 - Computational Tree Logic (CTL)
 - Continuous Stochastic Logic (CSL)

"There is a possibility that I will stay hungry forever."

"There is a possibility that eventually I am no longer hungry."

- *Linear-time logics* consider separately all single time lines
 - Linear-time Temporal Logics (LTL, LTLc, PLTLc)

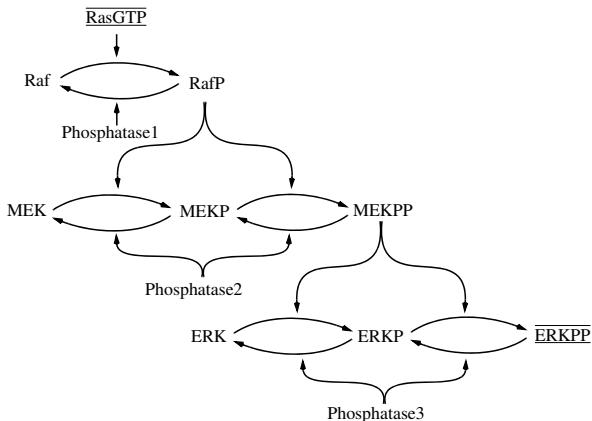
"I am hungry."

"I am always hungry."

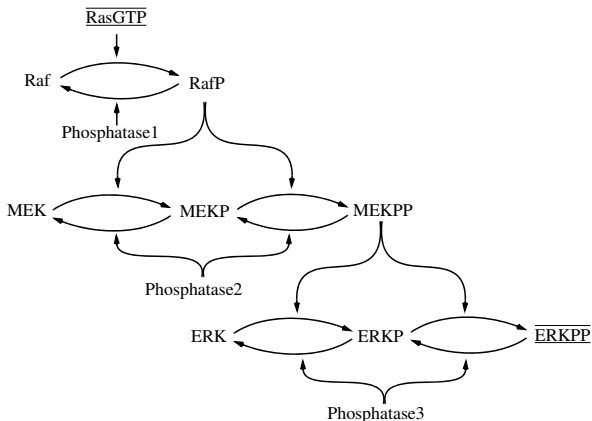
"I will eventually be hungry."

"I will be hungry until I eat something."

- ... a typical signalling cascade



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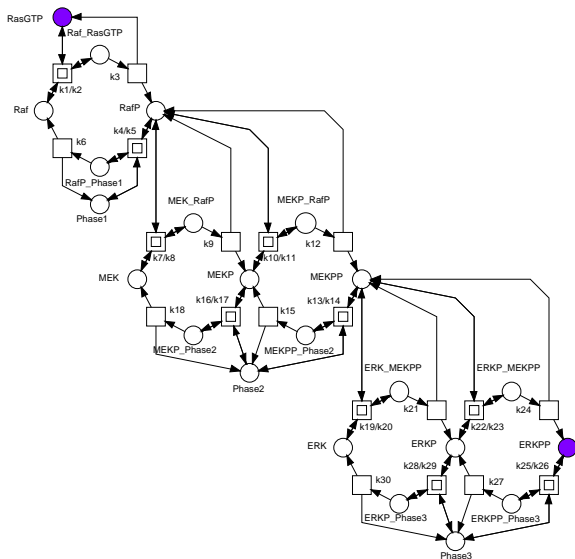
modelled in [Levchenko et al. 2000] like this ...

Running Case Study - Origin

[Levchenko et al. 2000], *Supplemental Material : ODEs*

$$\begin{aligned}dRaf/dt &= k_2 * Raf_RasGTP + k_6 * RafP_Phase1 - k_1 * Raf * RasGTP \\dRasGTP/dt &= k_2 * Raf_RasGTP + k_3 * Raf_RasGTP - k_1 * Raf * RasGTP \\dRaf_RasGTP/dt &= k_1 * Raf * RasGTP - k_2 * Raf_RasGTP - k_3 * Raf_RasGTP \\dRafP/dt &= k_3 * Raf_RasGTP + k_{12} * MEKP_RafP + k_9 * MEK_RafP + \\&k_5 * RafP_Phase1 + k_8 * MEK_RafP + k_{11} * MEKP_RafP - \\&k_7 * RafP * MEK - k_{10} * MEKP * RafP - k_4 * Phase1 * RafP \\dRafP_Phase1/dt &= k_4 * Phase1 * RafP - k_5 * RafP_Phase1 - k_6 * RafP_Phase1 \\dMEK_RafP/dt &= k_7 * RafP * MEK - k_8 * MEK_RafP - k_9 * MEK_RafP \\dMEKP_RafP/dt &= k_{10} * MEKP * RafP - k_{11} * MEKP_RafP - k_{12} * MEKP_RafP \\dMEKP_Phase2/dt &= k_{16} * Phase2 * MEKP - k_{18} * MEKP_Phase2 - k_{17} * MEKP_Phase2 \\dMEKPP_Phase2/dt &= k_{13} * MEKPP * Phase2 - k_{15} * MEKPP_Phase2 - k_{14} * MEKPP_Phase2 \\dERK/dt &= k_{20} * ERK_MEKPP + k_{30} * ERKP_Phase3 - k_{19} * MEKPP * ERK \\dERK_MEKPP/dt &= k_{19} * MEKPP * ERK - k_{20} * ERK_MEKPP - k_{21} * ERK_MEKPP \\dERKP_MEKPP/dt &= k_{22} * MEKPP * ERKP - k_{24} * ERKP_MEKPP - k_{23} * ERKP_MEKPP \\etcetera &= \dots\end{aligned}$$

Running Case Study



- **initial marking construction**
P-invariants

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 - P-invariants

- **subnetwork identification**

 - P-invariants : token preserving modules (*mass conservation*)
 - T-invariants : state repeating modules (*elementary modes*)

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 - *boundedness* : every place gets finite token number only
 - *liveness* : every transition may happen forever
 - *reversibility* : every state may be reached forever

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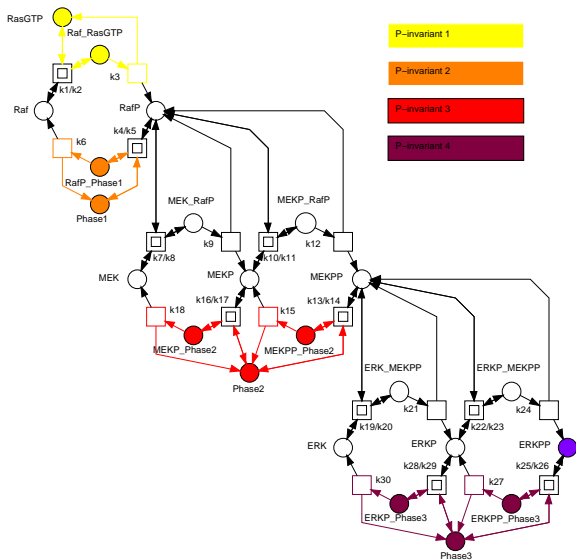
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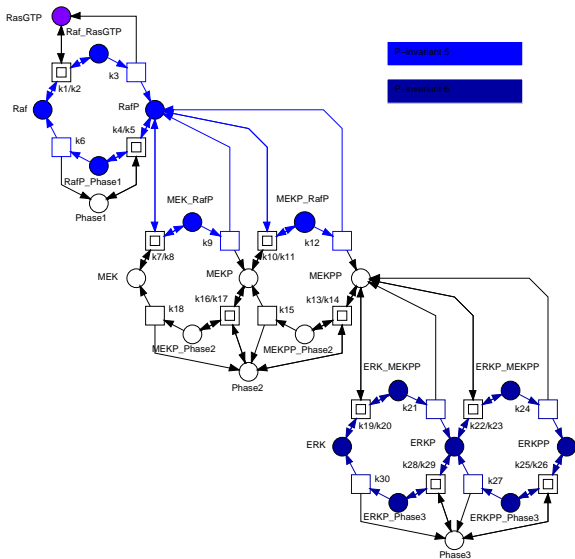
- **special behavioural properties**

 - CTL / LTL model checking

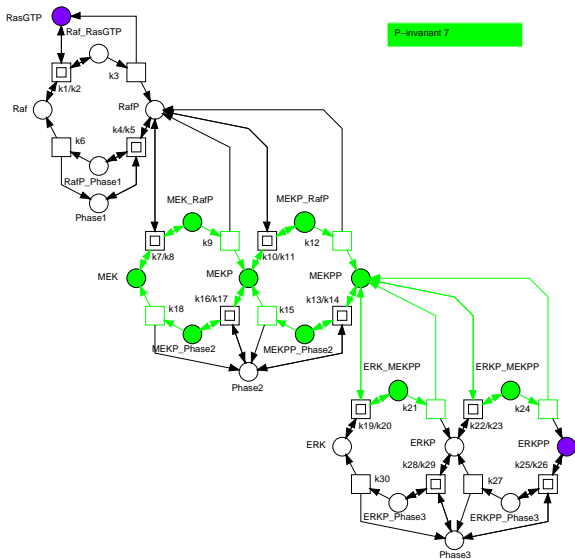
Running Case Study - P-invariants



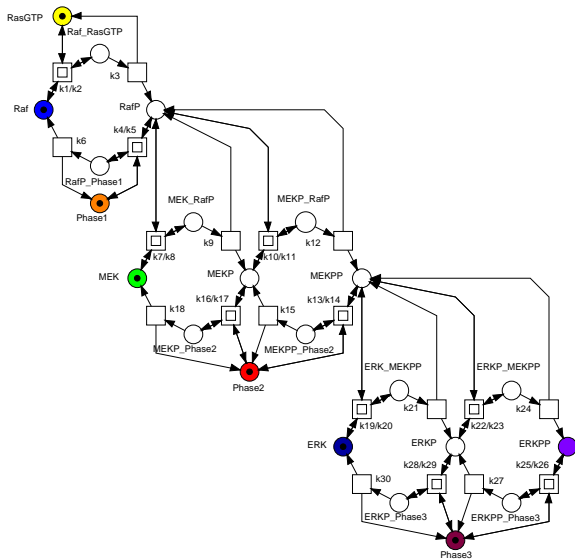
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Running Case Study - initial marking



Running Case Study - general properties

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- *state space*

levels	reachability graph number of states	IDD data structure number of nodes
1	118	52
4	$2.4 \cdot 10^4$	115
8	$6.1 \cdot 10^6$	269
80	$5.6 \cdot 10^{18}$	13,472
120	$1.7 \cdot 10^{21}$	29,347

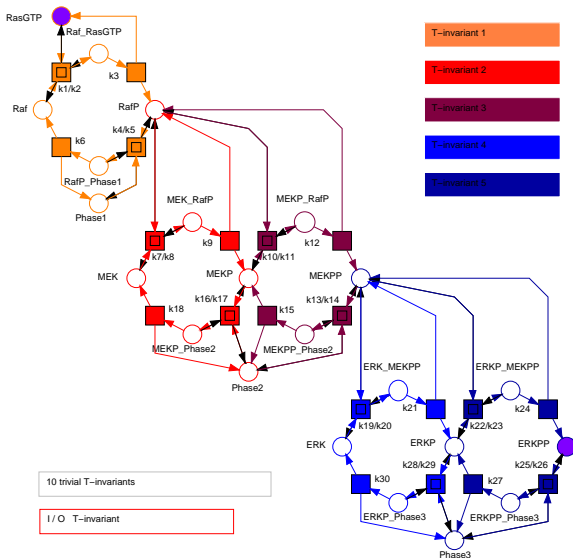
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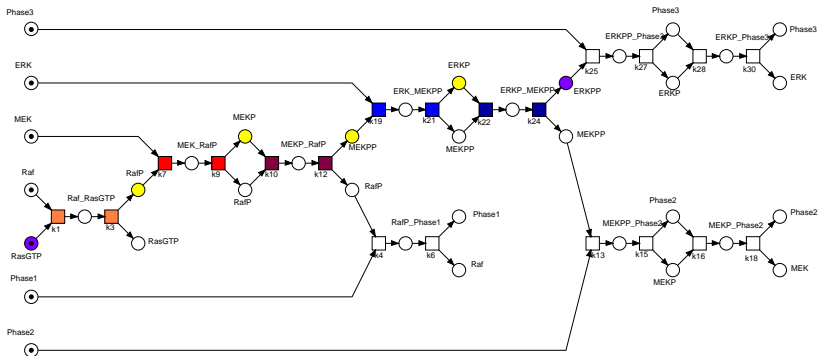
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- reachability graph
 - strongly connected \Rightarrow **reversible**
 - contains every transition (reaction) \Rightarrow **live**

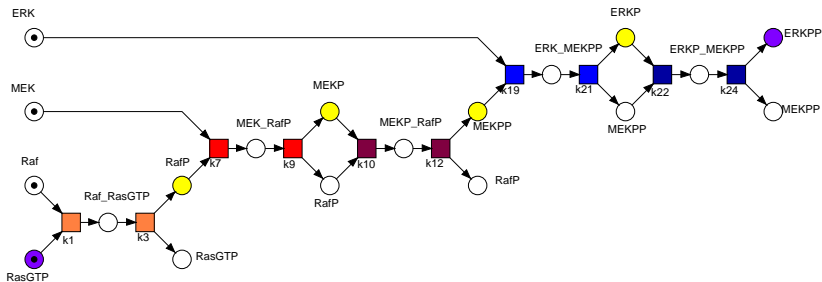
Running Case Study - T-invariants



Running Case Study - partial order run of I/O T-invariant



Running Case Study - partial order run of I/O T-invariant

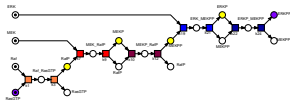


There is a path ...

- $EX\phi$
 - if there is a state reachable by one step where ϕ holds.
- $EF\phi$
 - if there is a path where ϕ holds finally, i.e., at some point.
- $EG\phi$
 - if there is a path where ϕ holds globally, i.e., forever.
- $E(\phi_1 U \phi_2)$
 - if there is a path where ϕ_1 holds until ϕ_2 holds.

For all path ...

- $AX\phi$
 - if ϕ holds for all states which are reachable by one step.
- $AF\phi$
 - if ϕ holds finally (at some point) for all paths.
- $AG\phi$
 - if ϕ holds globally (i.e. for ever) for all paths.
- $A(\phi_1 U \phi_2)$
 - if ϕ_1 holds until ϕ_2 holds for all paths.



property Q1 :

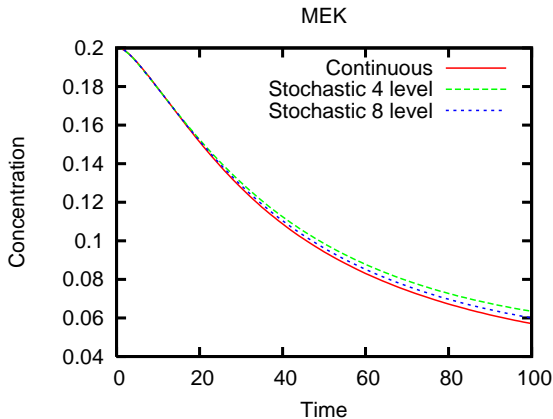
The signal sequence predicted by the partial order run of the I/O T-invariant is the only possible one ;
i.e., starting at the initial state, it is necessary to pass through RafP, MEKP, MEKPP and ERKP in order to reach ERKPP.

$$\neg [\mathbf{E} (\neg \text{RafP} \mathbf{U} \text{MEKP}) \vee \\ \mathbf{E} (\neg \text{MEKP} \mathbf{U} \text{MEKPP}) \vee \\ \mathbf{E} (\neg \text{MEKPP} \mathbf{U} \text{ERKP}) \vee \\ \mathbf{E} (\neg \text{ERKP} \mathbf{U} \text{ERKPP})]$$

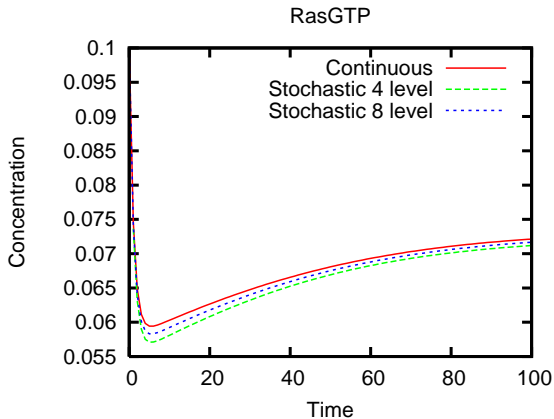
- *isomorphy of reachability graph and CTMC*, thus all qualitative properties still valid
- *How many levels needed for quantitative evaluation ?*
 - state space(1 levels) = 118 (Boolean interpretation)
 - state space(4 levels) = 24,065
 - state space(8 levels) = 6,110,643
- *equivalence check*

$$C_{RafP}(t) = \frac{0.1}{s} \cdot \underbrace{\sum_{i=1}^{4s} (i \cdot P(L_{RafP}(t) = i))}_{\text{expected value of } L_{RafP}(t)}$$

- *equivalence check, results, e.g. for MEK :*



- *equivalence check, results, e.g. for RasGTP :*



Replaces the path quantifiers (E, A) in CTL by the probability operator $P_{\triangleleft x}$, where $\triangleleft x$ specifies the probability x of the formula.

- $P_{=?}[X\phi]$
 - prob there is a state reachable by one step where ϕ holds.
- $P_{=?}[F\phi]$
 - prob there is a path where ϕ holds finally, i.e., at some point.
- $P_{=?}[G\phi]$
 - prob there is a path where ϕ holds globally, i.e., forever.
- $P_{=?}[\phi_1 U \phi_2]$
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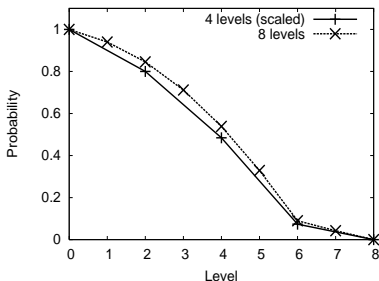
Syntactic sugar

- $\phi_1\{\phi_2\}$ - ϕ_1 happens from the first time ϕ_2 happens, where no temporal operators in ϕ_2 .

property S1 :

What is the probability of the concentration of RafP increasing, when starting in a state where the level is already at L?

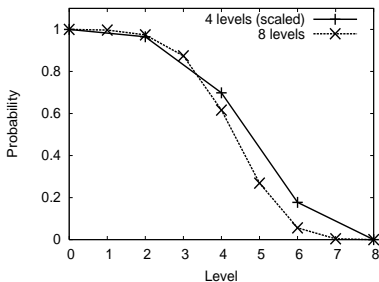
$$P_{=?} [(\text{RafP} = L) \mathbf{U}^{<=100} (\text{RafP} > L) \{ \text{RafP} = L \}]$$



property S2 :

What is the probability that RafP is the first species to react?

$$P_{=?} [((\text{MEKPP} = 0) \wedge (\text{ERKPP} = 0)) \mathbf{U}^{\leq 100} (\text{RafP} > L) \\ \{ (\text{MEKPP} = 0) \wedge (\text{ERKPP} = 0) \wedge (\text{RafP} = 0) \}]$$



Example figures for MC2 model checking of property S1 at varying number of levels/molecules.

Levels	MC Time ^a	Simulation Output Size
4	10 s ^b	750 KB
8	15 s ^b	1.5 MB
40	1.5 minutes ^b	7.5 MB
400	1 minute ^c	80 MB
4,000	30 minutes ^c	900 MB

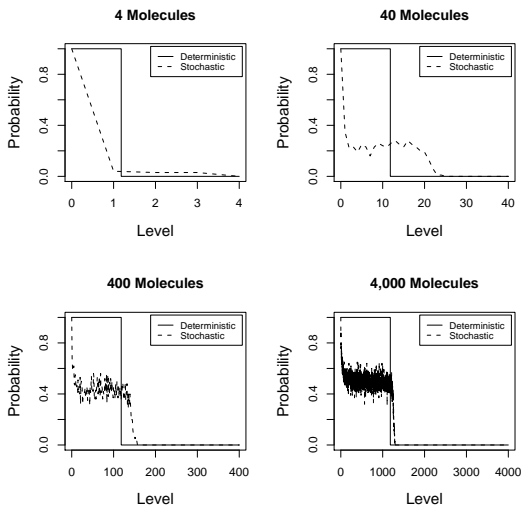
^a Both Gillespie simulation and MC2 checking.

^b Computation on a standard workstation.

^c Distributed computation on a computer cluster comprising 45 Sun X2200 servers each with 2 dual core processors (180 CPU cores).

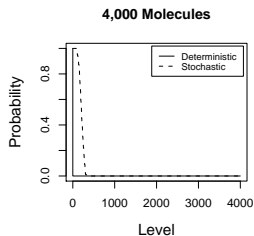
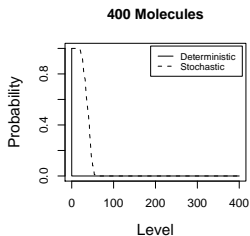
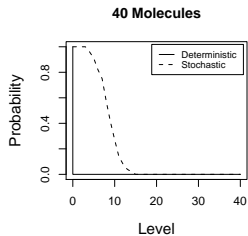
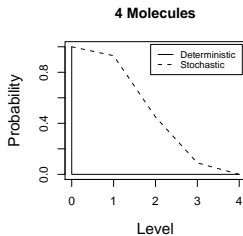
Stochastic Model Checking - Simulative Approach

- S1 at varying number of molecules shows progression towards deterministic behaviour as number of molecules increases.*



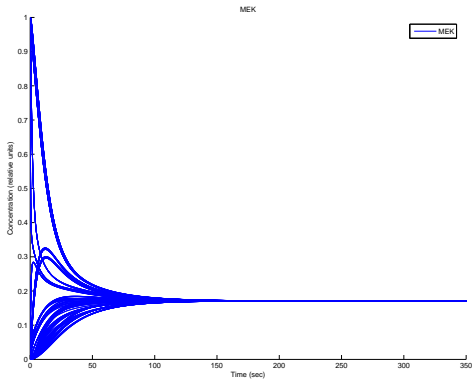
Stochastic Model Checking - Simulative Approach

- S2 at varying number of molecules shows progression towards deterministic behaviour as number of molecules increases.*

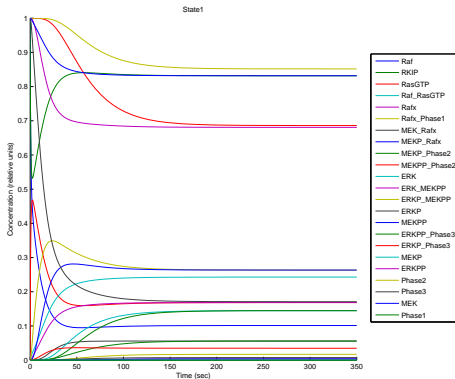


Continuous Model Checking - Preparation

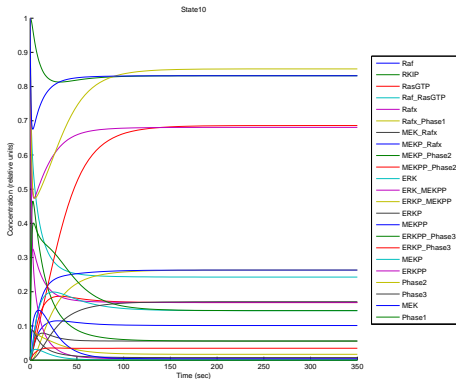
- *steady state analysis, results for all 118 'good' states, e.g. for MEK :*



- *steady state analysis for state 1 :*



- *steady state analysis for state 10 :*



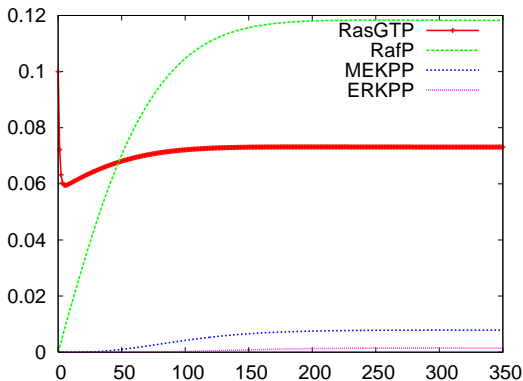
For all single path ...

- $X\phi$
 - ϕ happens in the next time point.
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 - ϕ happens at some time.
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 - ϕ always happens.
- $A(\phi_1 U \phi_2)$
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Syntactic sugar

- $\phi_1\{\phi_2\}$ - ϕ_1 happens from the first time ϕ_2 happens, where no temporal operators in ϕ_2 .

- *transient analysis for RasGTP, RafP, MEKPP, ERKPP :*



property C1 :

The concentration of RafP rises to a significant level, while the concentrations of MEKPP and ERKPP remain close to zero ;
i.e. *RafP is really the first species to react.*

$$((MEKPP < 0.001) \wedge (ERKPP < 0.0002)) \mathbf{U} (RafP > 0.06)$$

property C2 :

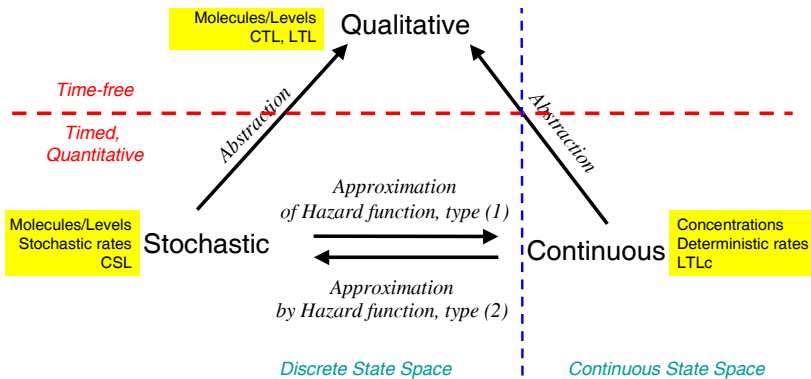
if the concentration of RafP is at a significant concentration level and that of ERKPP is close to zero, then both species remain in these states until the concentration of MEKPP becomes significant ; i.e. *MEKPP is the second species to react.*

$$\begin{aligned} & ((\text{RafP} > 0.06) \wedge (\text{ERKPP} < 0.0002)) \Rightarrow \\ & \quad ((\text{RafP} > 0.06) \wedge (\text{ERKPP} < 0.0002)) \mathbf{U} (\text{MEKPP} > 0.004) \end{aligned}$$

property C3 :

if the concentrations of RafP and MEKPP are significant, they remain so, until the concentration of ERKPP becomes significant ;
i.e. *ERKPP is the third species to react.*

$$\left((\text{RafP} > 0.06) \wedge (\text{MEKPP} > 0.004) \right) \Rightarrow \\ \left((\text{RafP} > 0.06) \wedge (\text{MEKPP} > 0.004) \right) \mathbf{U} (\text{ERKPP} > 0.0005)$$



- *validation criterion 1*
 - all expected structural properties hold
 - all expected general behavioural properties hold

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- *validation criterion 3*
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 - no known biological behaviour without corresponding T-invariant
- *validation criterion 4*
 - all expected special behavioural properties hold
 - temporal-logic properties yield TRUE

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qualitative & stochastic & continuous paradigms

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- **not bound to the Petri net perspective**

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stochastic and continuous behaviour may differ ; why? when?
- *sharing structure = sharing properties*
BUT, to which extend?
relation : qualitative properties & continuous behaviour?

- all data files and analysis results available at www-dssz.informatik.tu-cottbus.de/examples/levchenko
- M Heiner, D Gilbert, R Donaldson :
Petri Nets for Systems and Synthetic Biology ;
SFM 2008, Springer LNCS 5016, pp. 215-264, 2008.