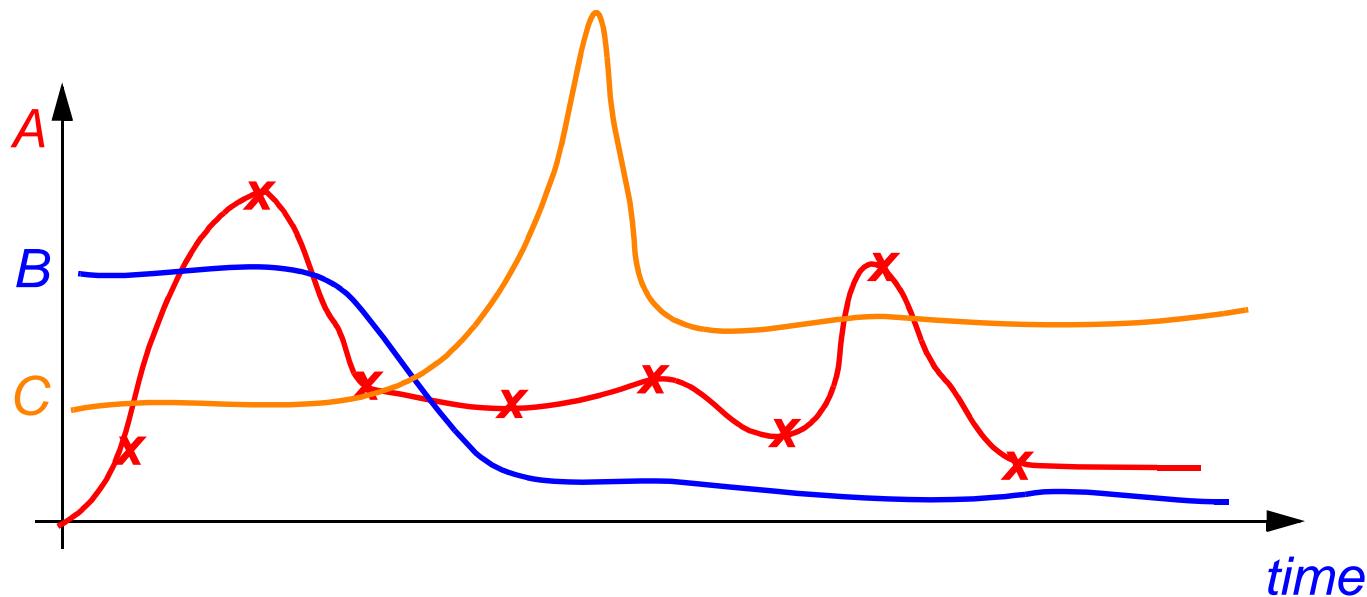
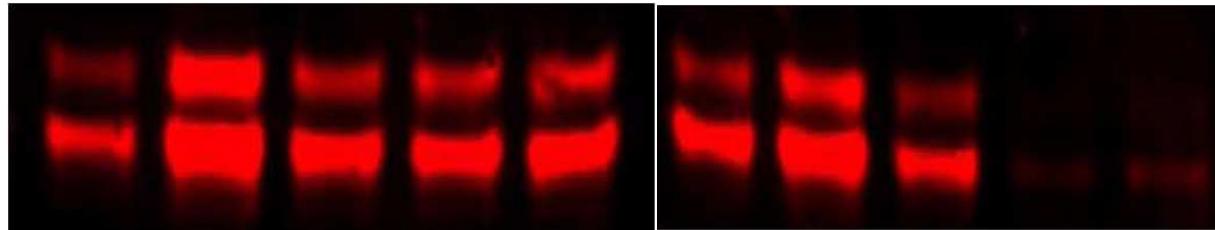


# **BIOMODEL ENGINEERING**

## **- A PETRI NET PERSPECTIVE -**

**Monika Heiner**

**Brandenburg University of Technology Cottbus**  
**Computer Science Institute**



**Qualitative**

*Protein rises then falls*

**Semi-qualitative**

*Protein rises then falls to less than 50% of its peak concentration*

**Semi-quantitative**

*Protein rises then falls to less than 50% of its peak concentration at 60 minutes*

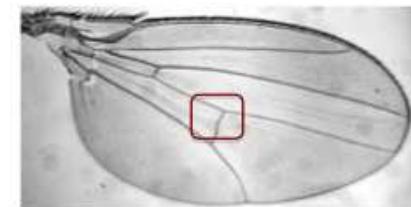
**Quantitative**

*Protein rises then falls to less than 100 microMol at 60 minutes*

*-> networks explaining the observations ?*

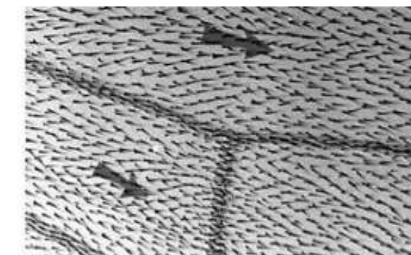
## □ BACKGROUND

- > *modelling, what for ?*
- > *how many model types do we need ?*



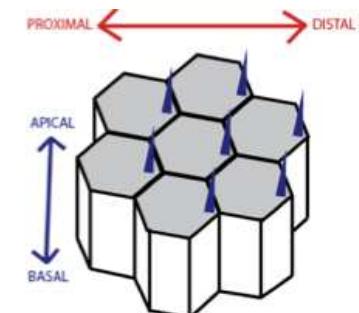
## □ FRAMEWORK

- > *unifying four paradigms: QPN - SPN - CPN - HPN*
- > *some case studies*
- > *moving between paradigms*



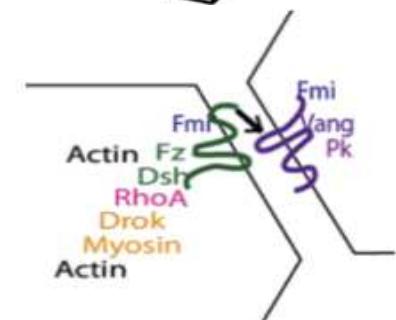
## □ COLOUR AND MULTI-SCALE SYSTEM

- > *replication*
- > *encoding space*



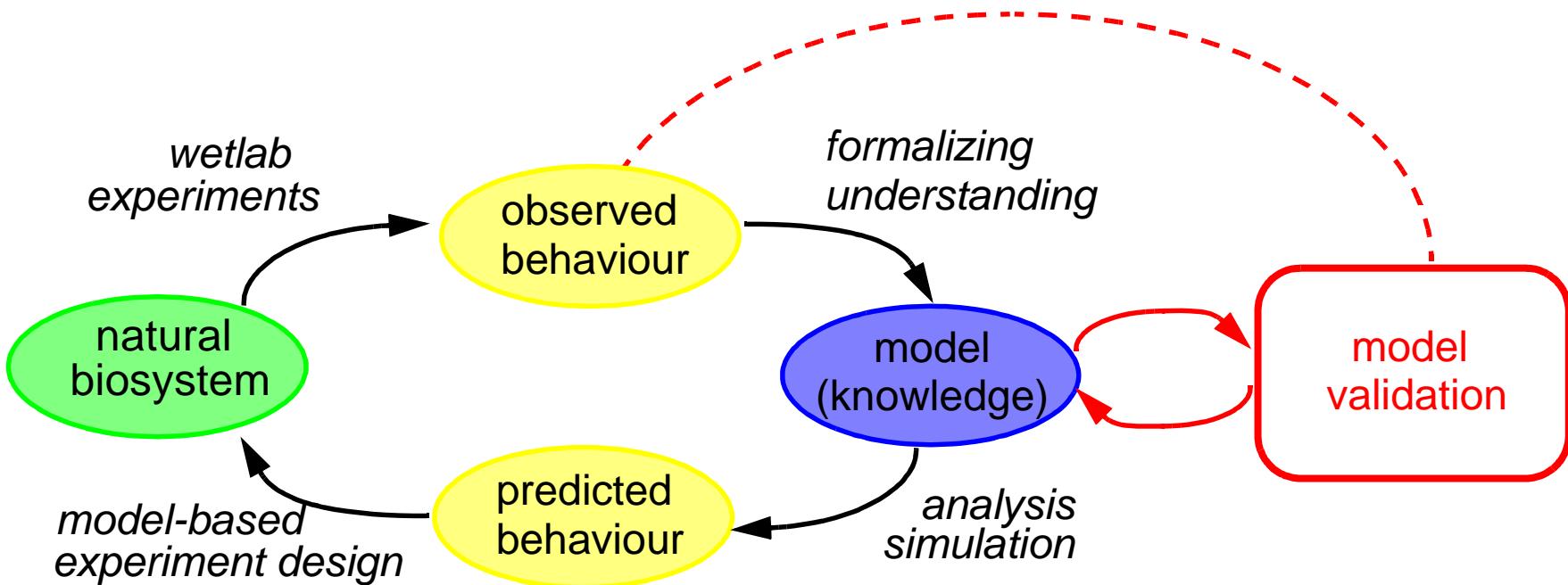
## □ SUMMARY & OUTLOOK

- > *open problems*
- > *next steps*



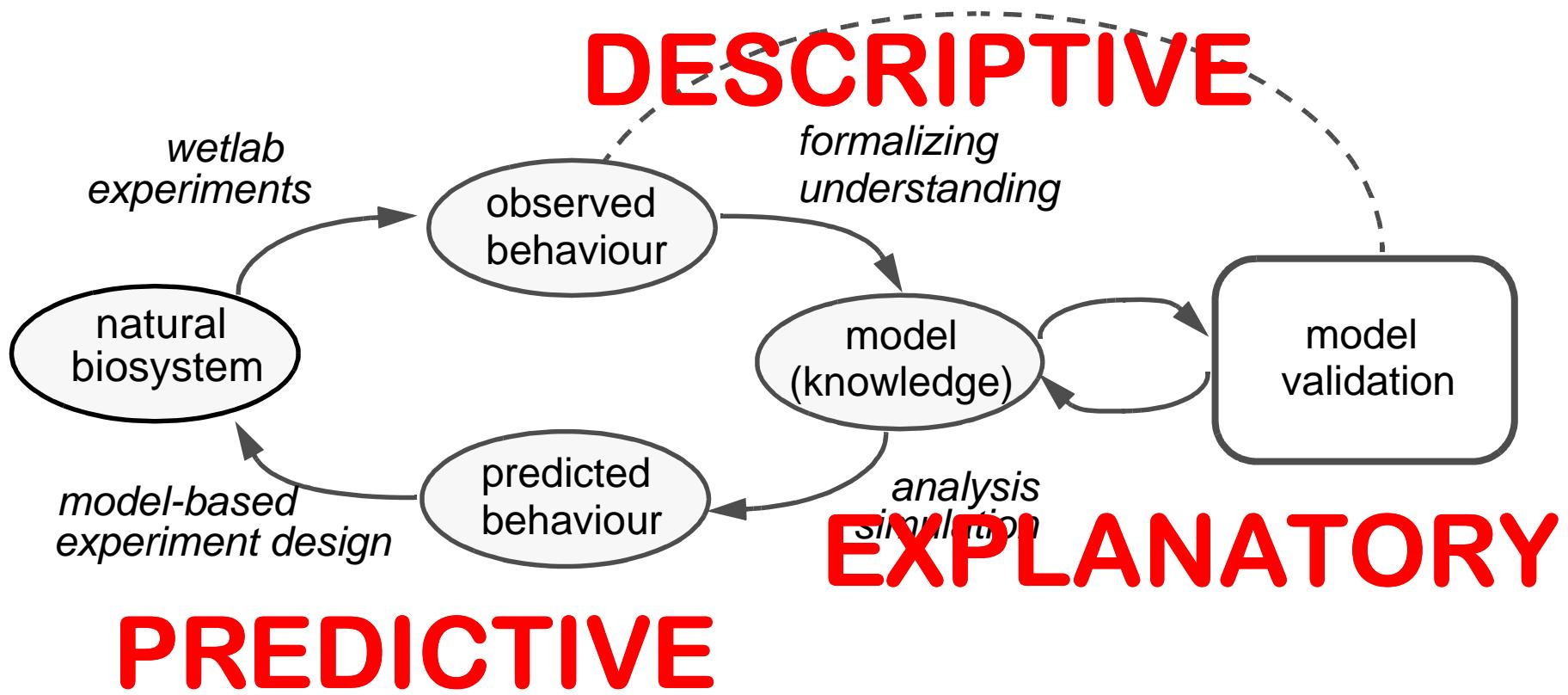
# **BACKGROUND**

## MODELLING = FORMAL KNOWLEDGE REPRESENTATION



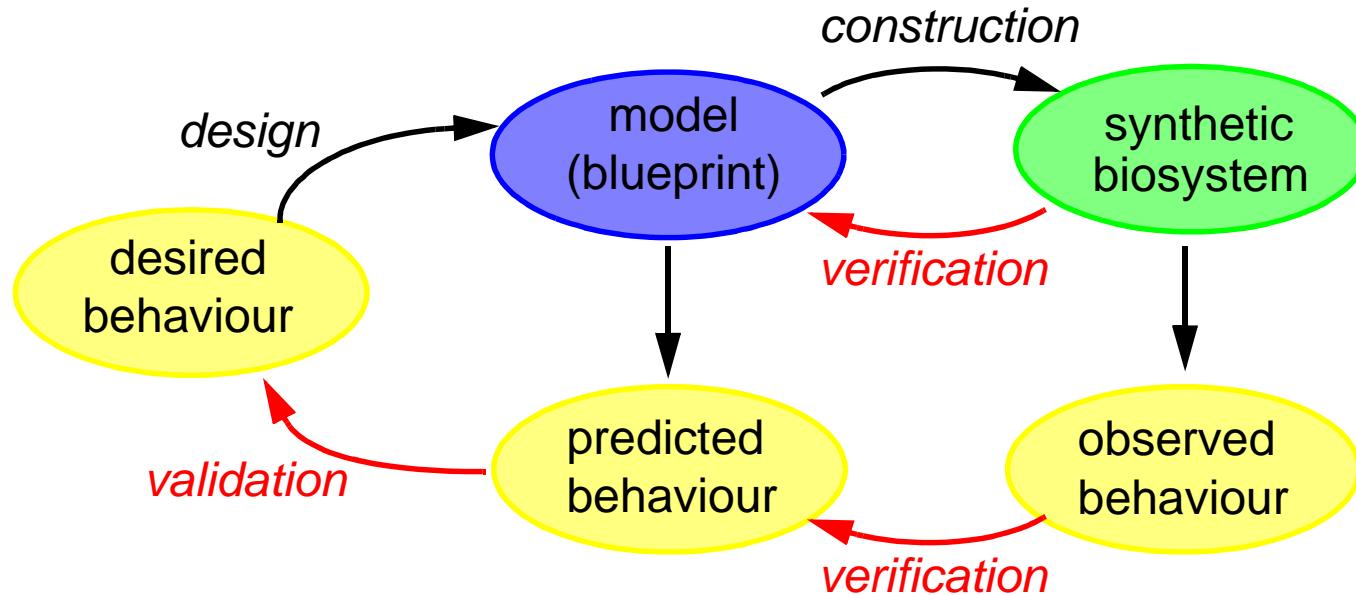
**MODEL VALIDATION = CONFIDENCE INCREASE**

**MODELLING = FORMAL KNOWLEDGE REPRESENTATION**



**MODEL VALIDATION = CONFIDENCE INCREASE**

## MODELLING = BLUEPRINT FOR SYSTEM CONSTRUCTION

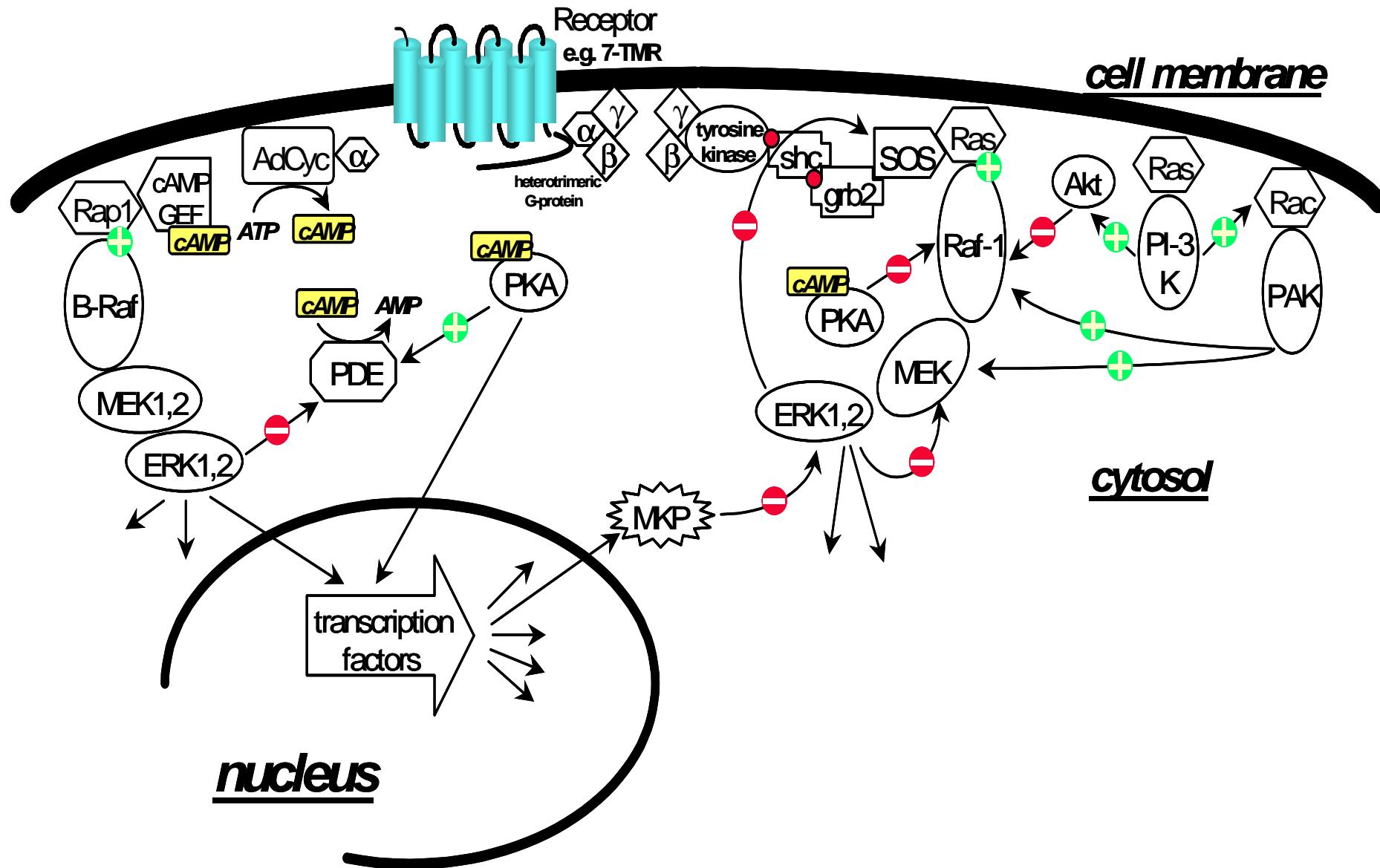


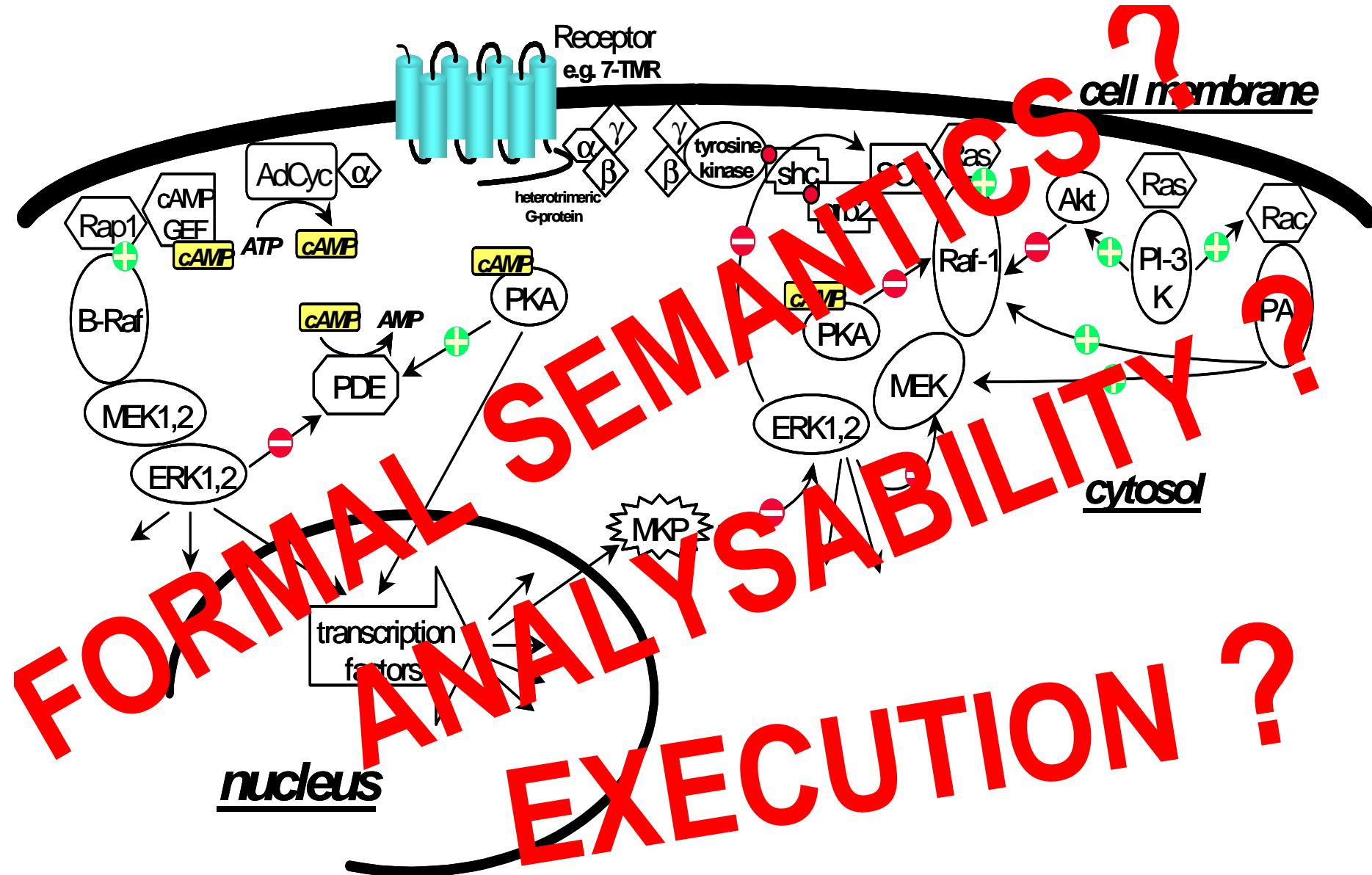
**RELIABLE AND ROBUST ENGINEERING REQUIRES VERIFIED MODELS**

# **WHAT KIND OF MODEL SHOULD BE USED? (BIOCHEMICAL NETWORKS)**

# NETWORK REPRESENTATIONS, Ex1

PN & BioModel Engineering





## NETWORK REPRESENTATIONS, Ex2

PN & BioModel Engineering

$$\begin{aligned}
 \frac{d\alpha}{dt} &= -v_1 \\
 \frac{dSte2}{dt} &= -v_2 + v_3 - v_5 \\
 \frac{dSte2_{active}}{dt} &= v_2 - v_3 - v_4 \\
 \frac{dSst2_{active}}{dt} &= v_{46} - v_{47} \\
 \frac{dG\alpha\beta\gamma}{dt} &= -v_6 + v_9 \\
 \frac{dG\alpha GTP}{dt} &= v_6 - v_7 - v_8 \\
 \frac{dG\alpha GDP}{dt} &= v_7 + v_8 - v_9 \\
 \frac{dG\beta\gamma}{dt} &= v_6 - v_9 - v_{10} + v_{11} + v_{21} + v_{23} + v_{25} + v_{27} + v_{32} \\
 &\quad - v_{42} + v_{43} \\
 \frac{dSte5}{dt} &= -v_{12} + v_{13} + v_{17} + v_{21} + v_{23} + v_{25} + v_{27} + v_{32} \\
 \frac{dSte11}{dt} &= -v_{12} + v_{13} + v_{17} + v_{21} + v_{23} + v_{25} + v_{27} + v_{32} \\
 \frac{dSte7}{dt} &= -v_{14} + v_{15} + v_{17} + v_{21} + v_{23} + v_{25} + v_{27} + v_{32} \\
 \frac{dFus3}{dt} &= -v_{14} + v_{15} + v_{17} + v_{21} + v_{23} + v_{25} + v_{27} - v_{29} \\
 &\quad + v_{30} + v_{33} \\
 \frac{dSte20}{dt} &= -v_{18} + v_{19} + v_{21} + v_{23} + v_{25} + v_{27} + v_{32}
 \end{aligned}$$

$$\begin{aligned}
 v_1 &= \alpha[t] \cdot Bar1_{active}[t] \cdot k_1 \\
 v_2 &= Ste2[t] \cdot \alpha[t] \cdot k_2 \\
 v_3 &= Ste2_{active}[t] \cdot k_3 \\
 v_4 &= Ste2_{active}[t] \cdot k_4 \\
 v_5 &= Ste2[t] \cdot k_5 \\
 v_6 &= Ste2_{active}[t] \cdot G\alpha\beta\gamma[t] \cdot k_6 \\
 v_7 &= G\alpha GTP[t] \cdot k_7 \\
 v_8 &= G\alpha GTP[t] \cdot Sst2_{active}[t] \cdot k_8 \\
 v_9 &= G\alpha GDP[t] \cdot G\beta\gamma[t] \cdot k_9 \\
 v_{10} &= G\beta\gamma[t] \cdot C[t] \cdot k_{10} \\
 v_{11} &= D[t] \cdot k_{11} \\
 v_{12} &= Ste5[t] \cdot Ste11[t] \cdot k_{12} \\
 v_{13} &= A[t] \cdot k_{13} \\
 v_{14} &= Ste7[t] \cdot Fus3[t] \cdot k_{14} \\
 v_{15} &= B[t] \cdot k_{15} \\
 v_{16} &= A[t] \cdot B[t] \cdot k_{16} \\
 v_{17} &= C[t] \cdot k_{17} \\
 v_{18} &= D[t] \cdot Ste20[t] \cdot k_{18}
 \end{aligned}$$

$$\begin{aligned}\frac{d\alpha}{dt} &= -v_1 \\ \frac{d\text{Ste2}}{dt} &= -v_2 + v_3 - v_5 \\ \frac{d\text{Ste2}_{\text{active}}}{dt} &= v_2 - v_3 - v_4 \\ \frac{d\text{Sst2}_{\text{active}}}{dt} &= v_{46} - v_{47} \\ \frac{d\text{G}\alpha\beta\gamma}{dt} &= -v_6 + v_9 \\ \frac{d\text{G}\alpha\text{GTP}}{dt} &= v_6 - v_7 - v_8 \\ \frac{d\text{G}\alpha\text{GDP}}{dt} &= v_7 + v_8 - v_9 \\ \frac{d\text{G}\beta\gamma}{dt} &= v_6 - v_9 - v_{10} + v_{11} + v_{21} + v_{23} + v_{25} + v_{27} + v_{32} \\ &\quad - v_{42} + v_{43} \\ \frac{d\text{Ste5}}{dt} &= -v_{12} + v_{13} + v_{17} + v_{21} + v_{23} + v_{25} + v_{27} + v_{32} \\ \frac{d\text{Ste7}}{dt} &= -v_{12} + v_{13} + v_{17} + v_{21} + v_{22} + v_{25} + v_{27} + v_{32} \\ \frac{d\text{Fus3}}{dt} &= -v_{14} + v_{15} + v_{17} + v_{21} + v_{23} + v_{25} + v_{27} + v_{32} \\ \frac{d\text{Fus3}}{dt} &= -v_{14} + v_{15} + v_{17} + v_{21} + v_{23} + v_{25} + v_{27} - v_{29} \\ &\quad + v_{30} + v_{33} \\ \frac{d\text{Ste20}}{dt} &= -v_{18} + v_{19} - v_{20} + v_{23} + v_{25} + v_{27} + v_{32}\end{aligned}$$

READABILITY?

CAUSALITY?

UNIQUE STRUCTURE?

$$\begin{aligned}v_1 &= \alpha[t] \cdot \text{Bar1}_{\text{active}}[t] \cdot k_1 \\ v_2 &= \text{Ste2}[t] \cdot \alpha[t] \cdot k_2 \\ v_3 &= \text{Ste2}_{\text{active}}[t] \cdot k_3 \\ v_4 &= \text{Ste2}_{\text{active}}[t] \cdot k_4 \\ v_5 &= \text{Ste2}[t] \cdot k_5 \\ v_6 &= \text{Ste2}_{\text{active}}[t] \cdot \text{G}\alpha\beta\gamma[t] \cdot k_6 \\ v_7 &= \text{G}\alpha\text{GTP}[t] \cdot k_7 \\ v_8 &= \text{G}\alpha\text{GTP}[t] \cdot \text{Sst2}_{\text{active}}[t] \cdot k_8 \\ v_9 &= \text{G}\alpha\text{GDP}[t] \cdot \text{G}\beta\gamma[t] \cdot k_9 \\ v_{10} &= \text{G}\beta\gamma[t] \cdot \text{C}[t] \cdot k_{10} \\ v_{11} &= \text{C}[t] \cdot k_{11} \\ v_{12} &= \text{Ste5}[t] \cdot \text{Ste11}[t] \cdot k_{12} \\ v_{13} &= \text{A}[t] \cdot k_{13} \\ v_{14} &= \text{Ste7}[t] \cdot \text{Fus3}[t] \cdot k_{14} \\ v_{15} &= \text{B}[t] \cdot k_{15} \\ v_{16} &= \text{A}[t] \cdot \text{B}[t] \cdot k_{16} \\ v_{17} &= \text{C}[t] \cdot k_{17} \\ v_{18} &= \text{D}[t] \cdot \text{Ste20}[t] \cdot k_{18}\end{aligned}$$

□ **knowledge**

-> **PROBLEM 1**

- > *uncertain*
- > *growing, changing*
- > *distributed over independent data bases, papers, journals, . . .*

□ **various, mostly ambiguous representations**

-> **PROBLEM 2**

- > *verbose descriptions*
- > *diverse graphical representations*
- > *contradictory and / or fuzzy statements*

□ **network structure**

-> **PROBLEM 3**

- > *tend to grow fast*
- > *dense, apparently unstructured*
- > *hard to read*

- knowledge

- > *uncertain*
- > *growing, changing*
- > *distributed over independent data bases, papers, journals, . . .*

-> PROBLEM 1

- variables mostly no just representations

- > *verbless descriptions*
- > *diverse graphical representations*
- > *contradictory and / or many statements*

-> PROBLEM 2

- network structure

- > *tend to grow fast*
- > *dense, apparently unstructured*
- > *hard to find*

-> PROBLEM 3

**FULL OF ASSUMPTIONS**



- **readable & unambiguous**  
-> *fault avoidant model construction*
- **locality - causality - concurrency**
- **compositional, hierarchical notations**  
-> *logical and macro nodes*
- **executable**  
-> *to experience the model, spec. causality*
- **umbrella with unifying power**  
-> *interpretation in qualitative / stochastic / continuous / hybrid paradigms*
- **Petri net theory**  
-> *P/T-invariants, ADT sets, partial order interpretation of T-invariants, conclusions CTI/CPI -> behavioural properties*  
-> *static analysis techniques: STP, reduction rules, . . .*



**SEE TUTORIALS MILANO 2013**

- **readable & unambiguous**  
-> fault avoidant model construction
- **locality - causality / concurrency**
- **composition, hierarchical notations**  
-> logical and macro nodes
- **executable**  
-> to experience the model spec. causality
- **umbrella with unifying power**  
interpretation in qualitative / stochastic / continuous / hybrid paradigms
- **Petri net theory**  
-> P/T-variants, partial order interpretation of T-invariants,  
congruences CTn/CPI -> behavioural properties  
-> TR-reduction rules, . . .

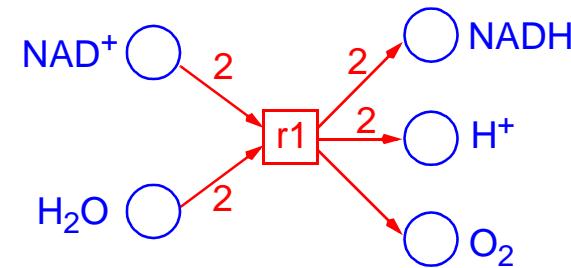
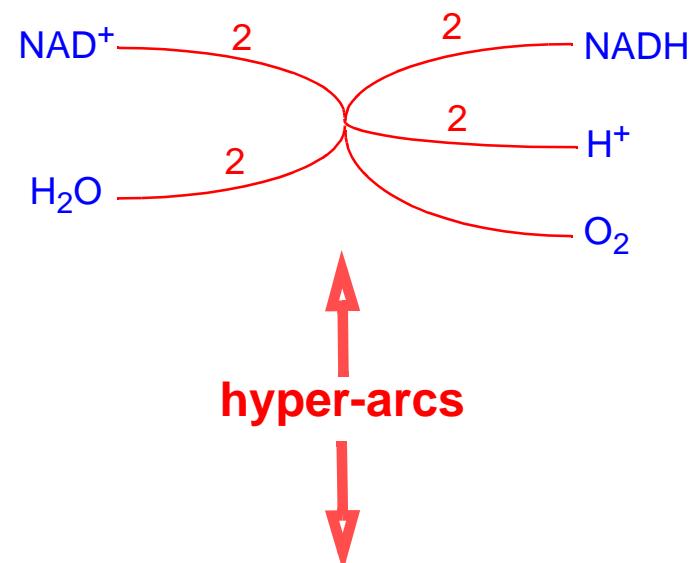
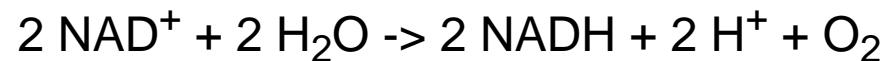
# **THE PETRI NET FRAMEWORK**

---

## ARE NETWORKS OF BIOCHEMICAL REACTIONS

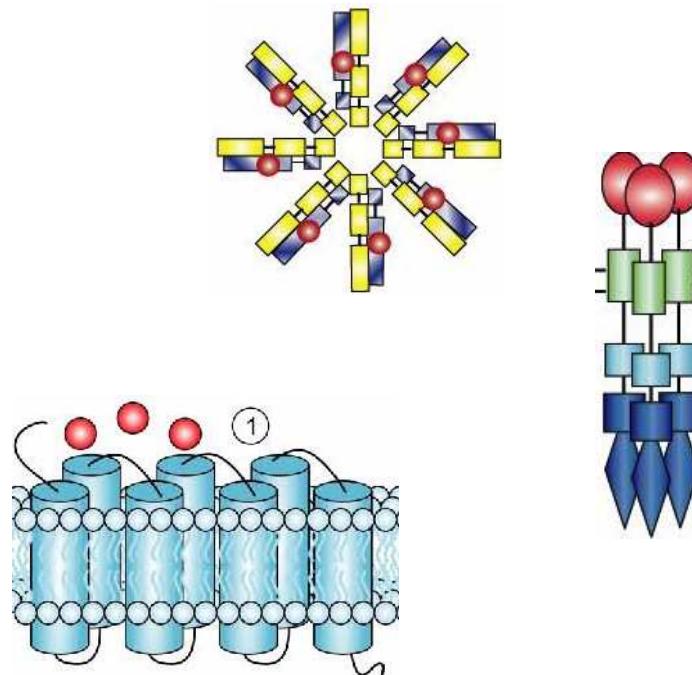
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## NATURALLY EXPRESSIBLE AS PETRI NETS



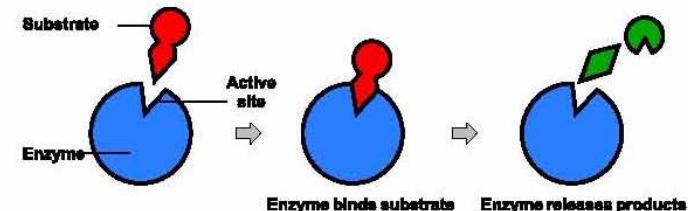
## □ places → model variables

- > (bio-) chemical compounds
- > proteins
- > protein conformations
- > complexes
- > genes, . . . , etc.
- ... in different locations*

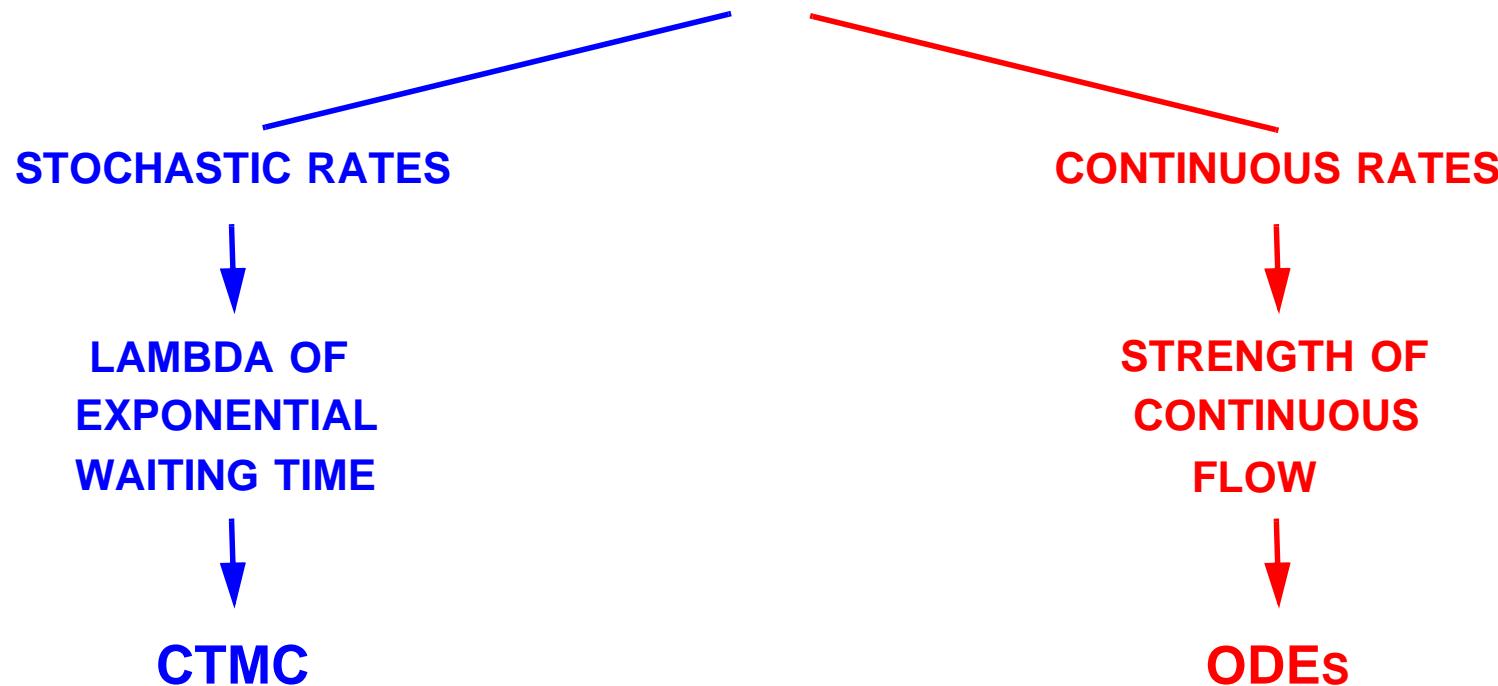


## □ transitions → atomic events

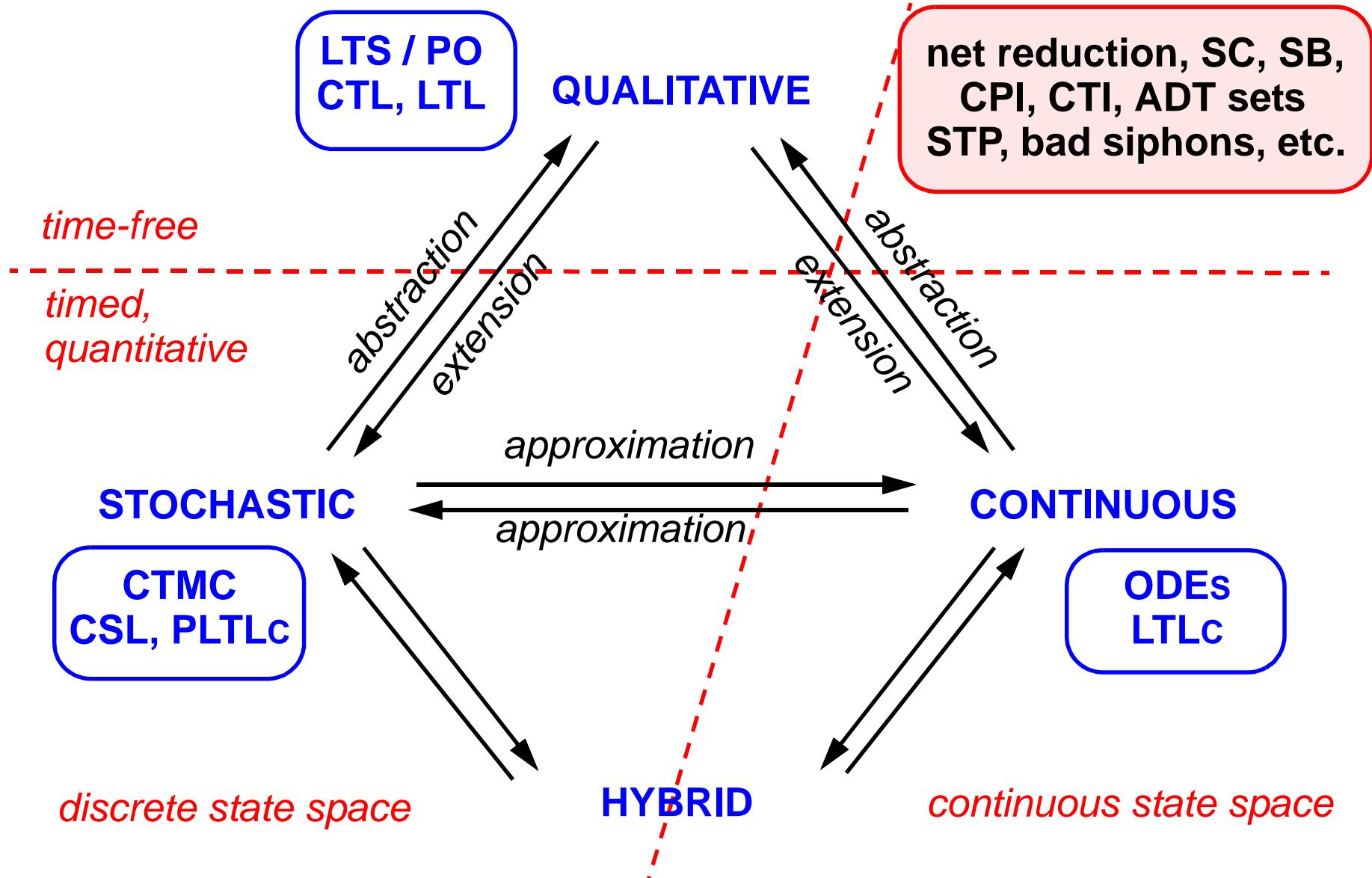
- > (stoichiometric) chemical reaction
- > complexation / decomplexation
- > phosphorylation / dephosphorylation
- > conformational change
- > transport step, . . . , etc.
- ... in different locations*



### STATE-DEPENDENT RATE FUNCTIONS

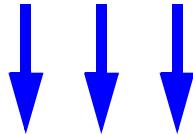


-> supported by, e.g., COPASI, Dizzy, ..., Snoopy



# 4

## MODELS SHARING STRUCTURE



**QUANTITATIVE MODEL = QUALITATIVE MODEL**

**+**

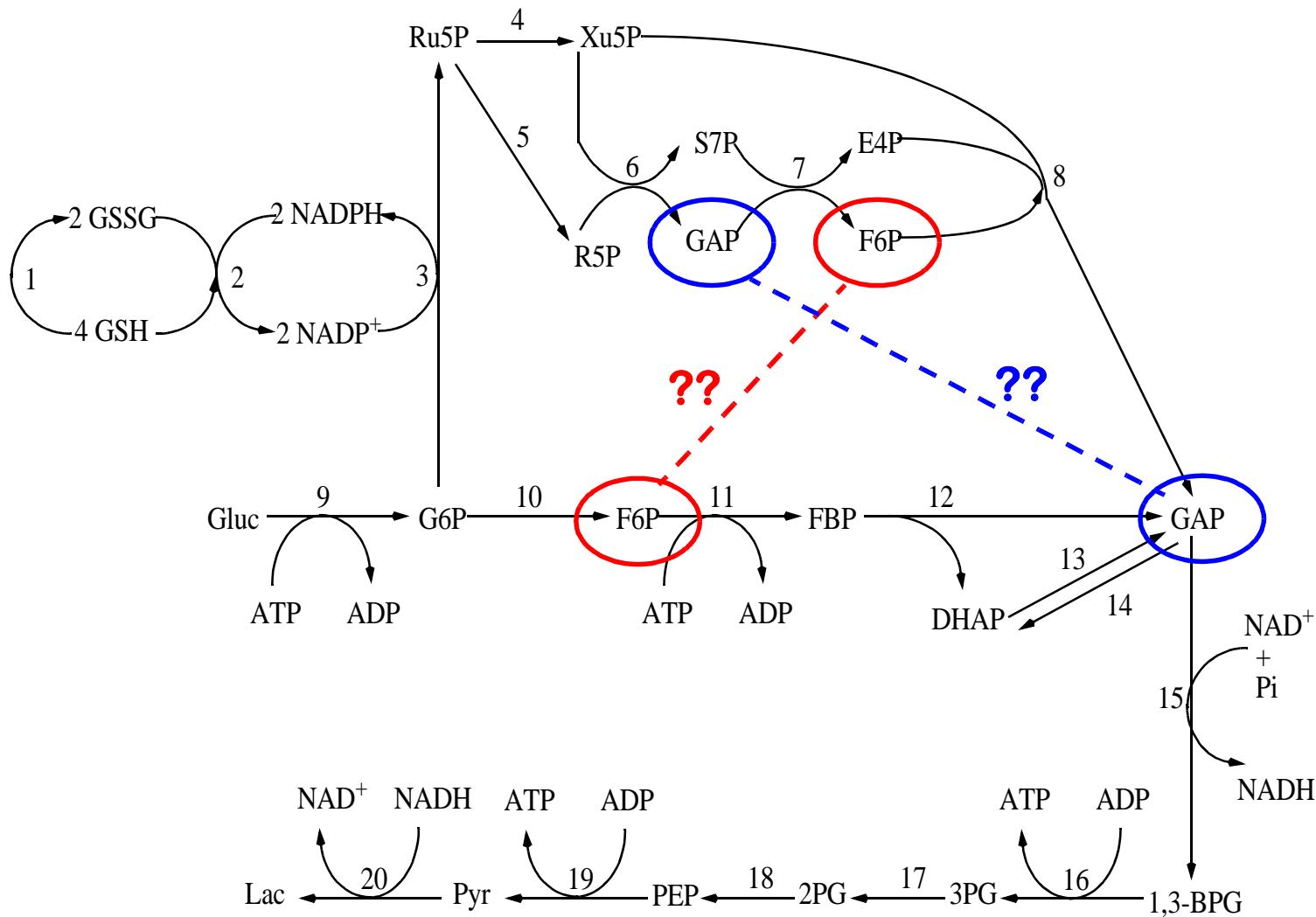
**RATE FUNCTIONS  
(KINETICS)**

# **BIO PETRI NETS - SOME EXAMPLES**

# Ex1 - Glycolysis and Pentose Phosphate Pathway

PN & BioModel Engineering

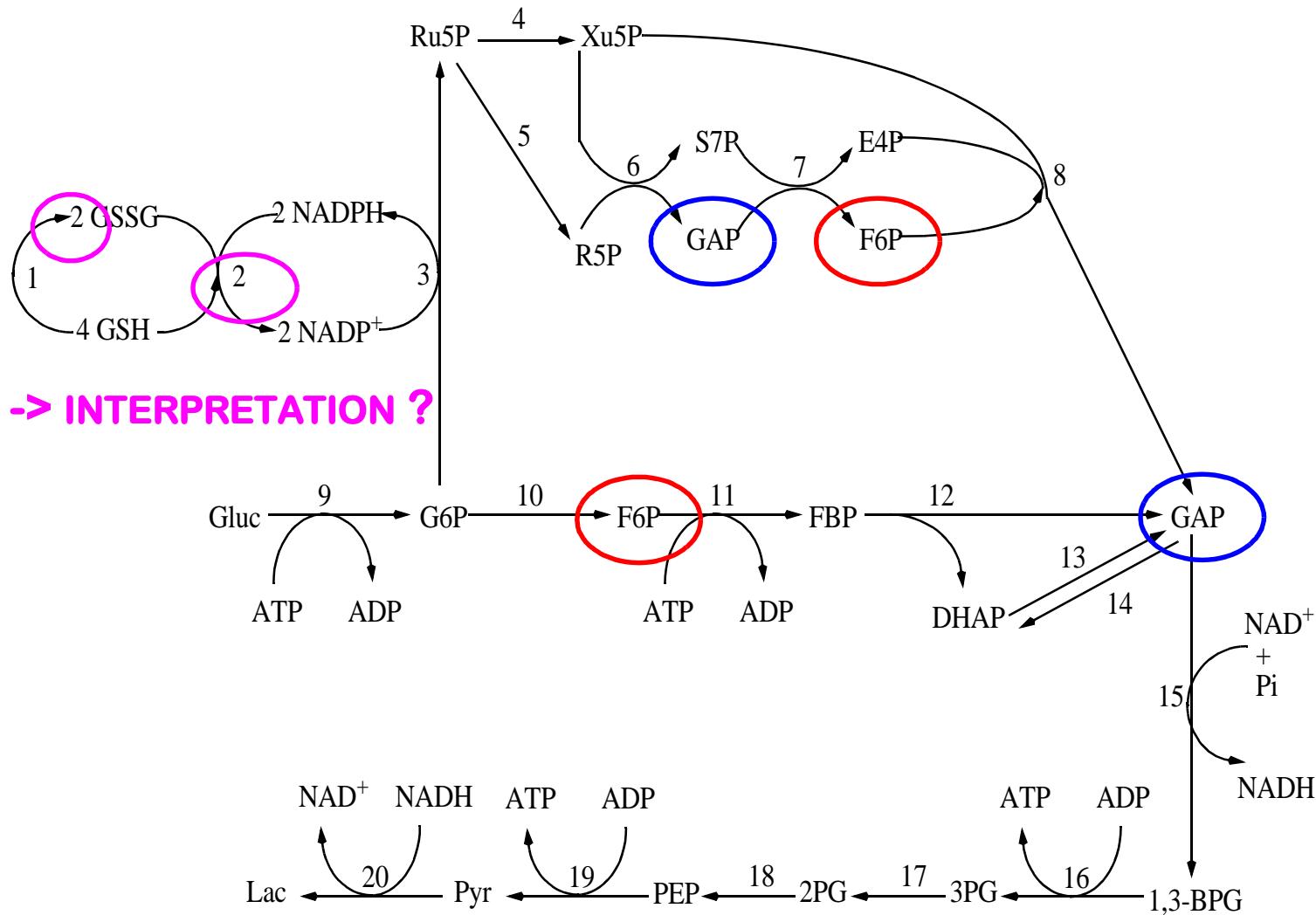
[Reddy 1993]



# Ex1 - Glycolysis and Pentose Phosphate Pathway

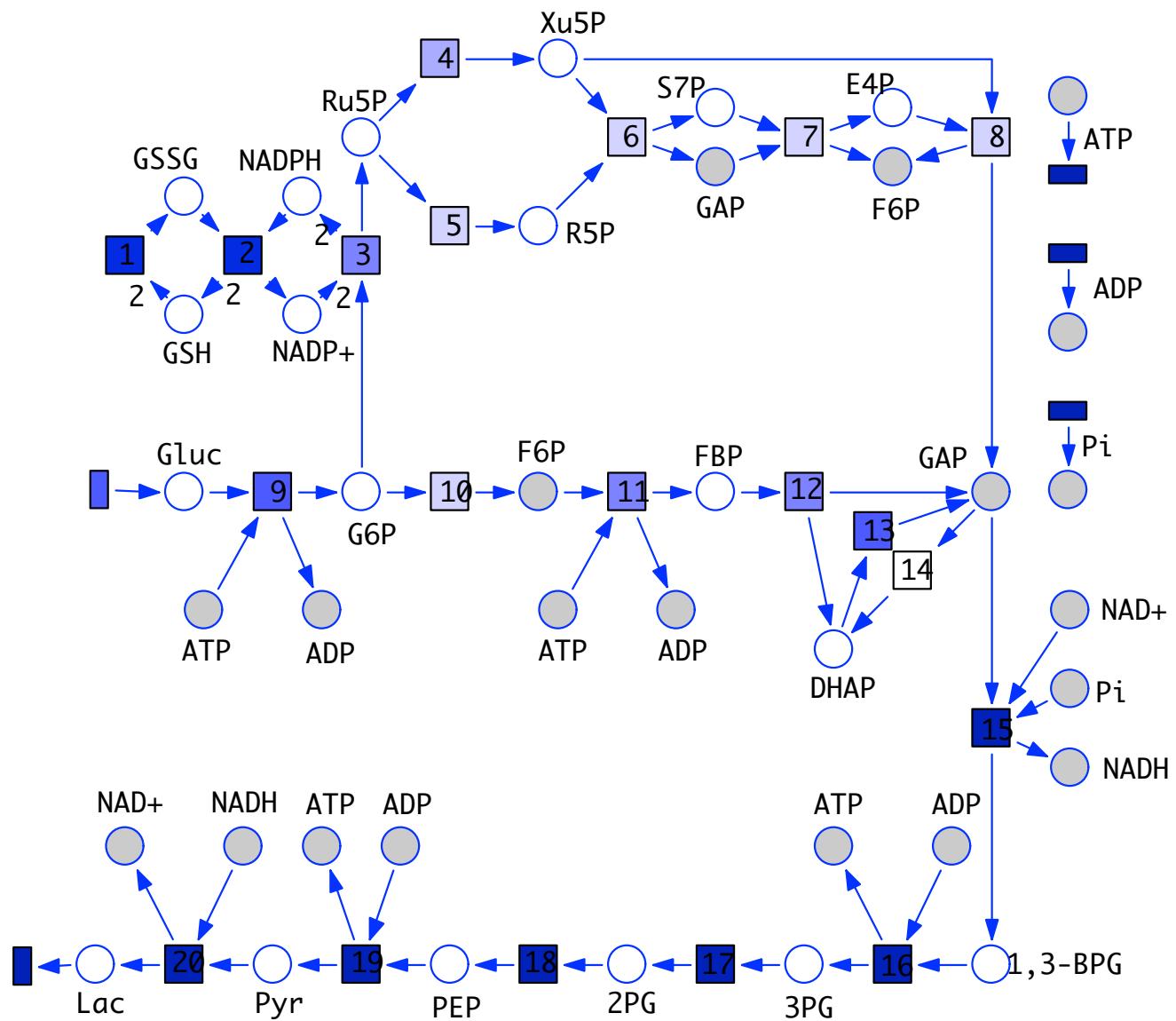
PN & BioModel Engineering

[Reddy 1993]



# Ex1 - Glycolysis and Pentose Phosphate Pathway

PN & BioModel Engineering

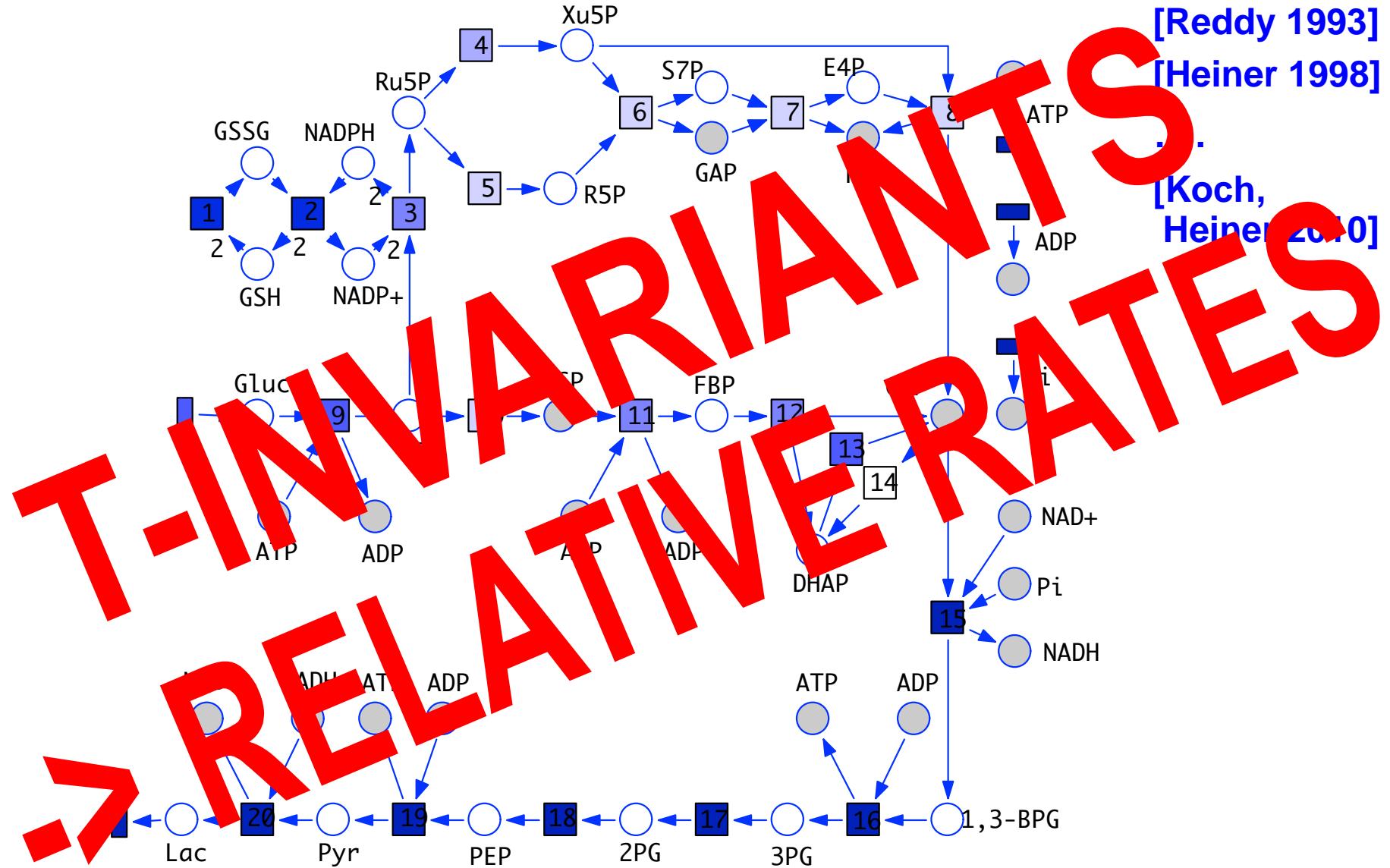


[Reddy 1993]

[Heiner 1998]

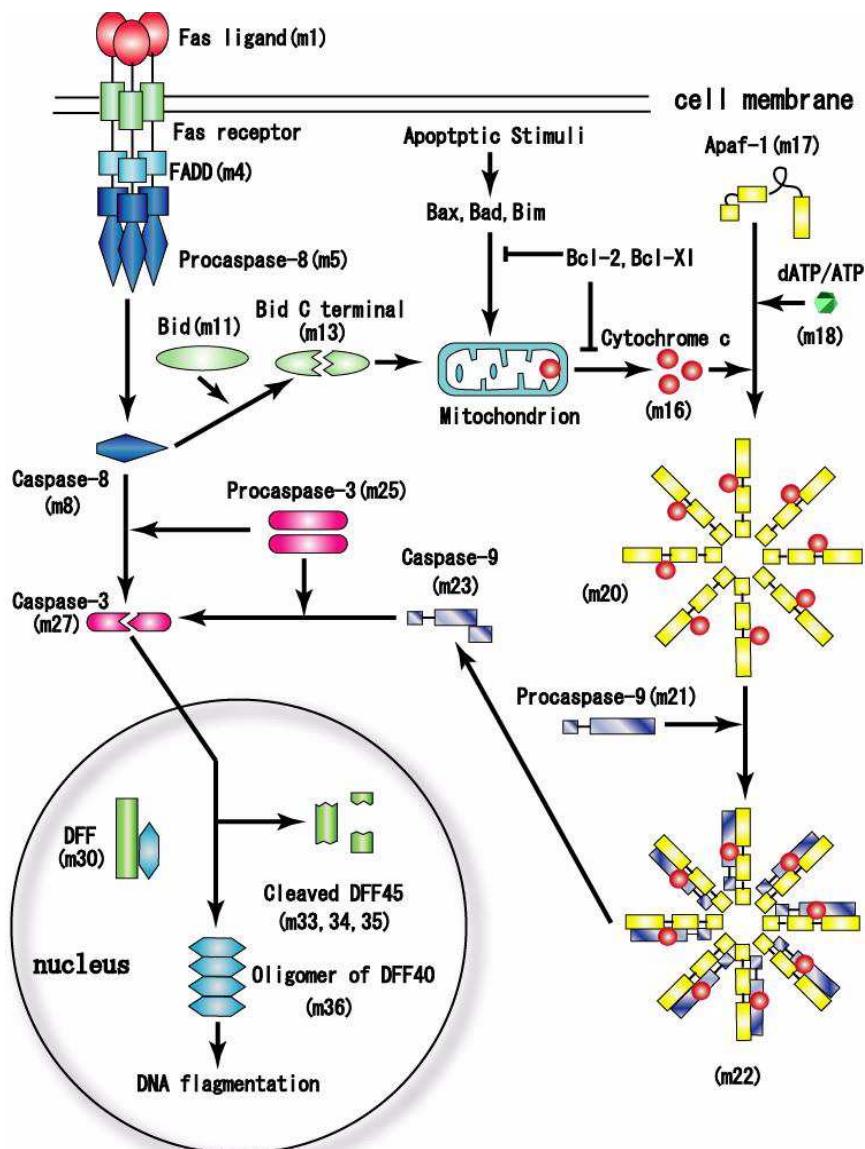
...

[Koch,  
Heiner 2010]

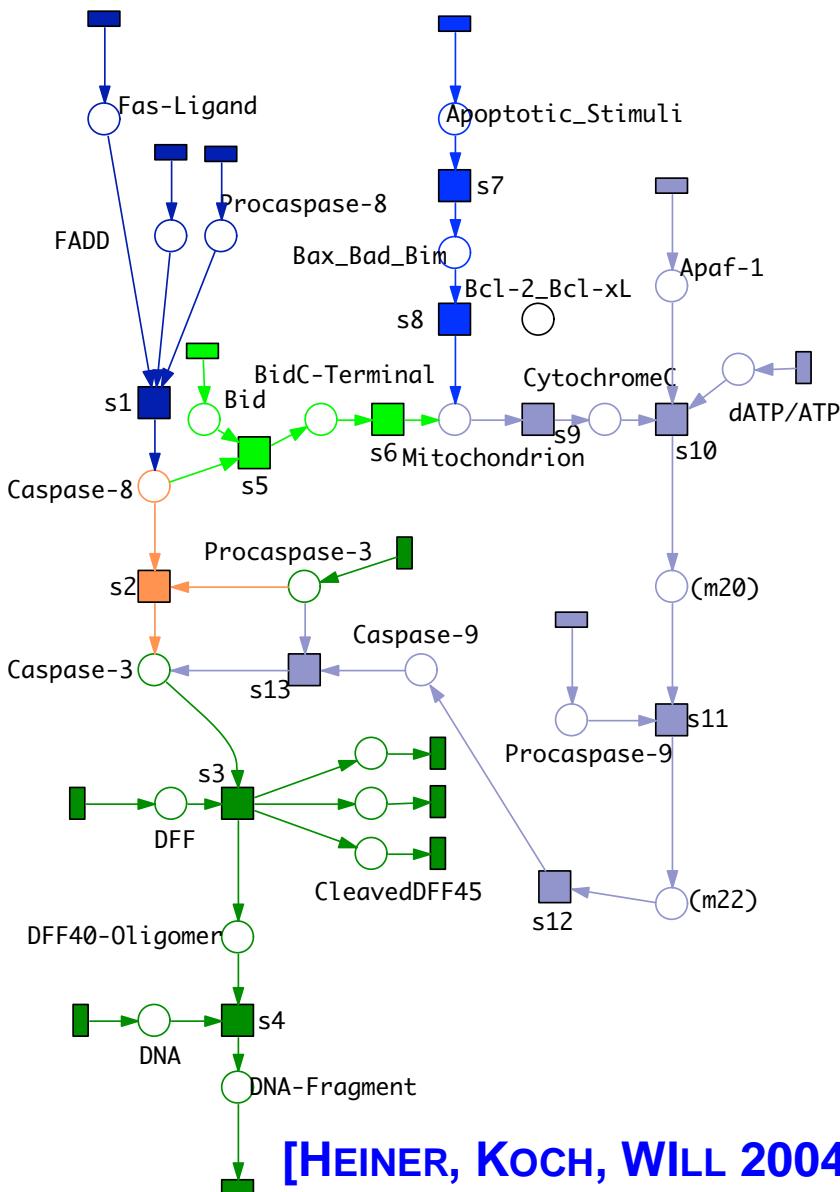


## Ex2 - APOPTOSIS IN MAMMALIAN CELLS

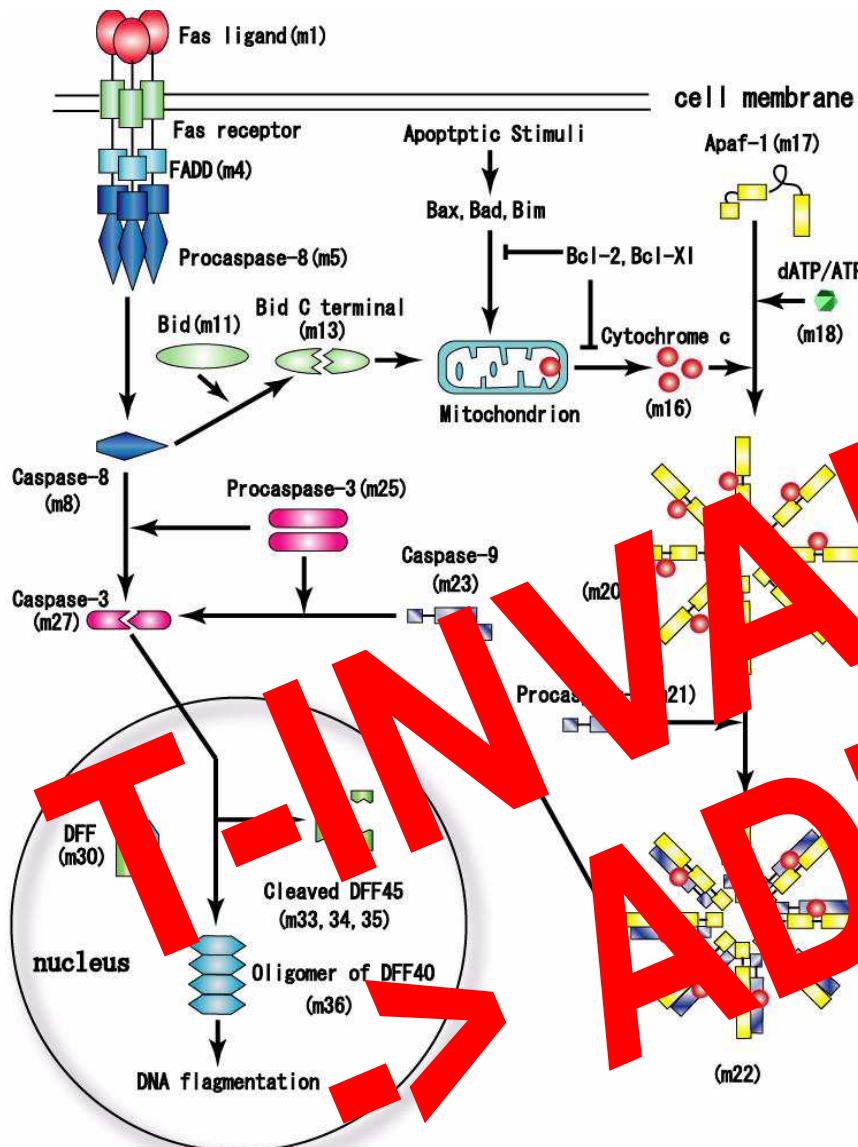
PN & BioModel Engineering



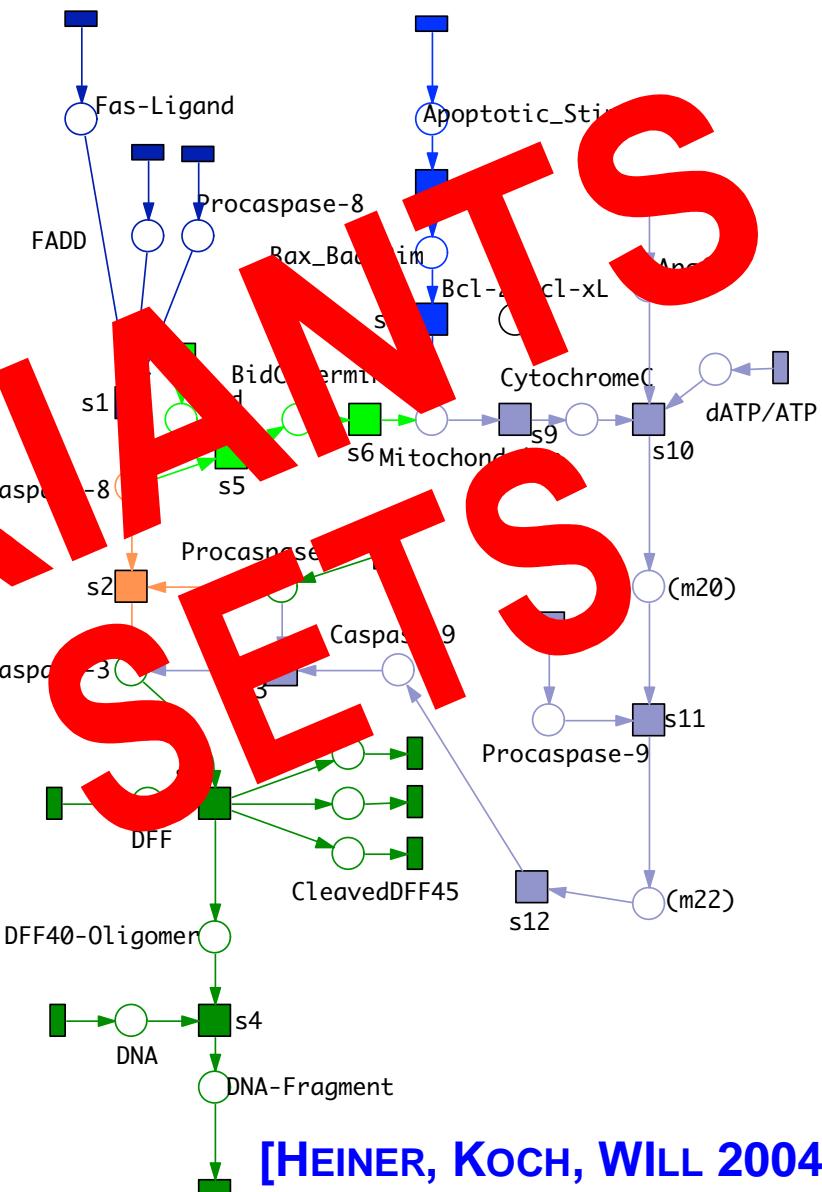
[GON 2003]



[HEINER, KOCH, WILL 2004]

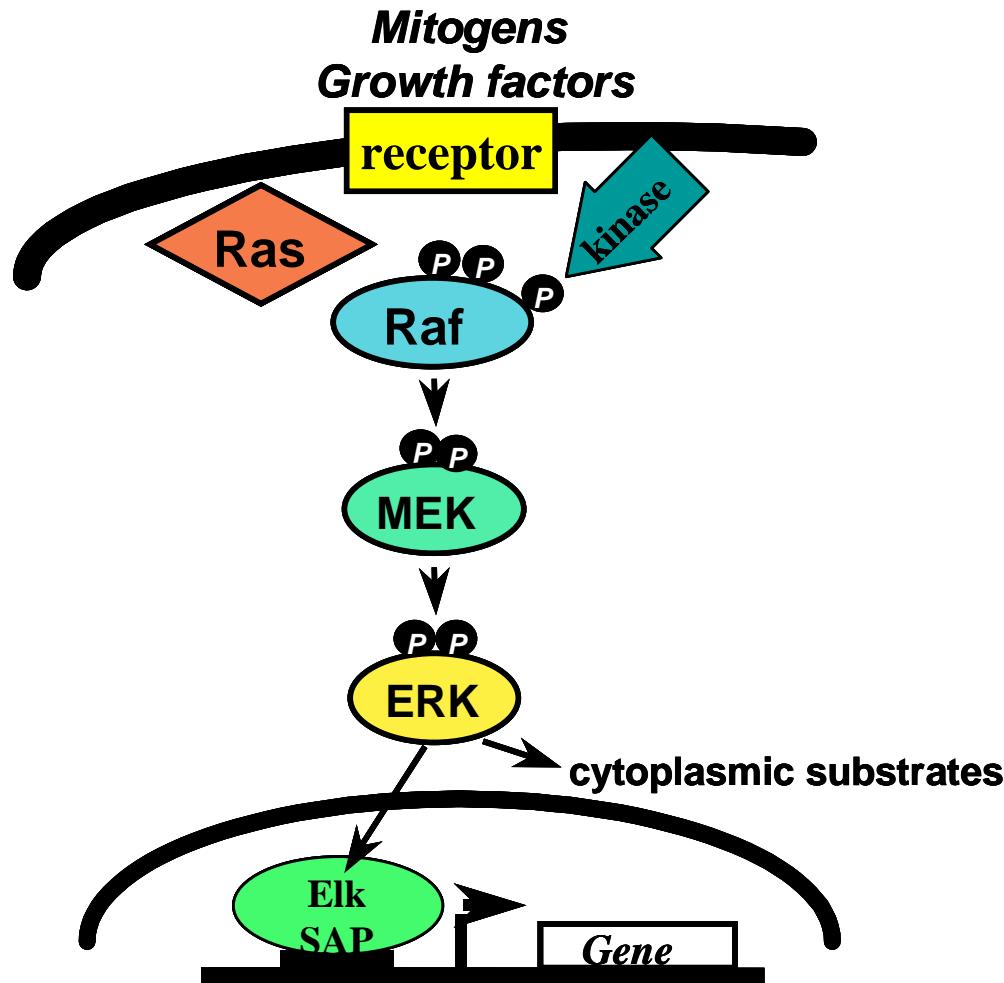


[GON 2003]



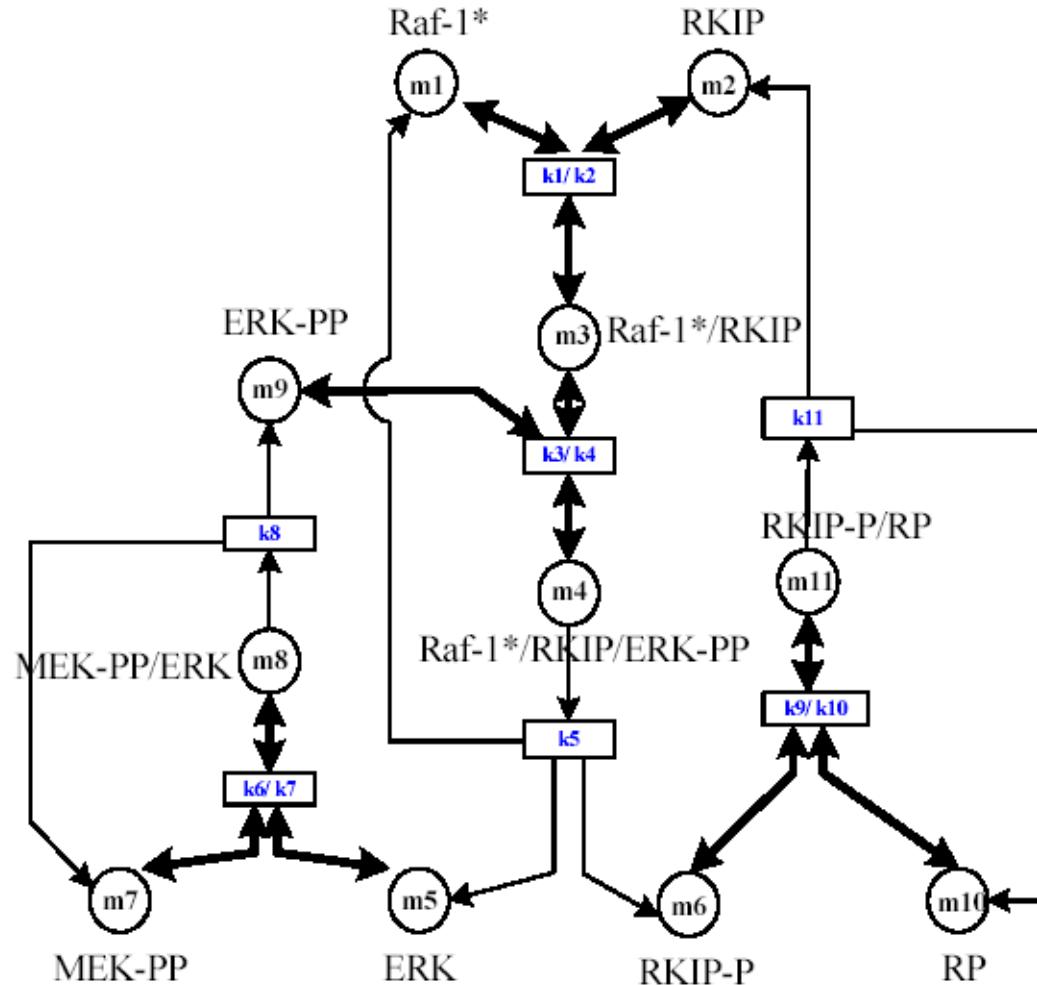
[HEINER, KOCH, WILL 2004]

...one pathway...



## Ex3 - RKIP SIGNALLING PATHWAY

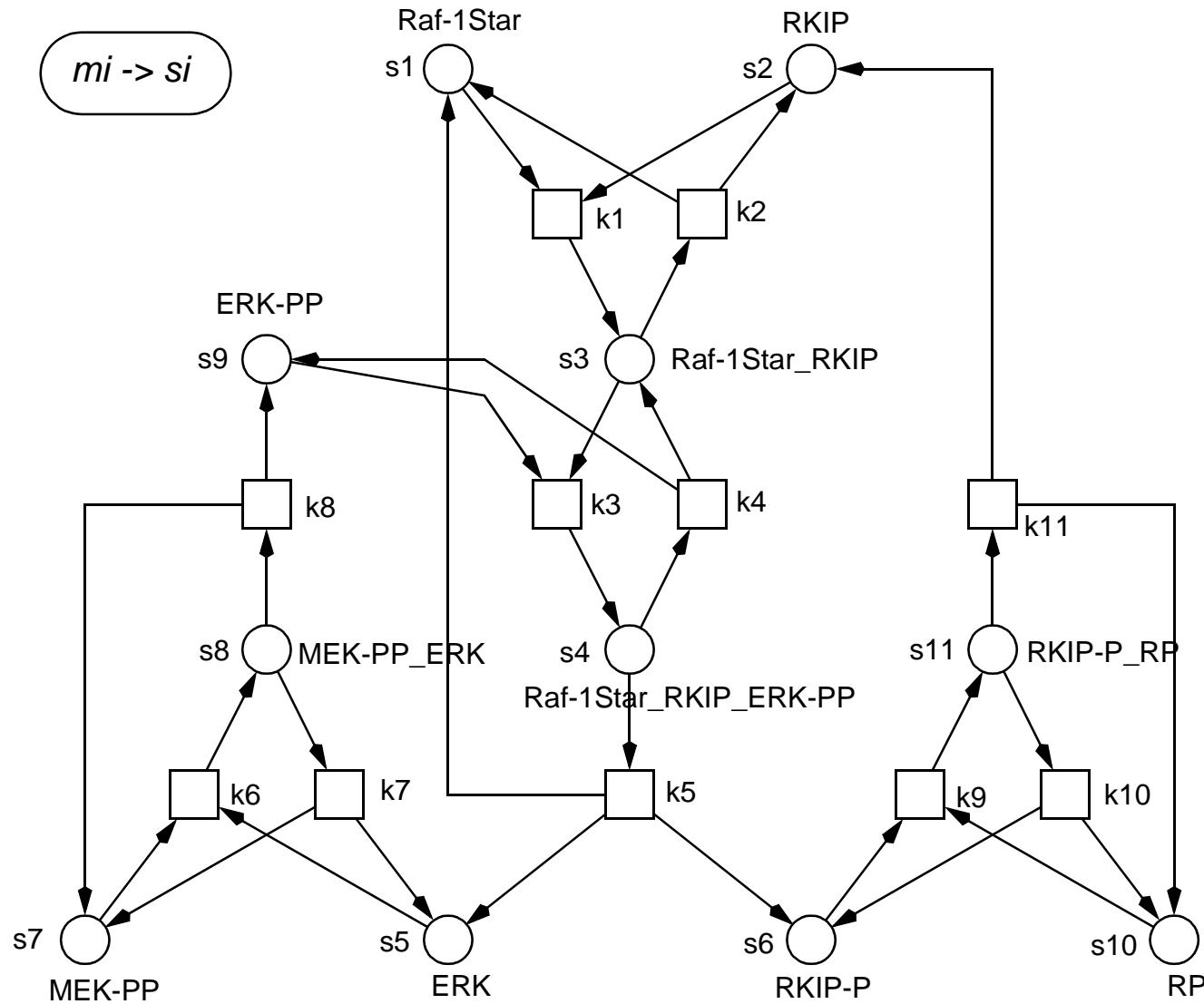
PN & BioModel Engineering



[Cho et al. 2003]

## Ex3 - RKIP SIGNALLING PATHWAY, PETRI NET

PN & BioModel Engineering

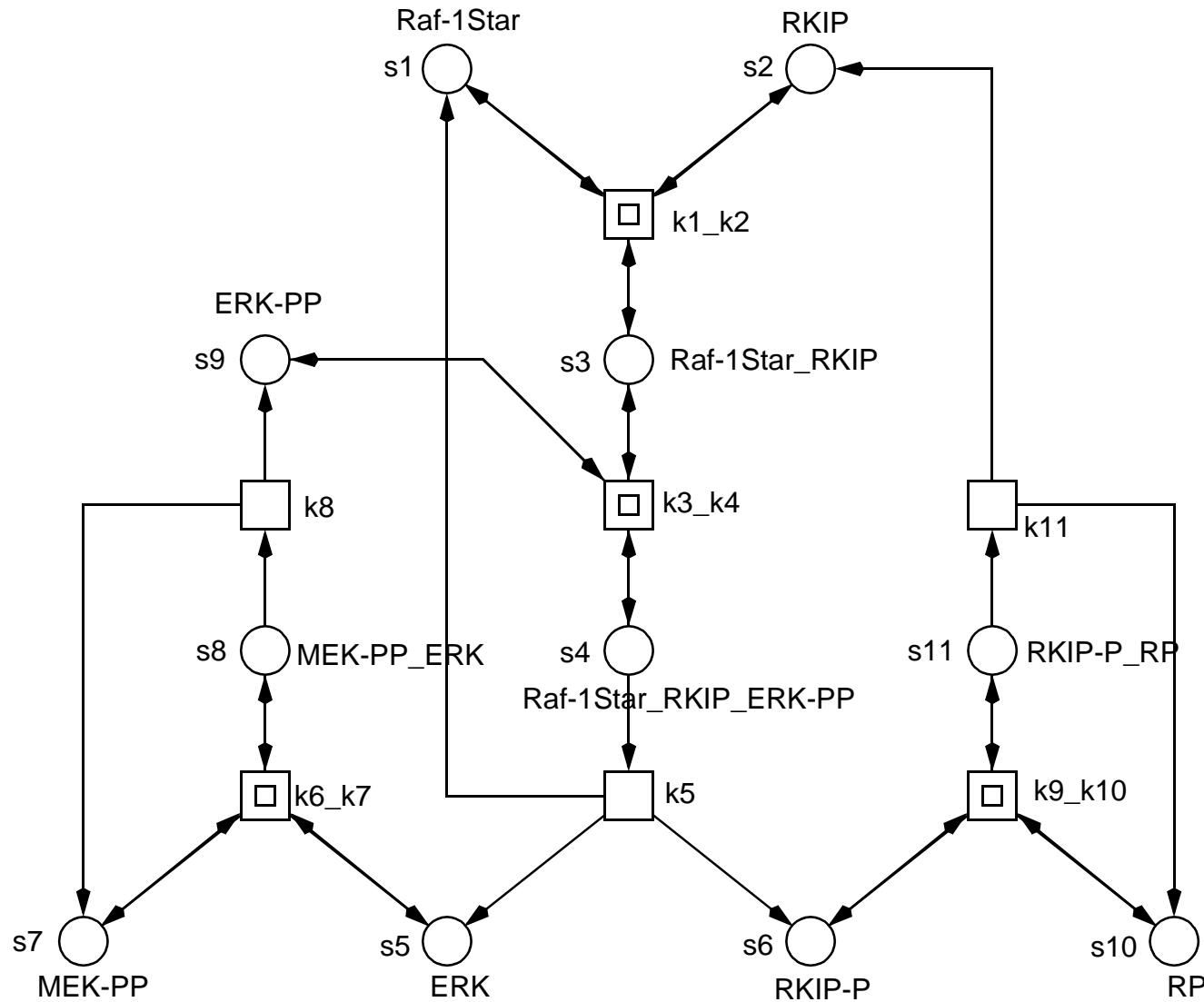


[HEINER,  
GILBERT 2006]

[HEINER,  
DONALDSON,  
GILBERT 2010]

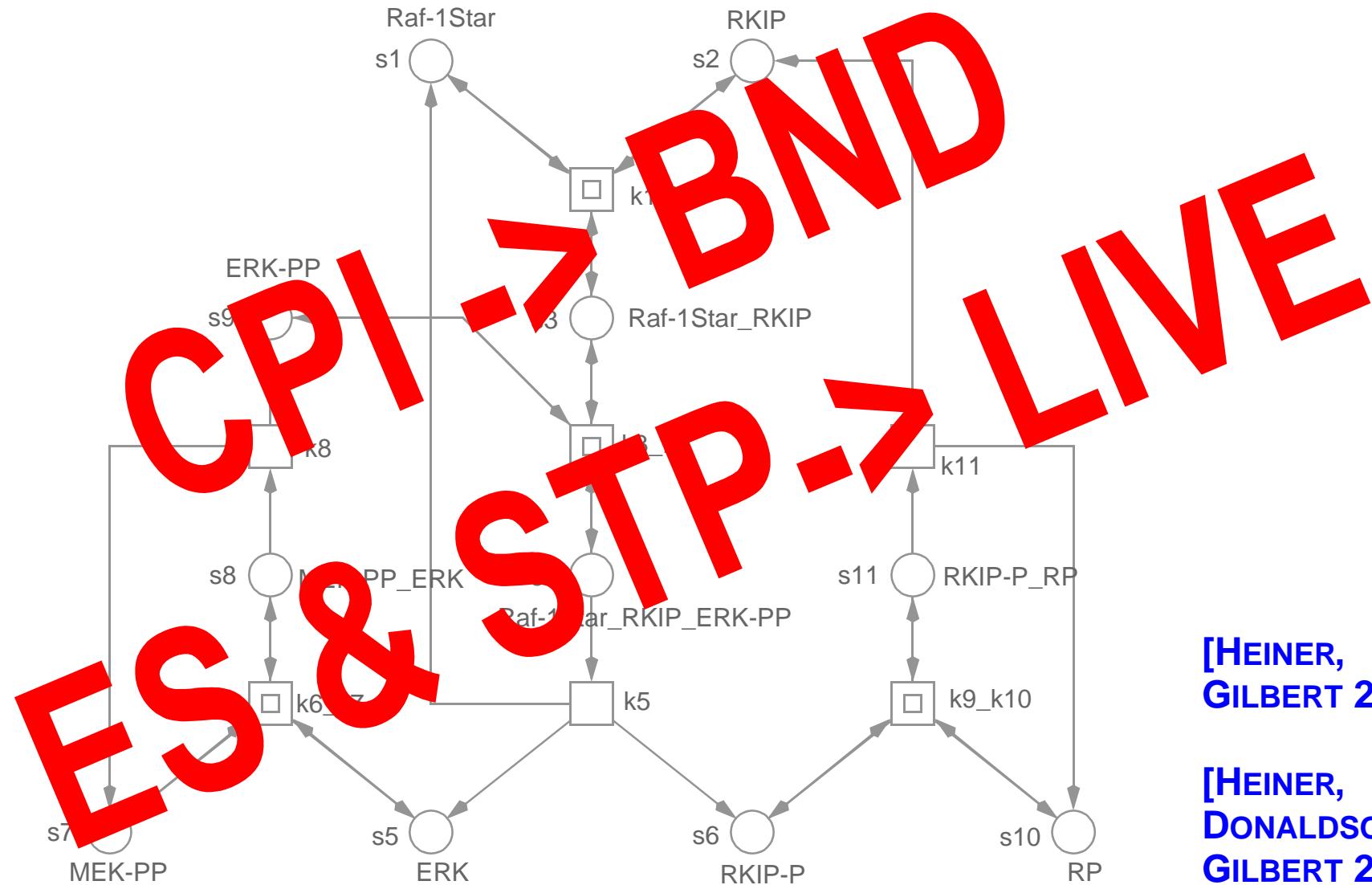
## Ex3 - RKIP SIGNALLING PATHWAY, HIERARCHICAL PETRI NET

PN & BioModel Engineering



[HEINER,  
GILBERT 2006]

[HEINER,  
DONALDSON,  
GILBERT 2010]

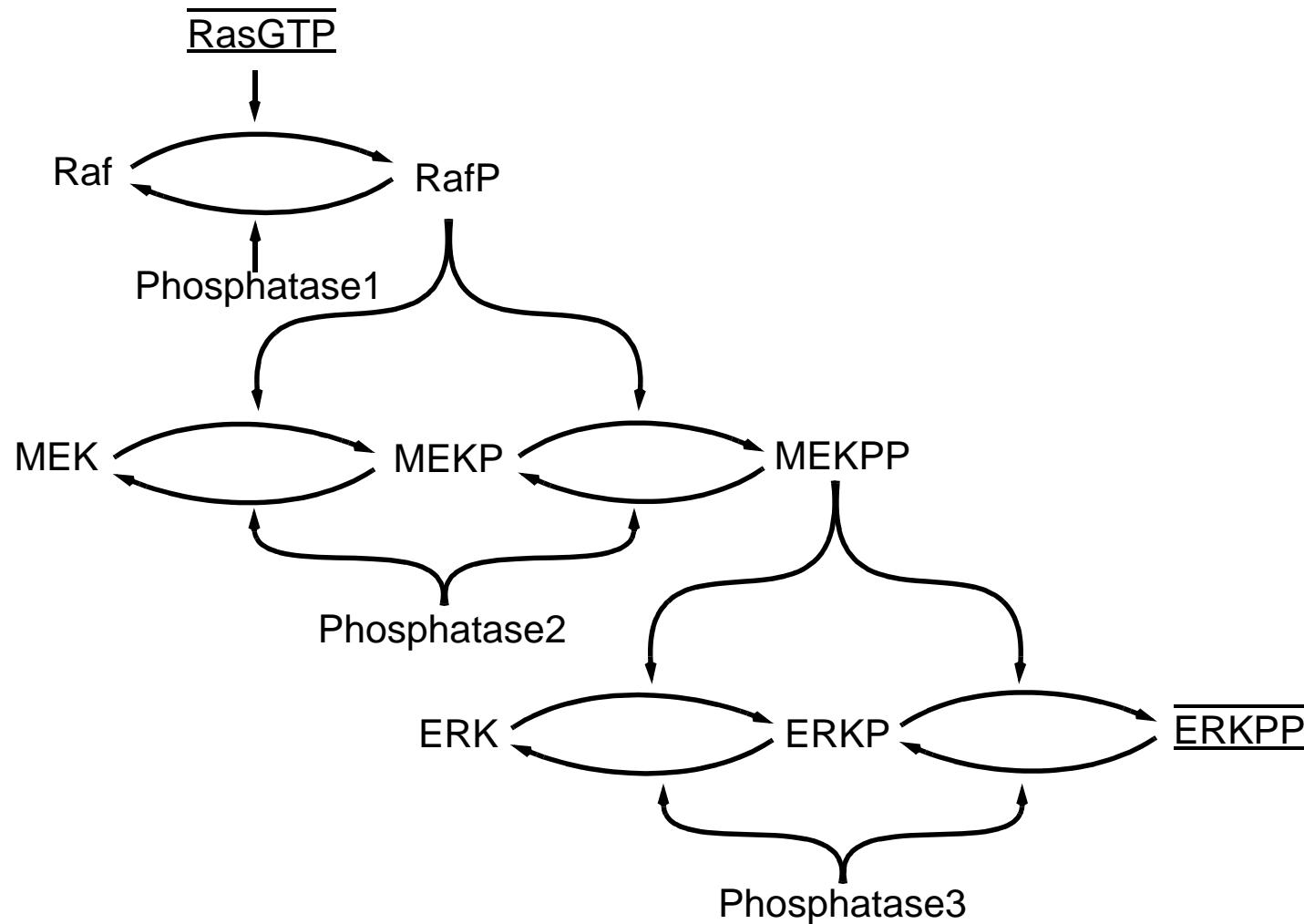


[HEINER,  
GILBERT 2006]

[HEINER,  
DONALDSON,  
GILBERT 2010]

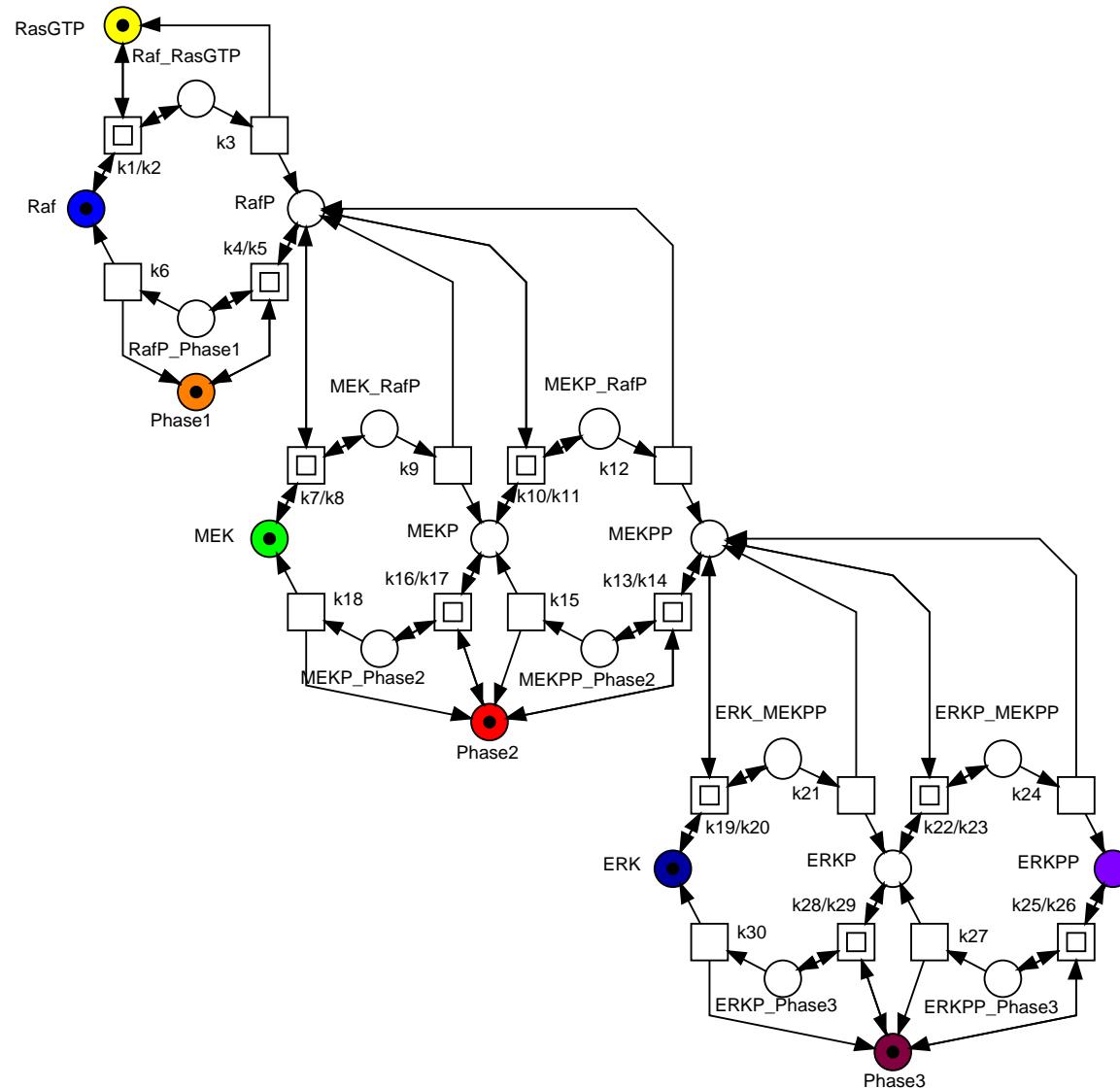
## Ex4 - SIGNALLING CASCADE

PN & BioModel Engineering



## Ex4 - SIGNALLING CASCADE

PN & BioModel Engineering

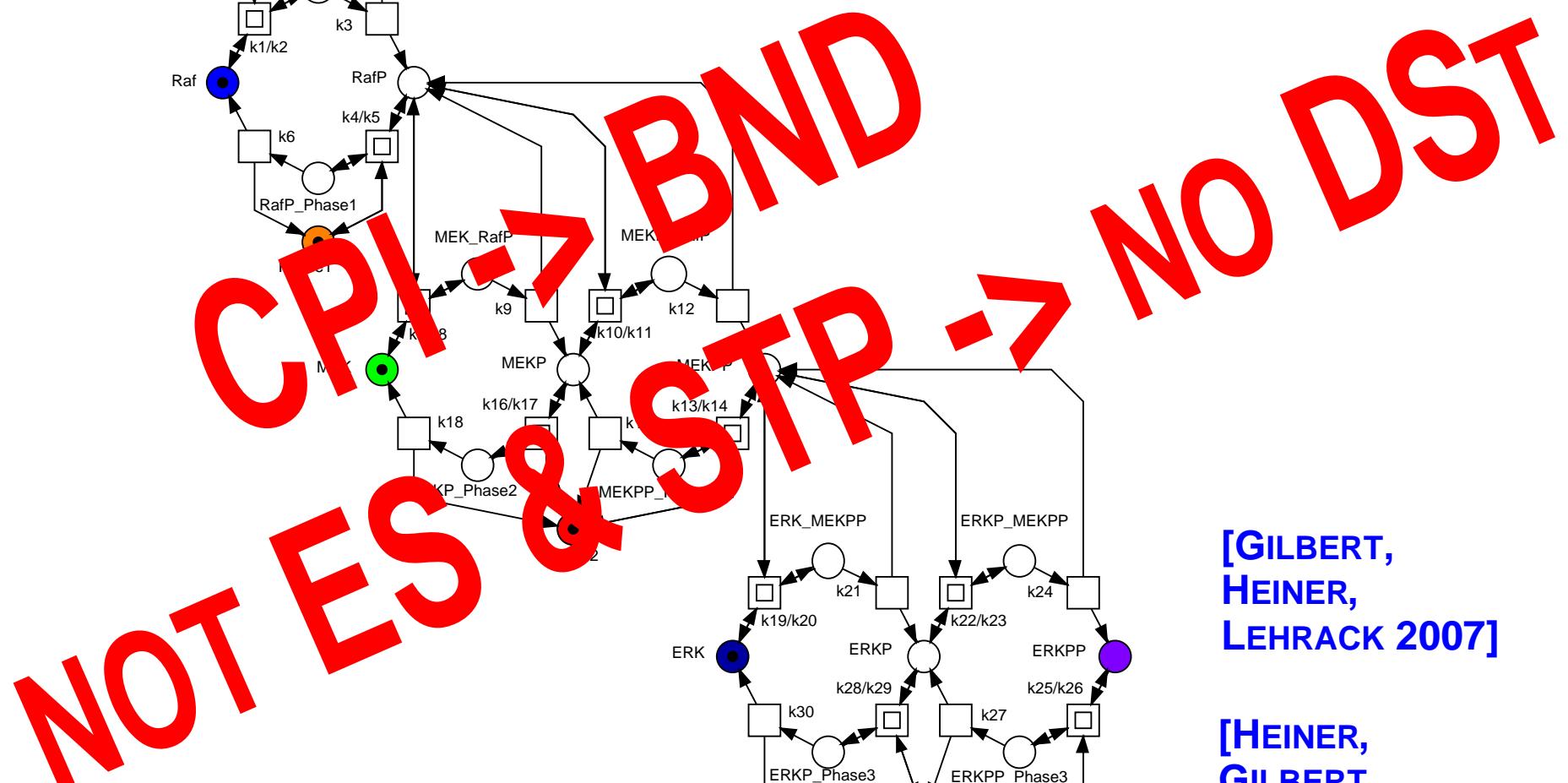


[GILBERT,  
HEINER,  
LEHRACK 2007]

[HEINER,  
GILBERT,  
DONALDSON 2008]

## Ex4 - SIGNALLING CASCADE

PN & BioModel Engineering

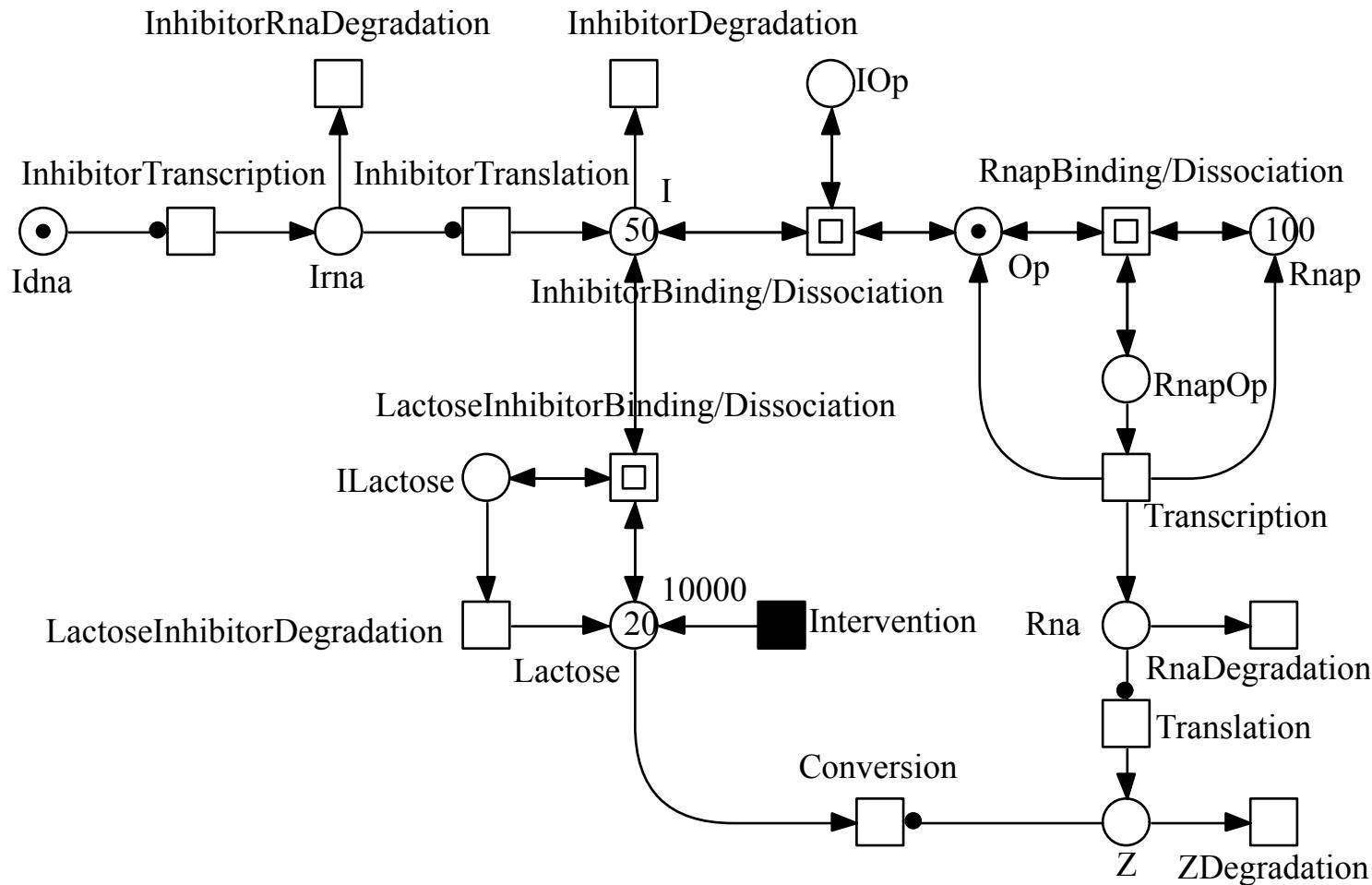


[GILBERT,  
HEINER,  
LEHRACK 2007]

[HEINER,  
GILBERT,  
DONALDSON 2008]

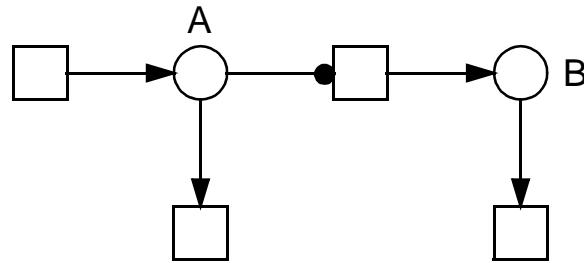
## Ex5 - LAC OPERON

PN & BioModel Engineering



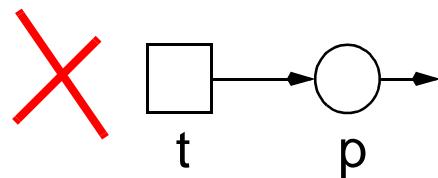
[WILKINSON 2006]

- reduced net structure while preserving liveness & boundedness

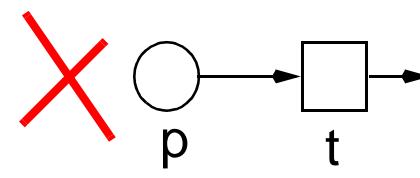


liveness becomes obvious

- example of two simple reduction rules



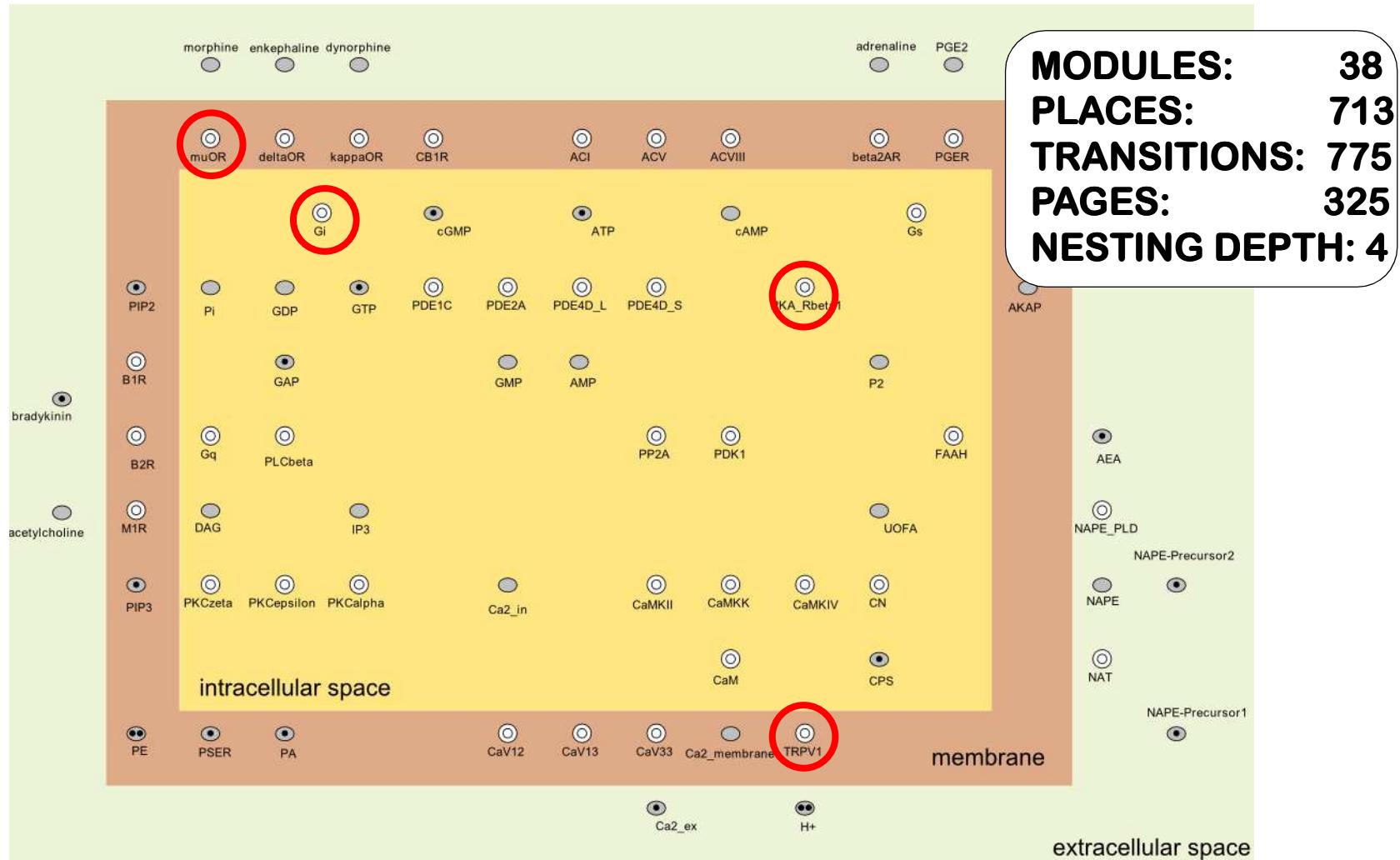
t live  
p unbounded



t not live  
p bounded

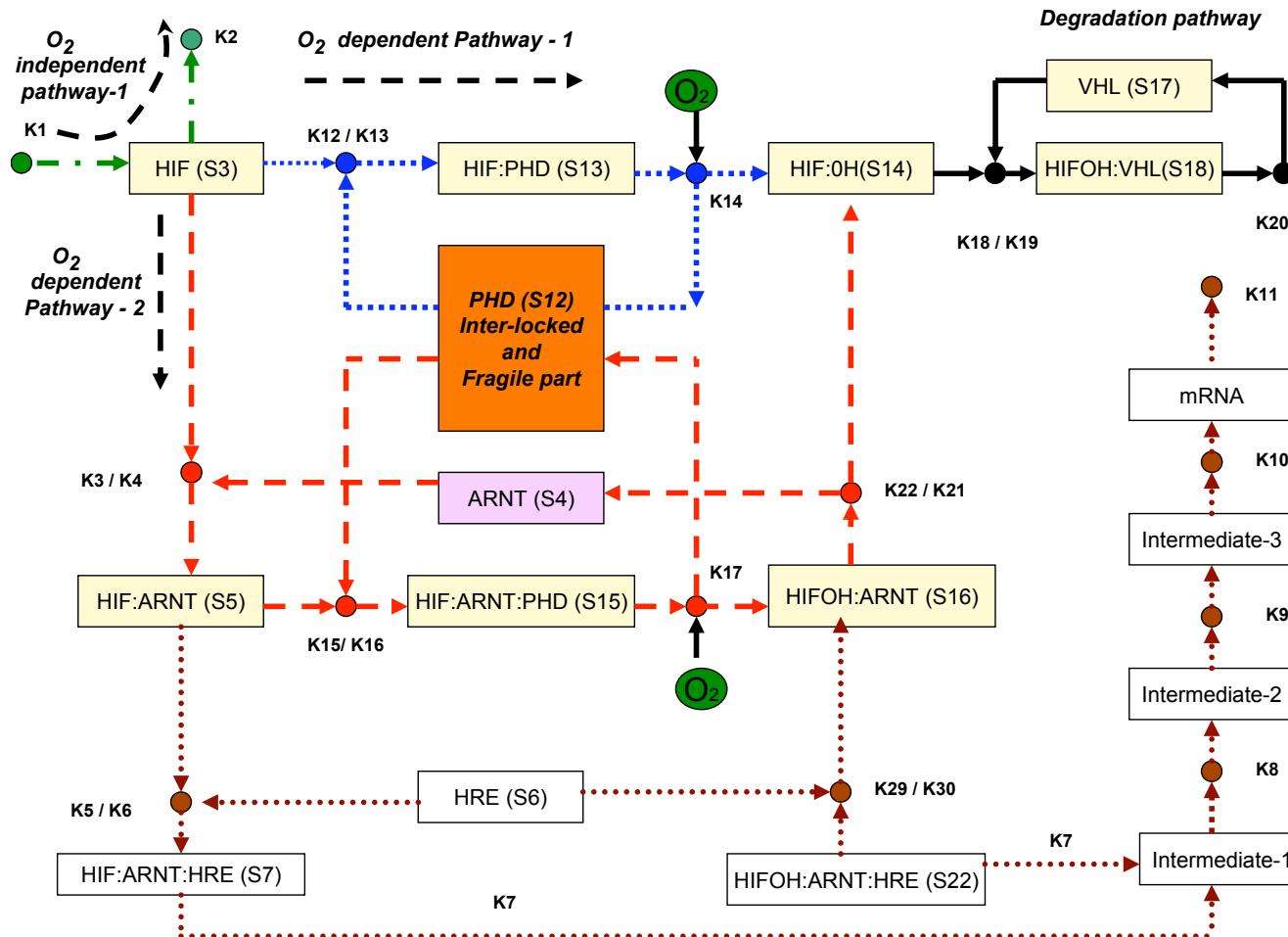
[BLÄTKE, MEYER, MARWAN 2011]

-> A PROTEIN-ORIENTED MODULAR MODELLING CONCEPT

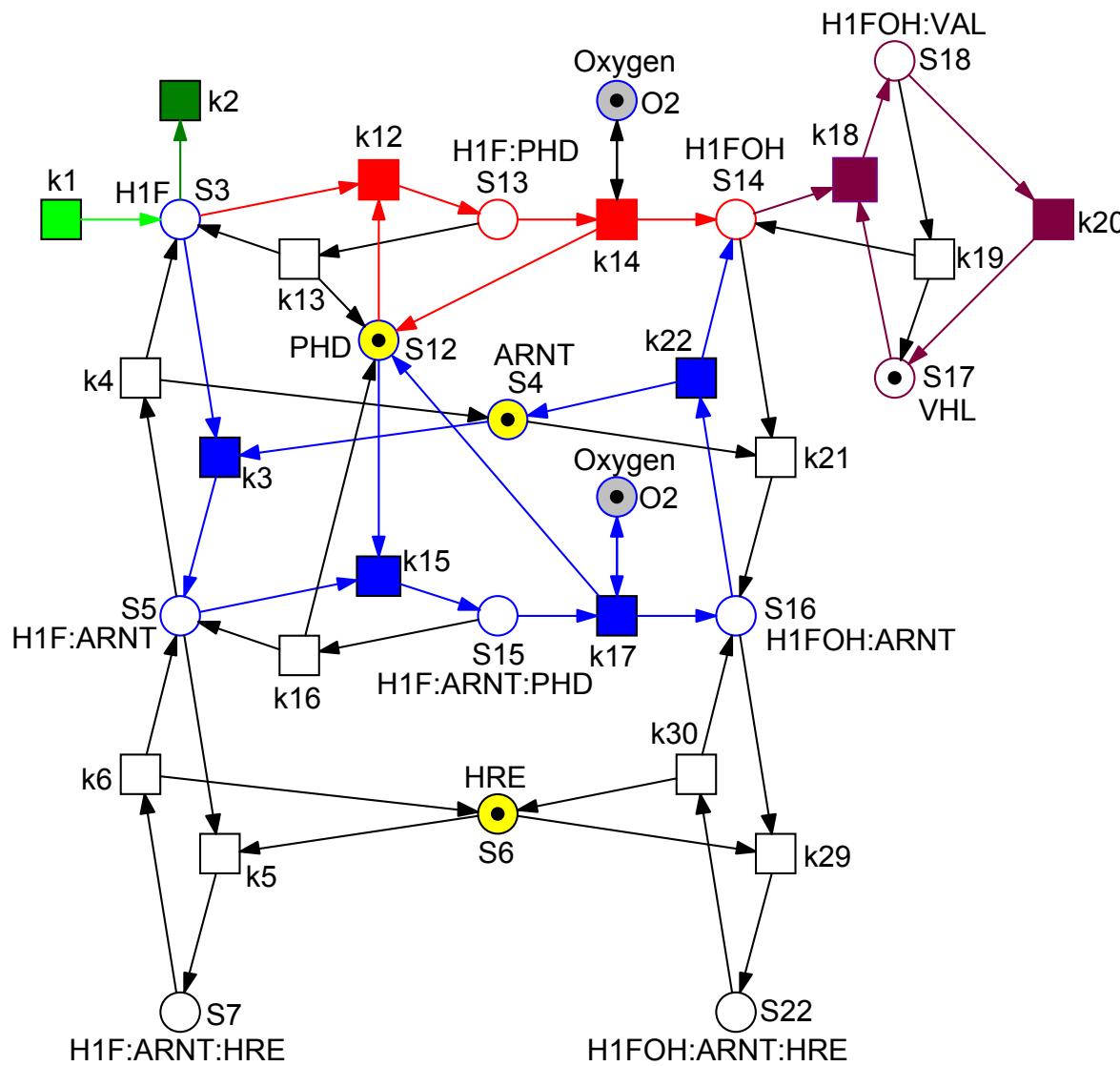


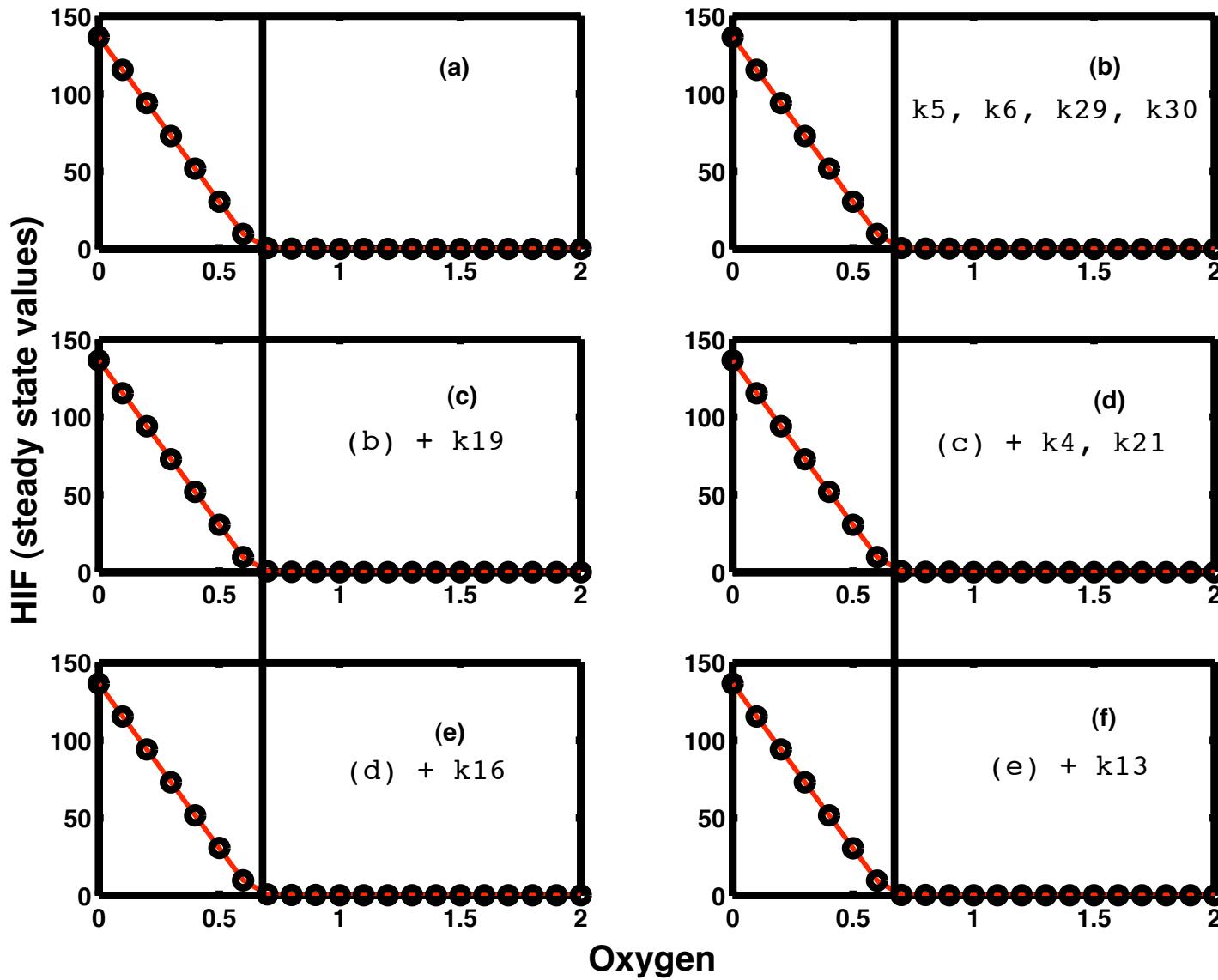
# **ABOUT THE RELATION QUALITATIVE VS CONTINUOUS**

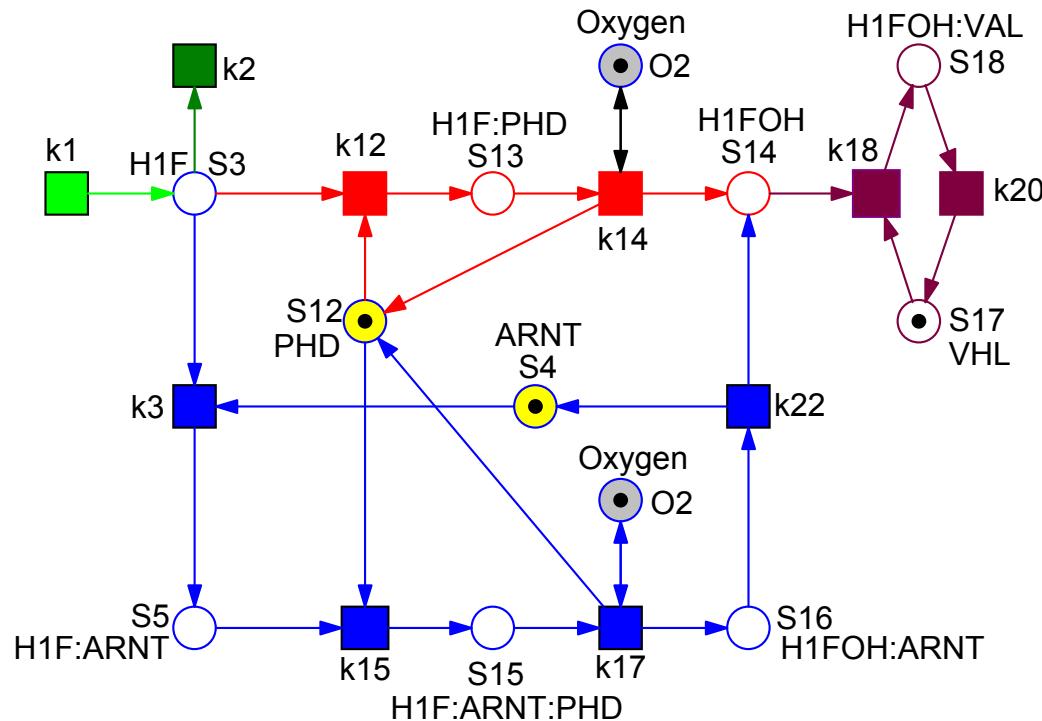
[YU ET AL. 2007]

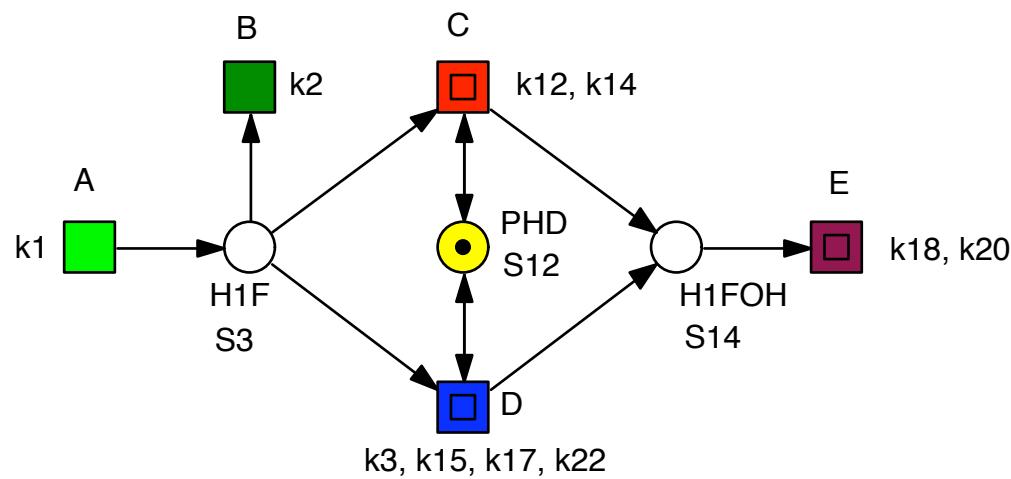


[HEINER,  
SRIRAM 2010]



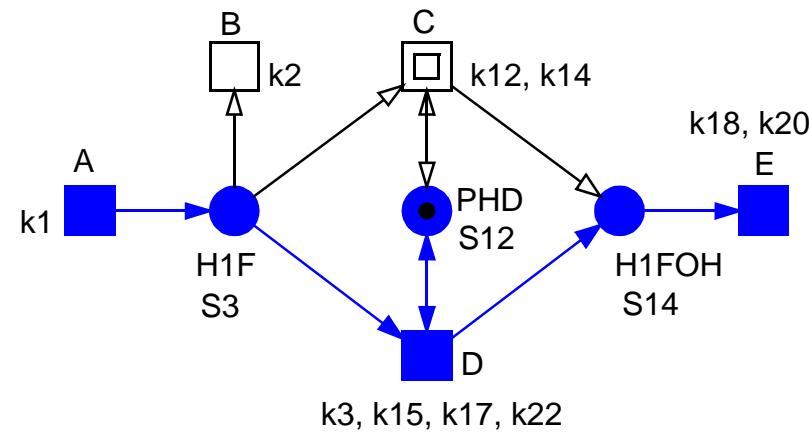
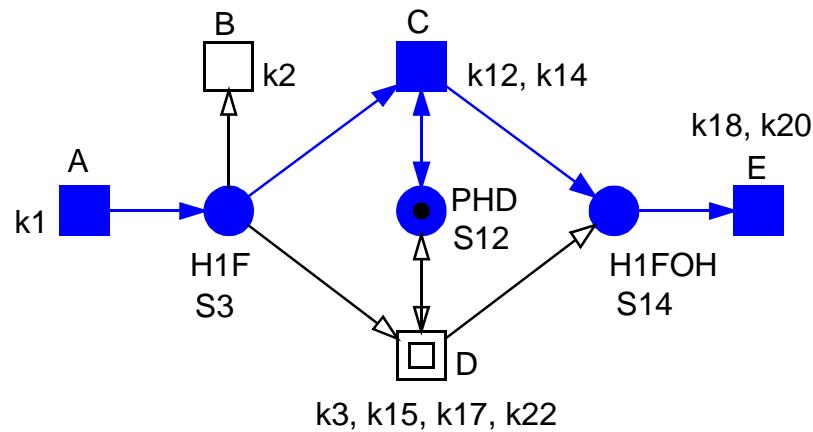
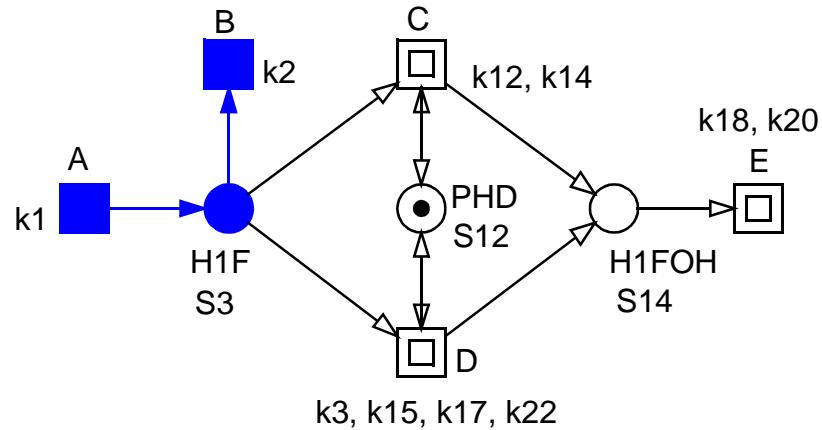






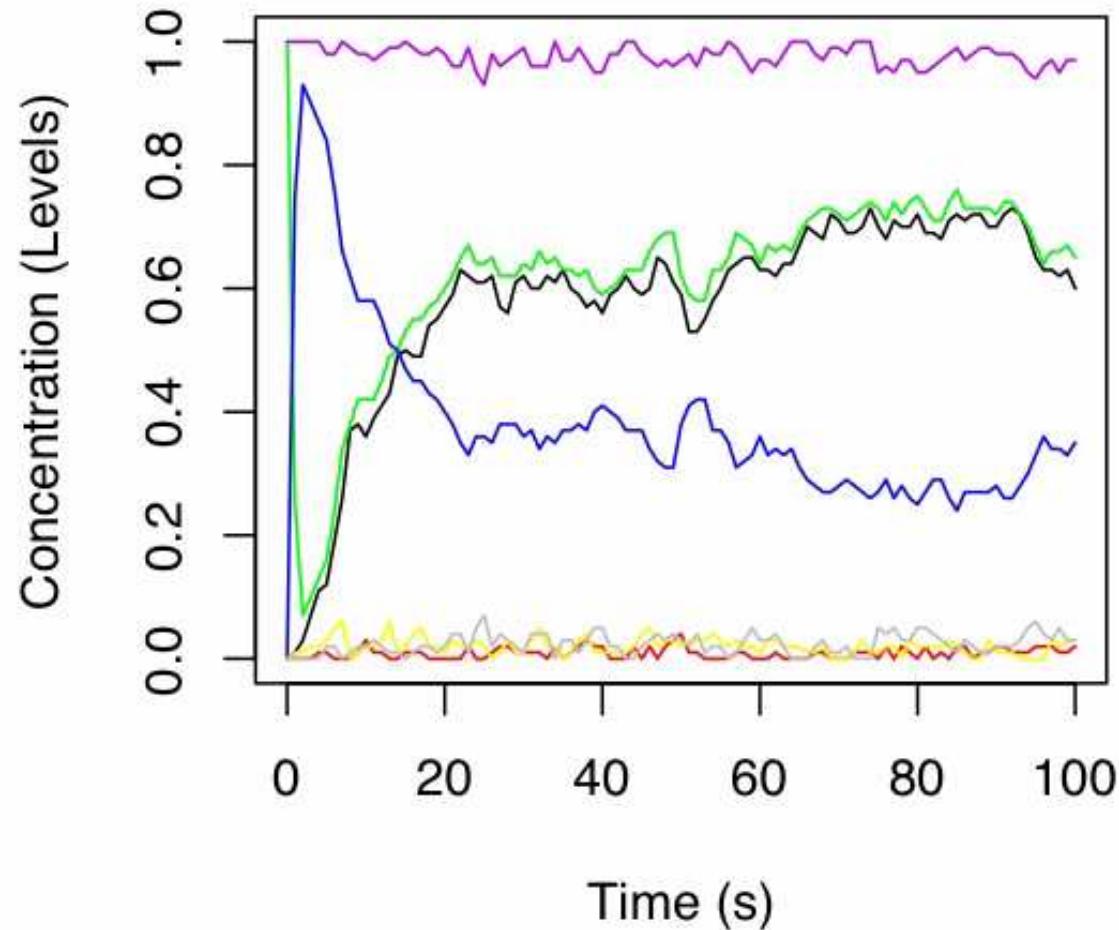
## Ex7 - HYPOXIA

PN & BioModel Engineering

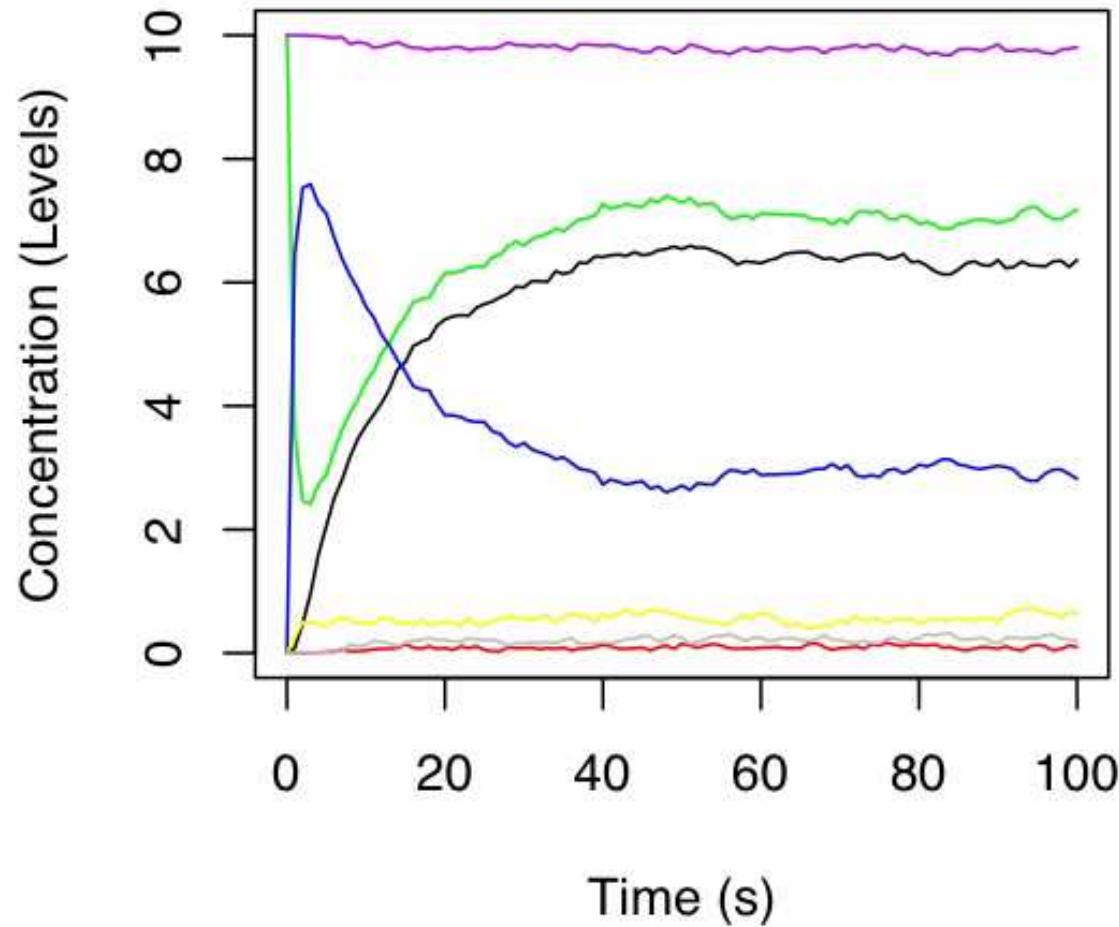


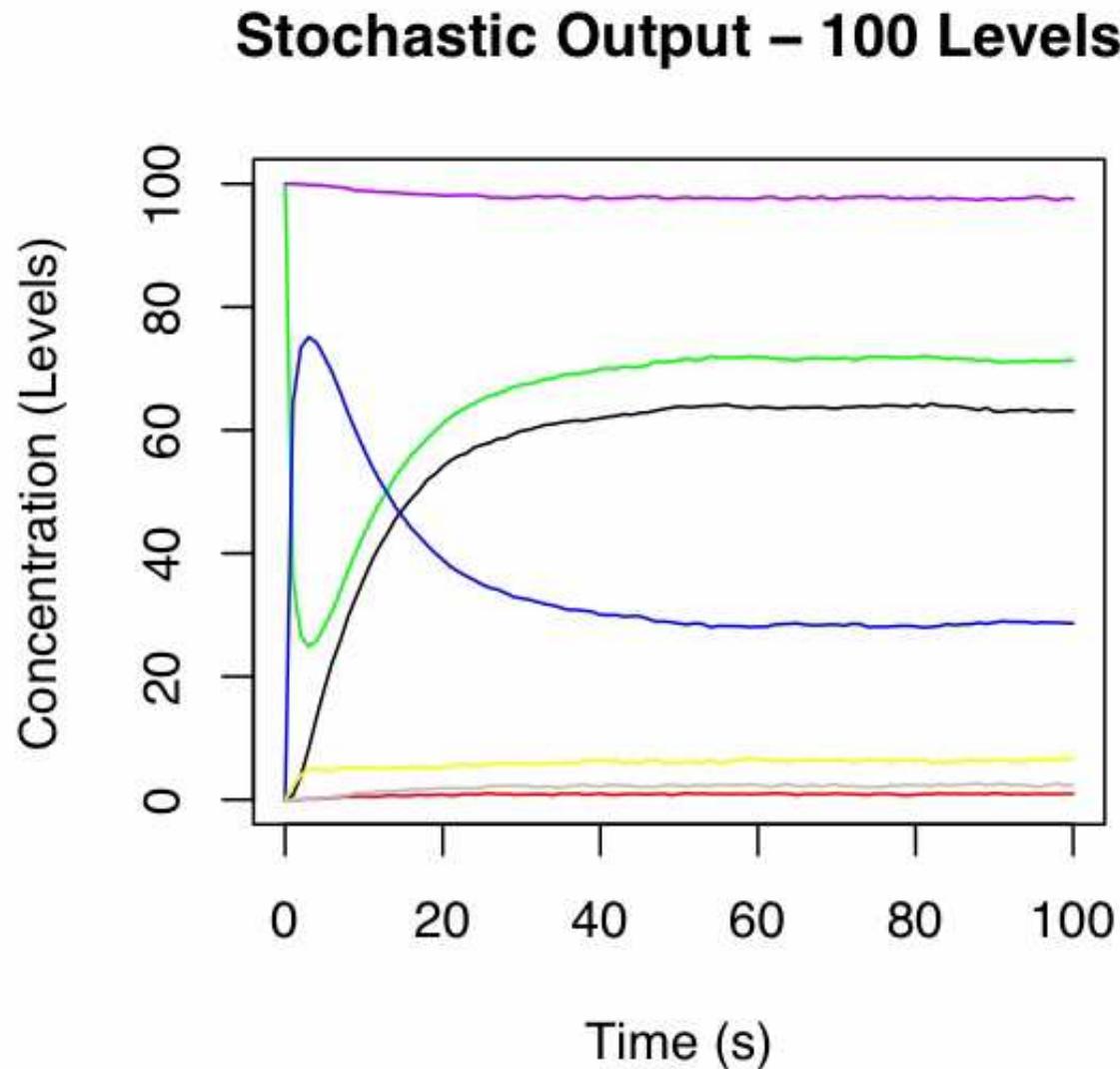
# **ABOUT THE RELATION STOCHASTIC VS CONTINUOUS**

## Stochastic Output – 1 Level

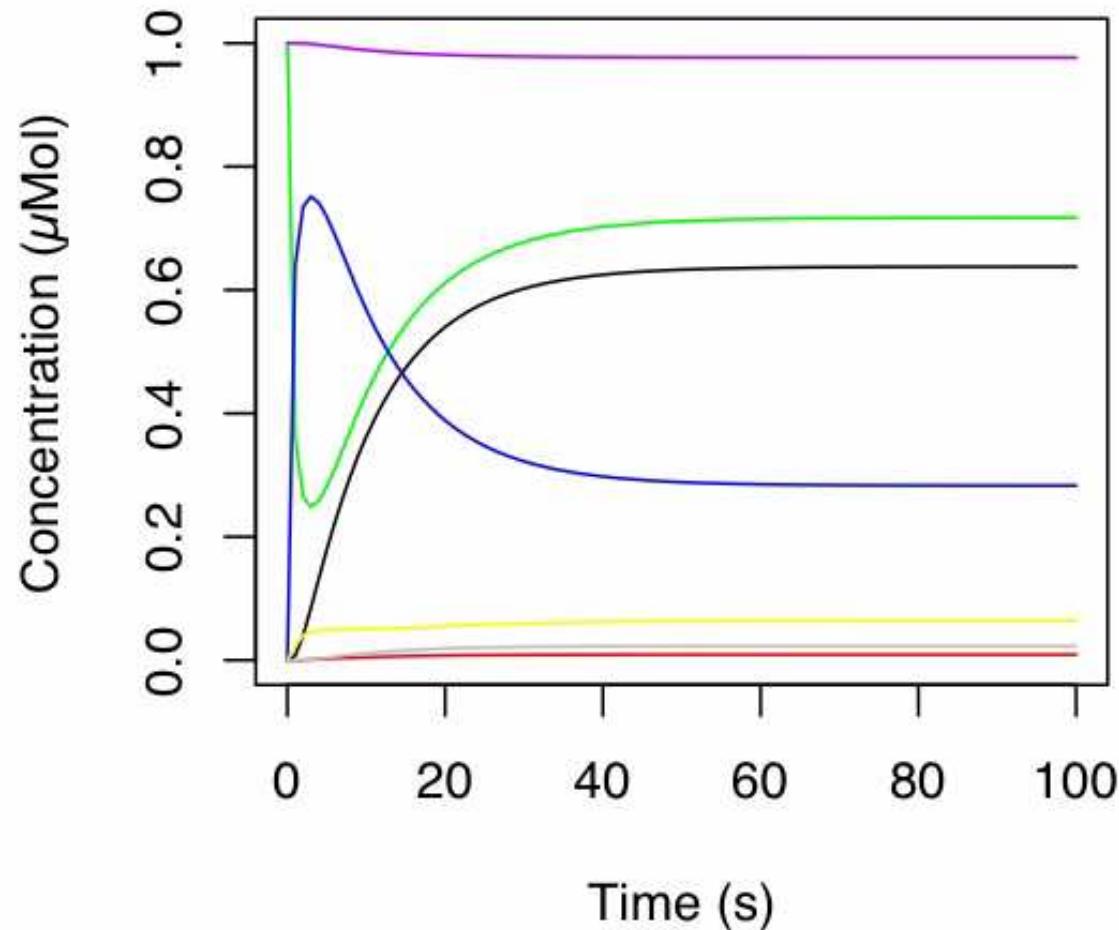


## Stochastic Output – 10 Levels



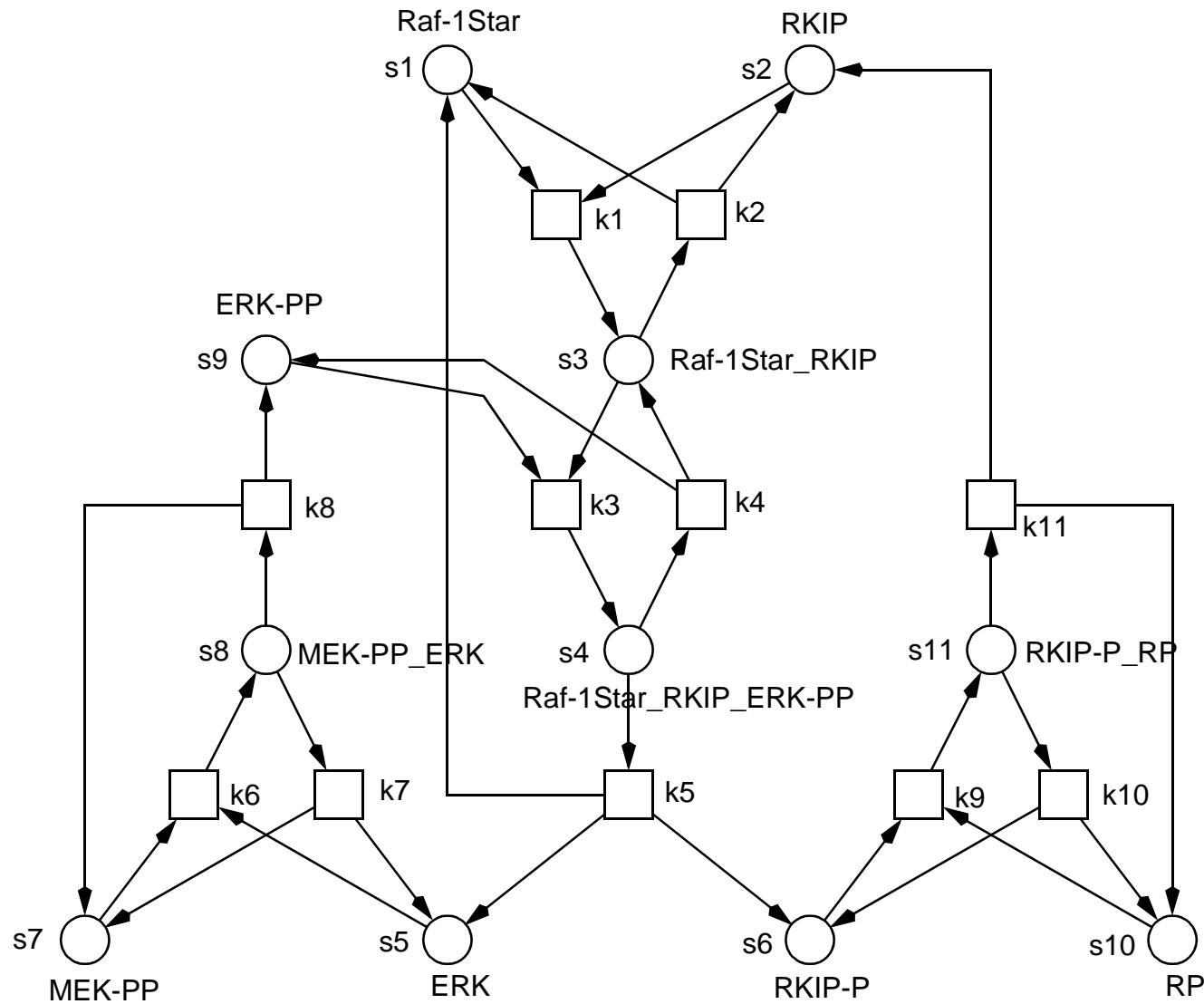


### Deterministic Output



## Ex3 - RKIP SIGNALLING PATHWAY, PETRI NET

PN & BioModel Engineering



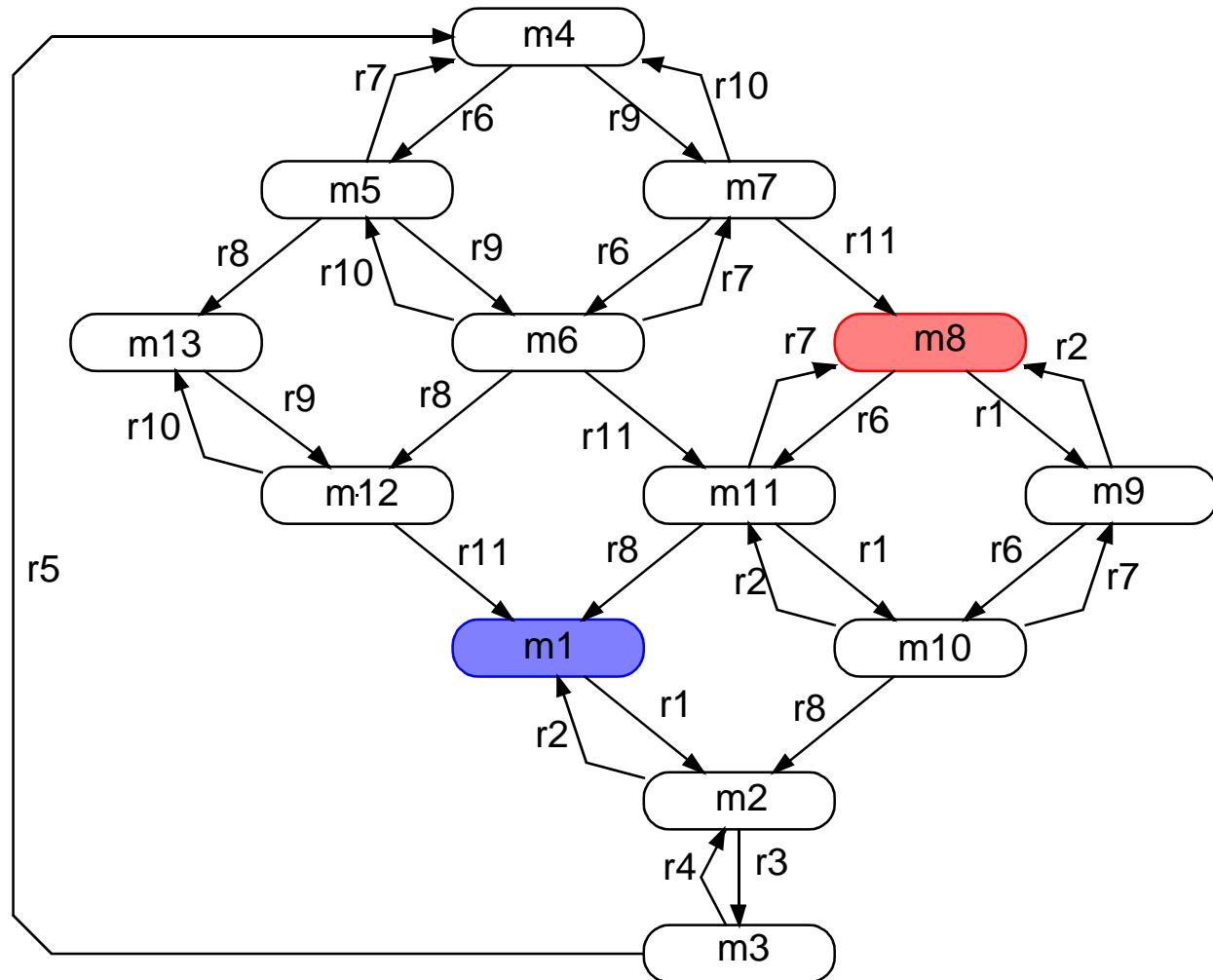
[HEINER,  
GILBERT 2006]

[HEINER,  
DONALDSON,  
GILBERT 2010]

## Ex3 - RKIP, REACHABILITY GRAPH (STS)

PN & BioModel Engineering

- simple algorithm
- nodes : system states
- arcs : the (single) firing transition
- single step firing rule

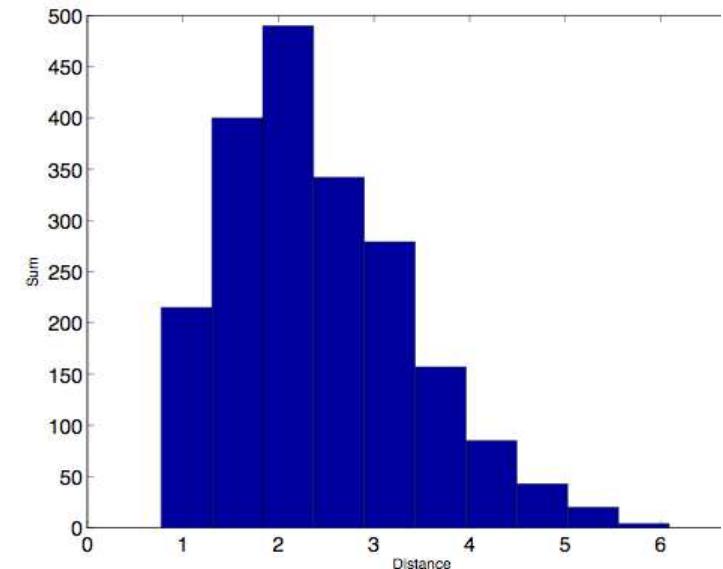


Species	S1	S2	S3	S4	S5	S6	S7	S8	S9	S10	S11	S12	S13
Raf-1*	1	0	0	1	1	1	1	1	0	0	1	1	1
RKIP	1	0	0	0	0	0	0	1	0	0	1	0	0
Raf-1*_RKIP	0	1	0	0	0	0	0	0	1	1	0	0	0
Raf-1*_RKIP_ERK-PP	0	0	1	0	0	0	0	0	0	0	0	0	0
ERK	0	0	0	1	0	0	1	1	1	0	0	0	0
RKIP-P	0	0	0	1	1	0	0	0	0	0	0	0	1
MEK-PP	1	1	1	1	0	0	1	1	1	0	0	1	1
MEK-PP_ERK	0	0	0	0	1	1	0	0	0	1	1	0	0
ERK-PP	1	1	0	0	0	0	0	0	0	0	1	1	
RP	1	1	1	1	1	0	0	1	1	1	1	0	1
RKIP-P_RP	0	0	0	0	0	1	1	0	0	0	0	1	0

Cho et al

Biochemist

*13 good state configurations*

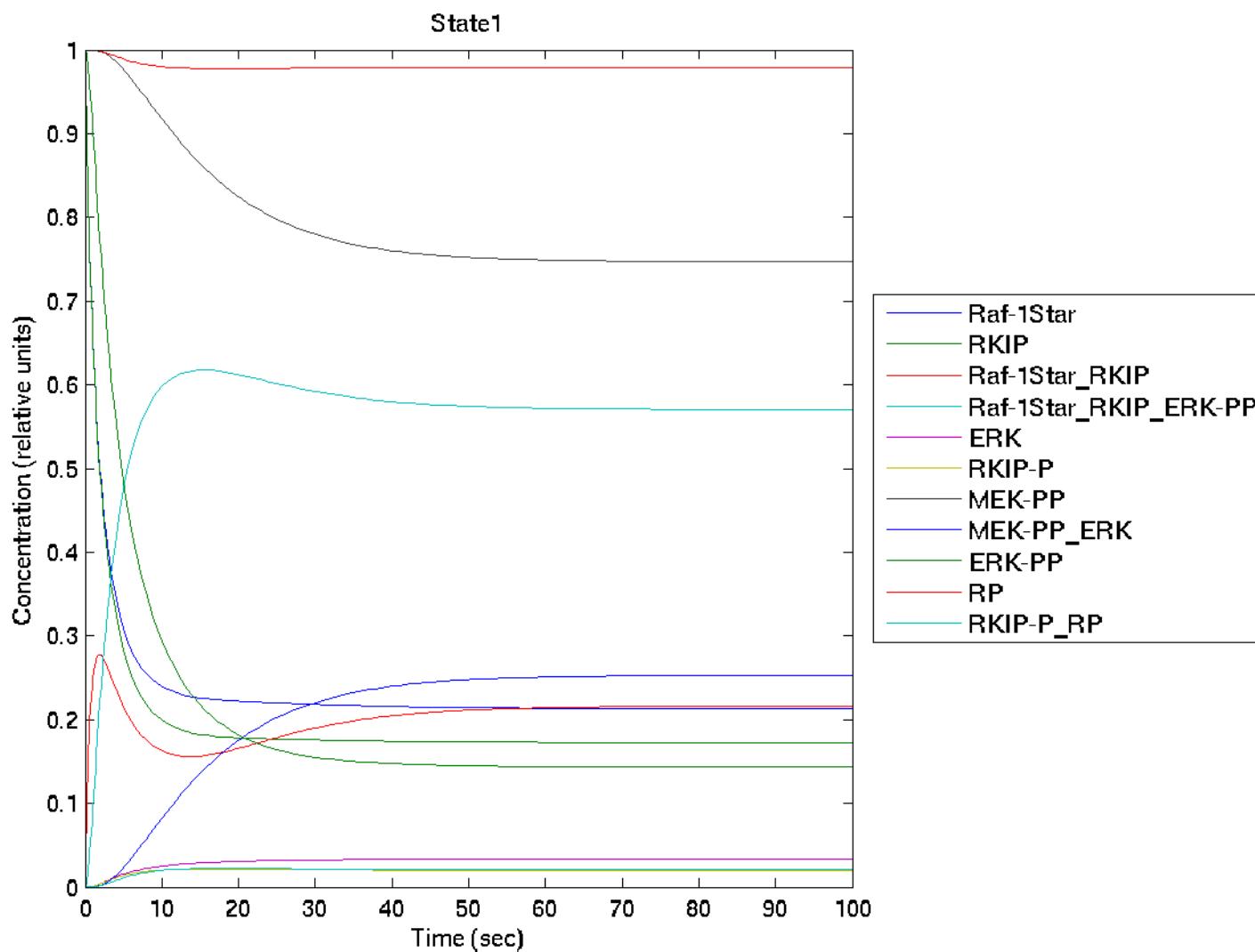


Distribution of 'bad' steady states as euclidean distances from the 'good' final steady state

*the bad ones*

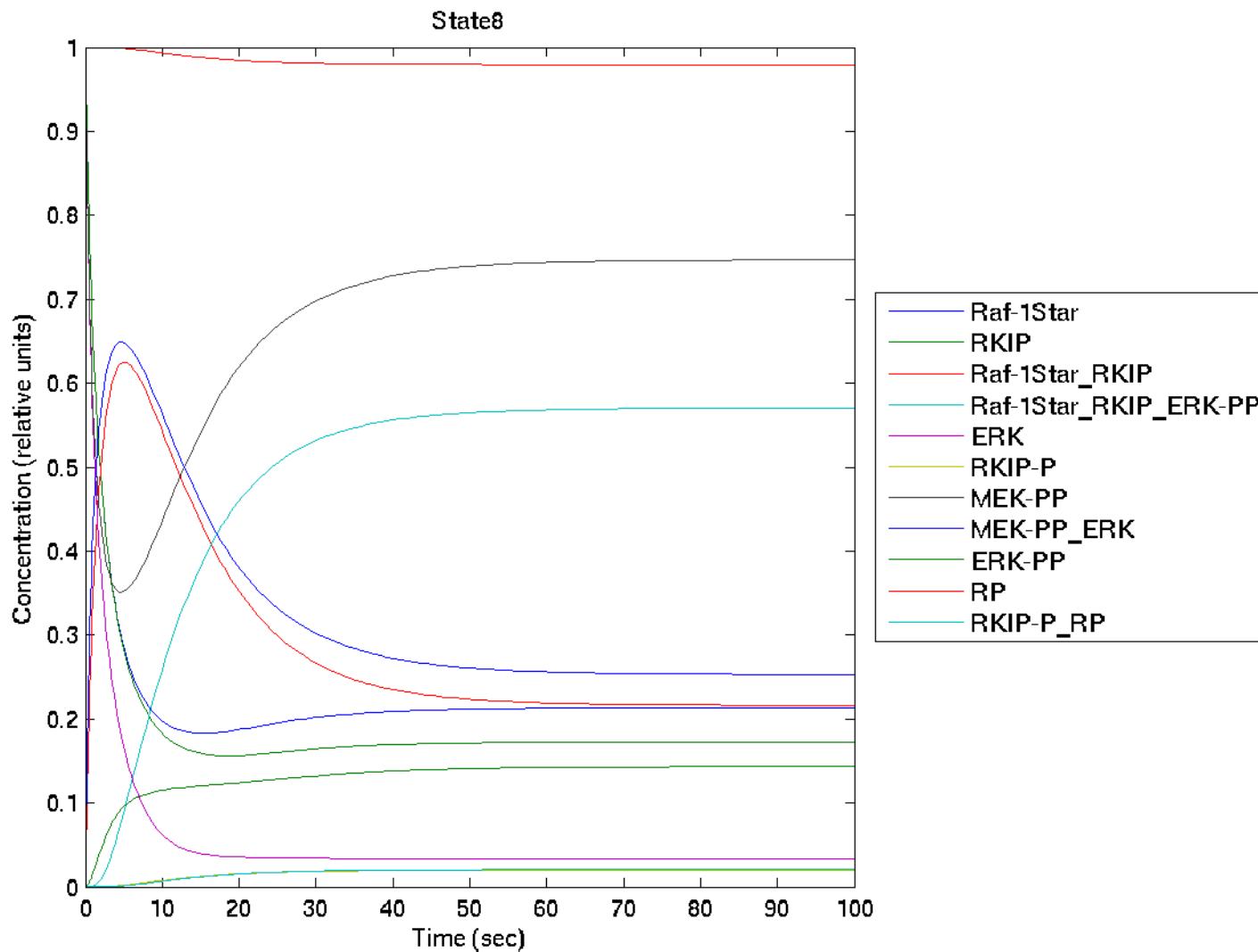
## Ex3 - RKIP, QUANTITATIVE ANALYSIS

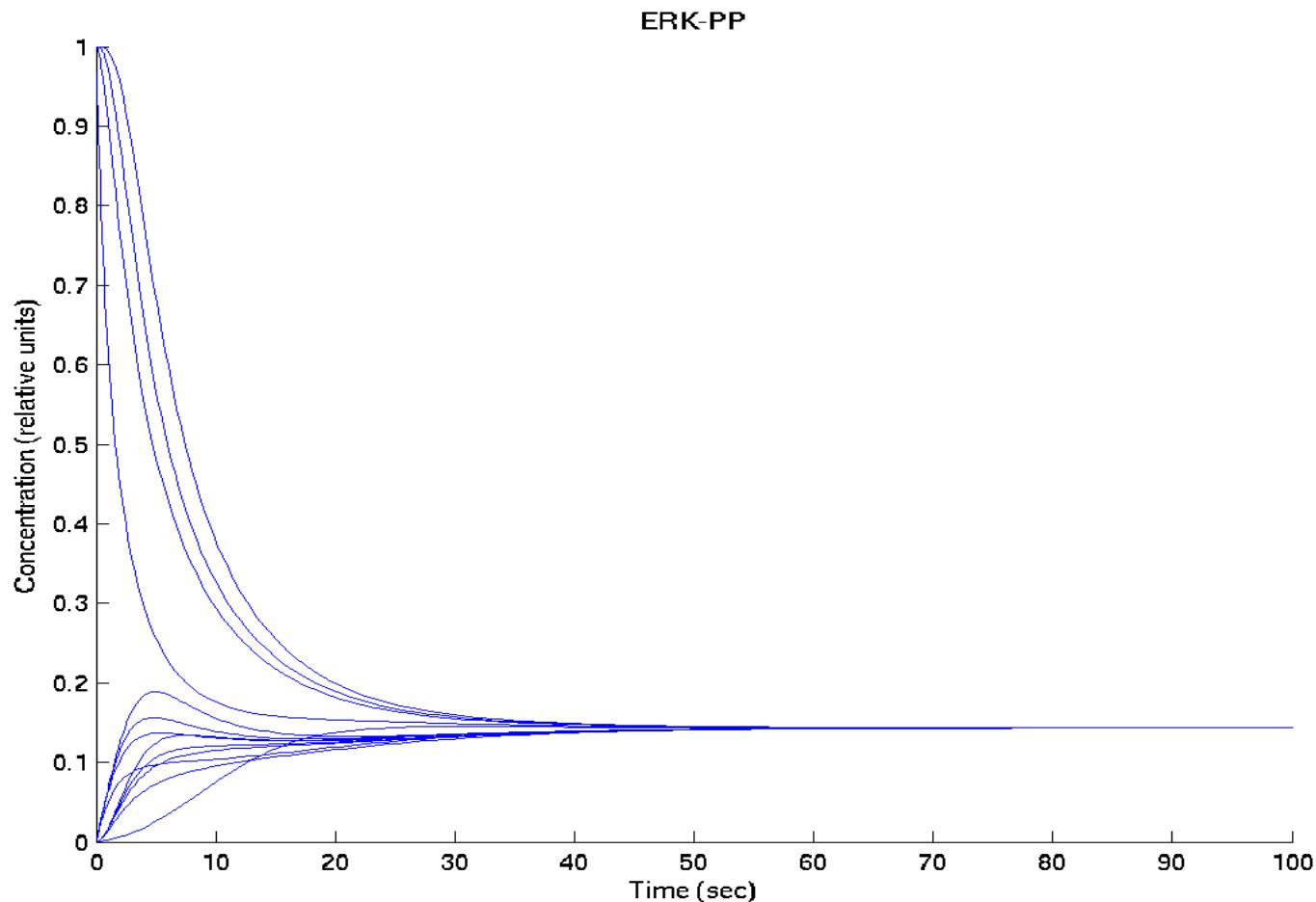
PN & BioModel Engineering



## Ex3 - RKIP, QUANTITATIVE ANALYSIS

PN & BioModel Engineering





**BUT,**

**TRANSITION SPN -> CPN  
MAY COME WITH  
COUNTERINTUITIVE EFFECTS.**

- ACR: steady state value of variable (place) does not depend on total mass, only on kinetic constants      -> [SHINAR, FEINBERG 2010]

- simple example      mass-action kinetics



$$v_1(r_1) = k_1 AB$$



$$v_2(r_2) = k_2 B$$

- ODEs

$$dA/dt = v_2 - v_1 = k_2 B - k_1 AB$$

$$dB/dt = v_1 - v_2 = k_1 AB - k_2 B$$

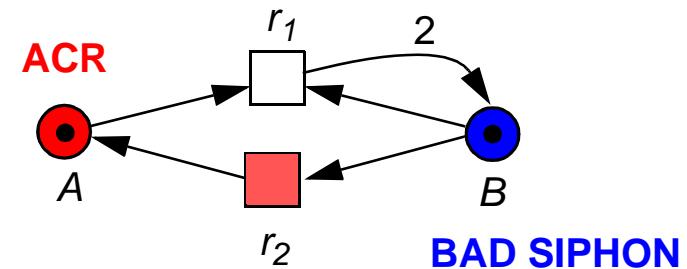
- steady state

$$dA/dt = k_2 B - k_1 AB = 0$$

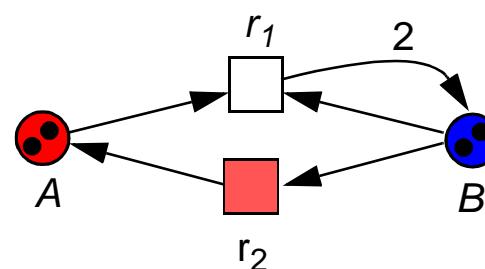
$$dB/dt = k_1 AB - k_2 B = 0$$

-> *steady\_state(A) =  $k_2/k_1$*

*steady\_state(B) = total -  $k_2/k_1$*



CPI:  $m_0(A) + m_0(B) = \text{total}$

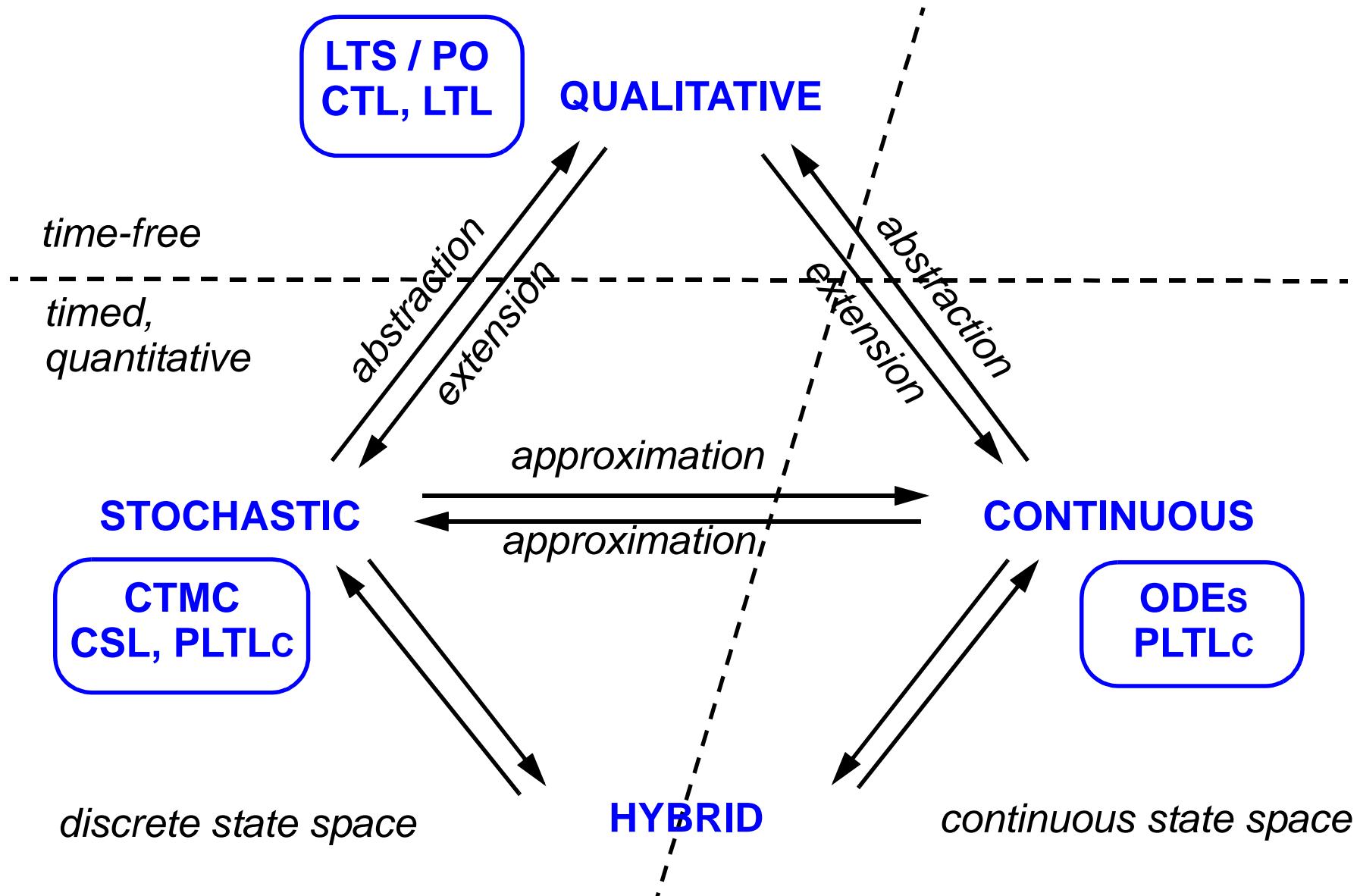


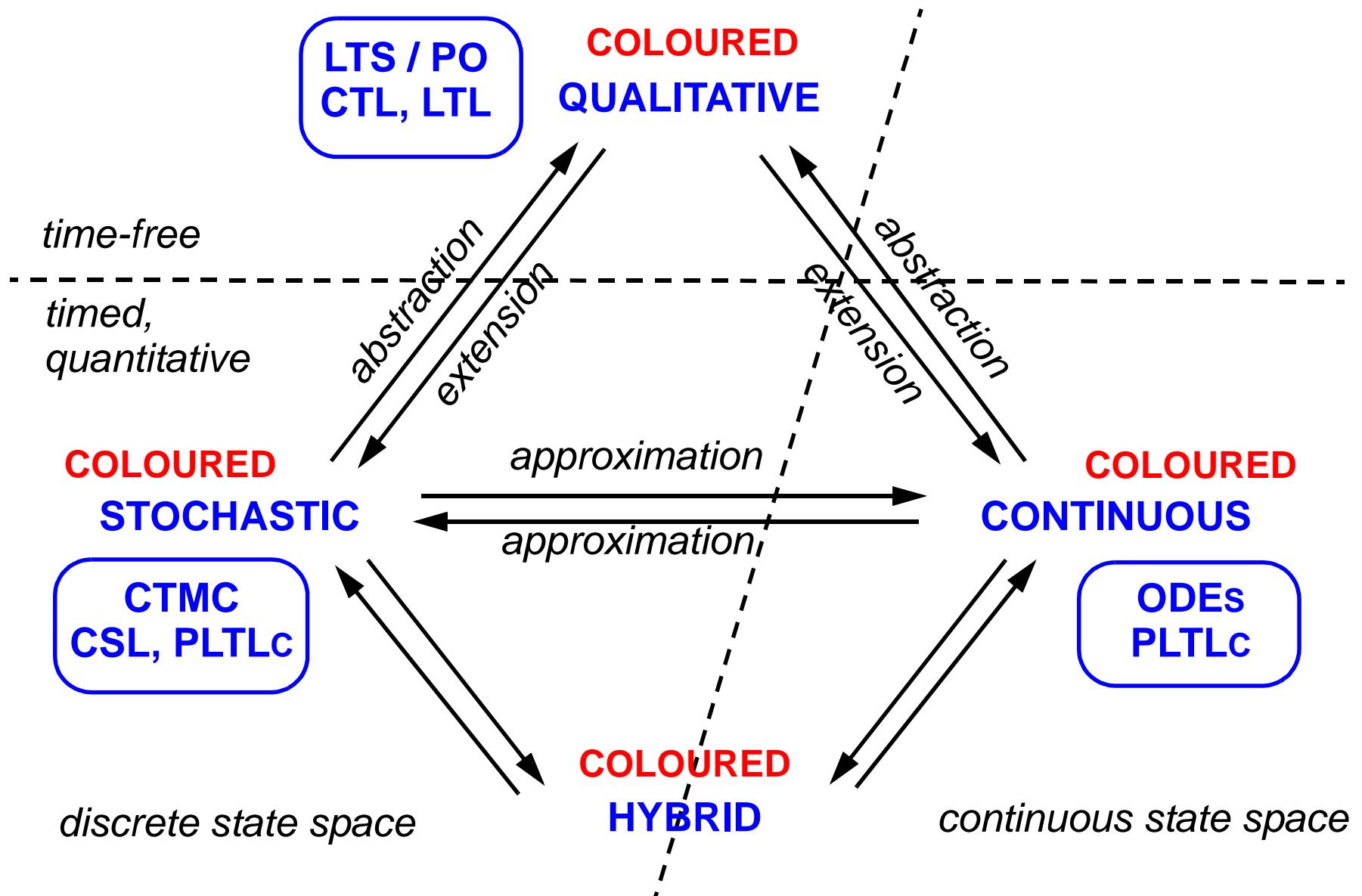
# .... AND THEN THERE WAS COLOUR

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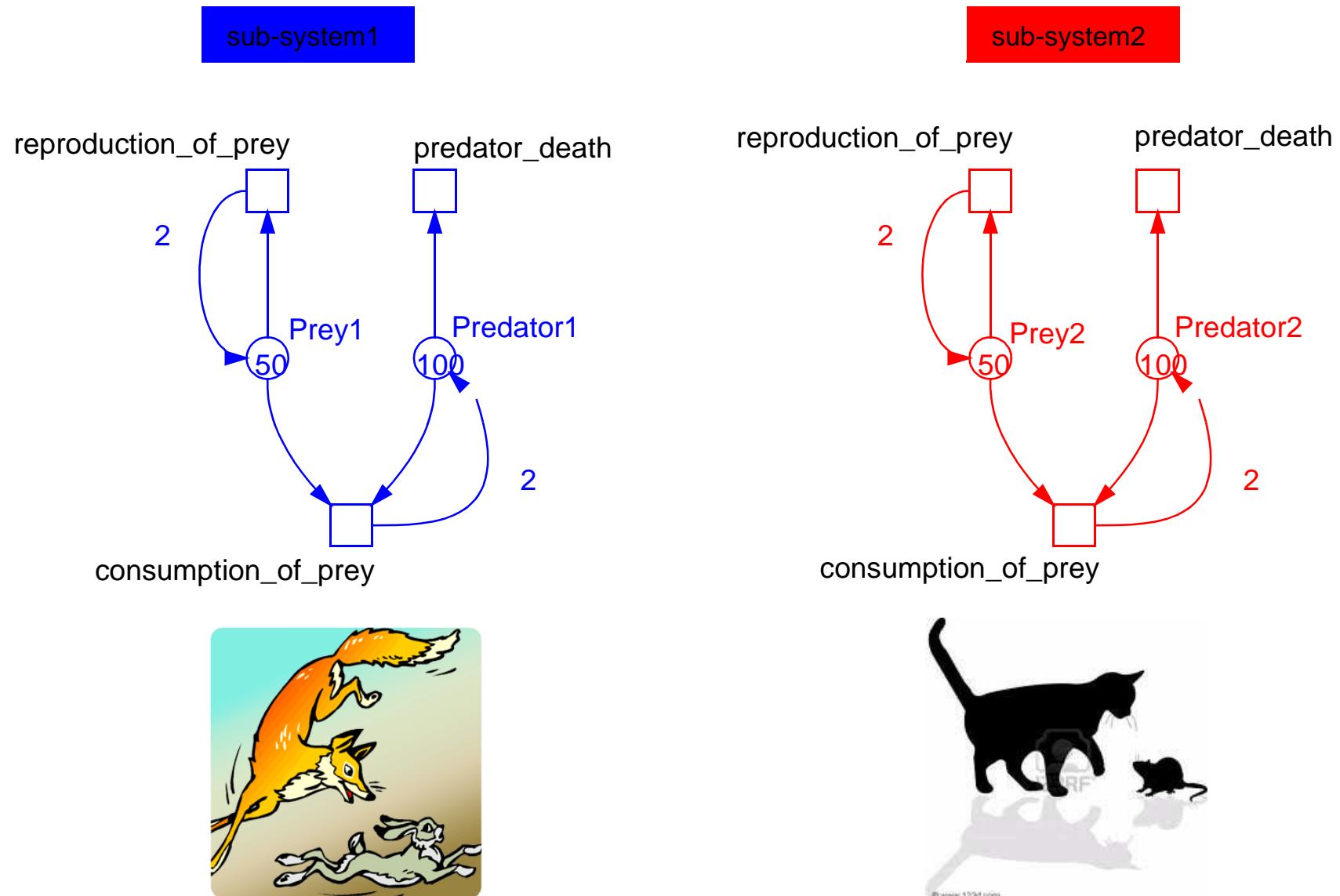
Kew Gardens, 24/04/2011





# **COLOUR - WHAT FOR ?**

## Ex1: PREY - PREDATOR



## Ex1: PREY - PREDATOR

PN & BioModel Engineering

### □ definitions

```
colourset CS = 1-2;
```

```
var x : CS;
```

### □ better:

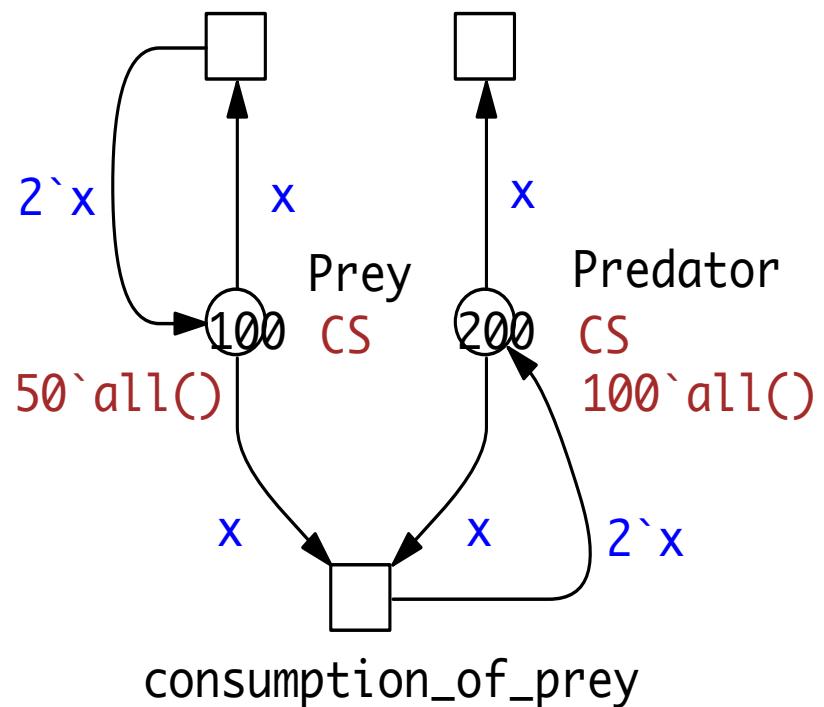
```
const SIZE = 2;
```

```
colourset CS = 1-SIZE;
```

```
var x : CS;
```



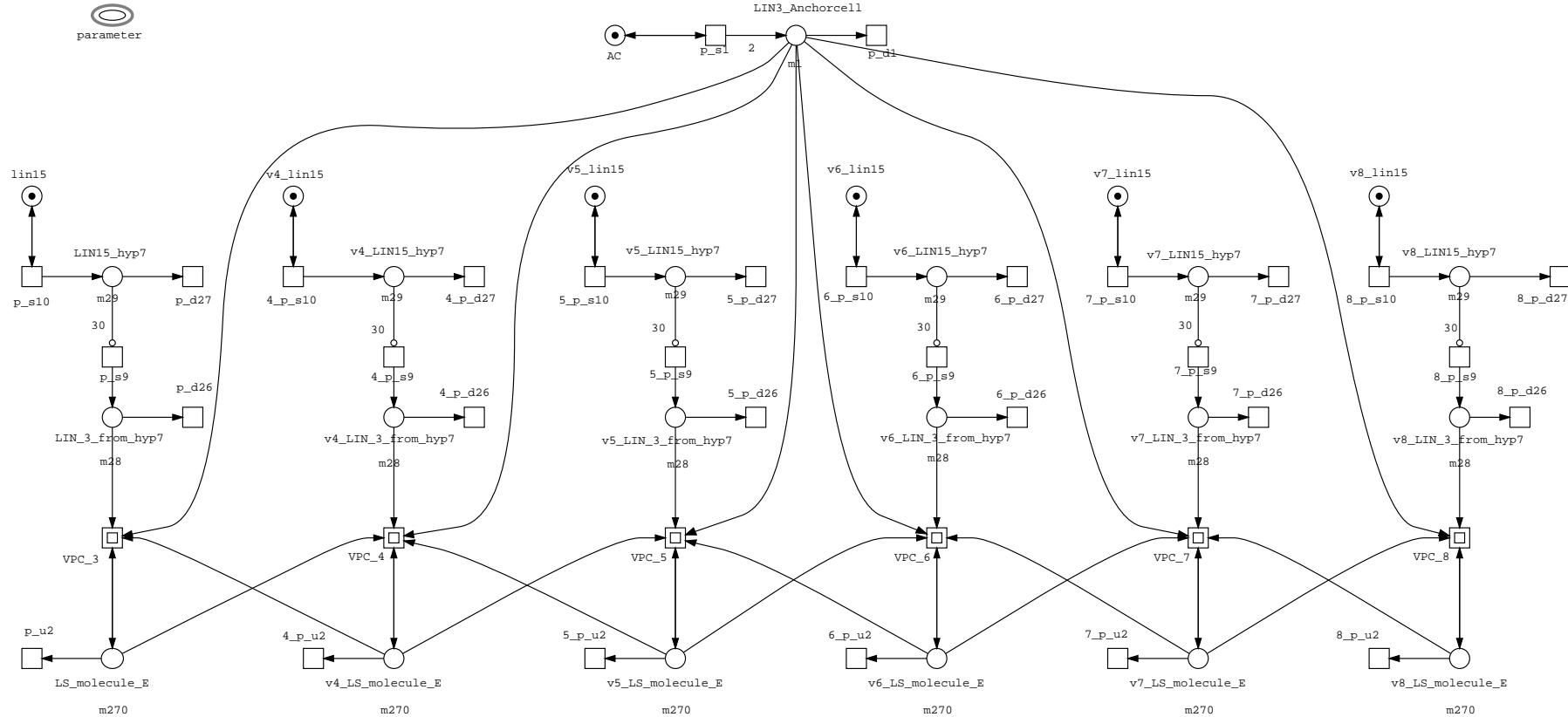
reproduction\_of\_prey predator\_death



### □ changing SIZE adapts the model to various scenarios

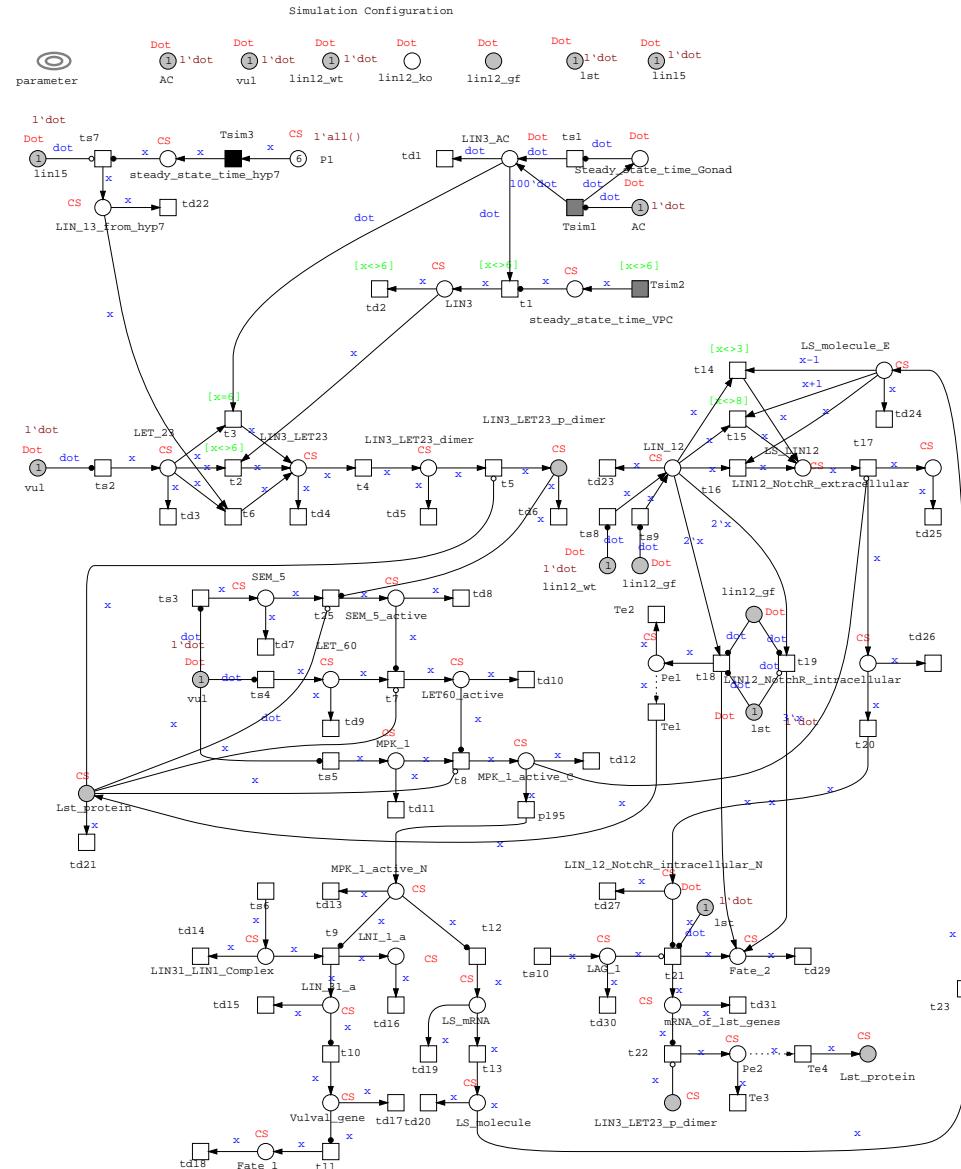
[LI ET AL. 2009]  
 [BONZANNI ET AL. 2009]

**PLACES:** 206  
**TRANSITIONS:** 366



## Ex2: C. ELEGANS, COLOURED

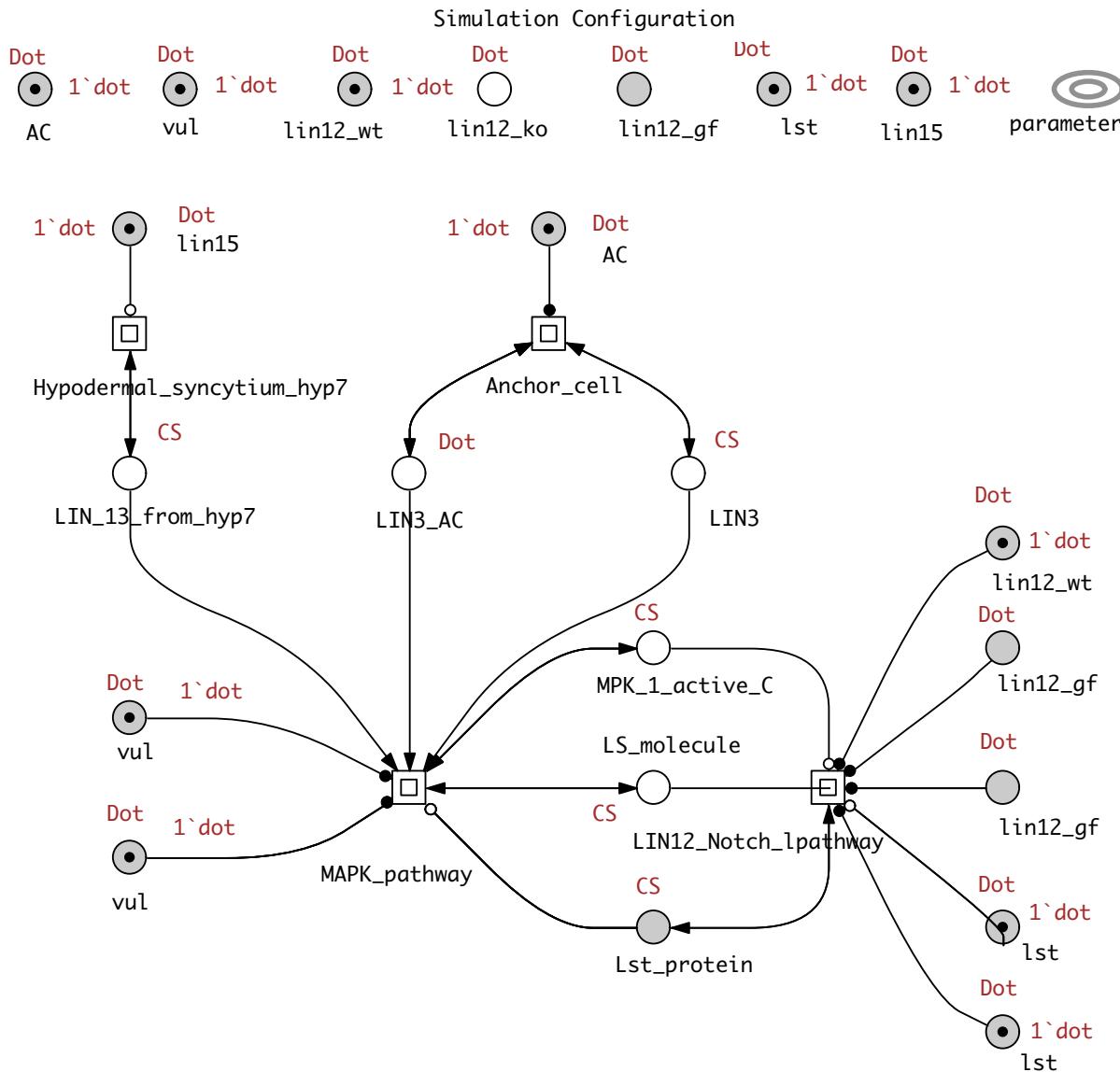
PN & BioModel Engineering



**PLACES:** 44  
**TRANSITIONS:** 72

## Ex2: C. ELEGANS, COLOURED & HIERARCHIES

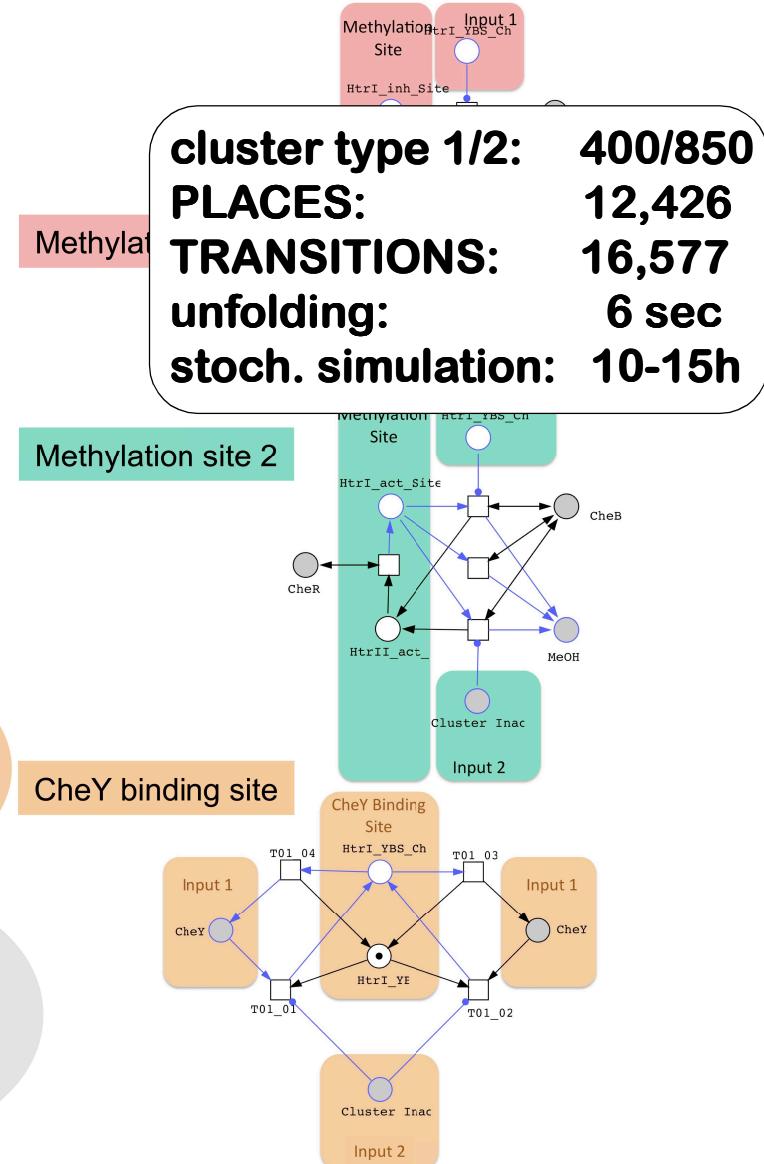
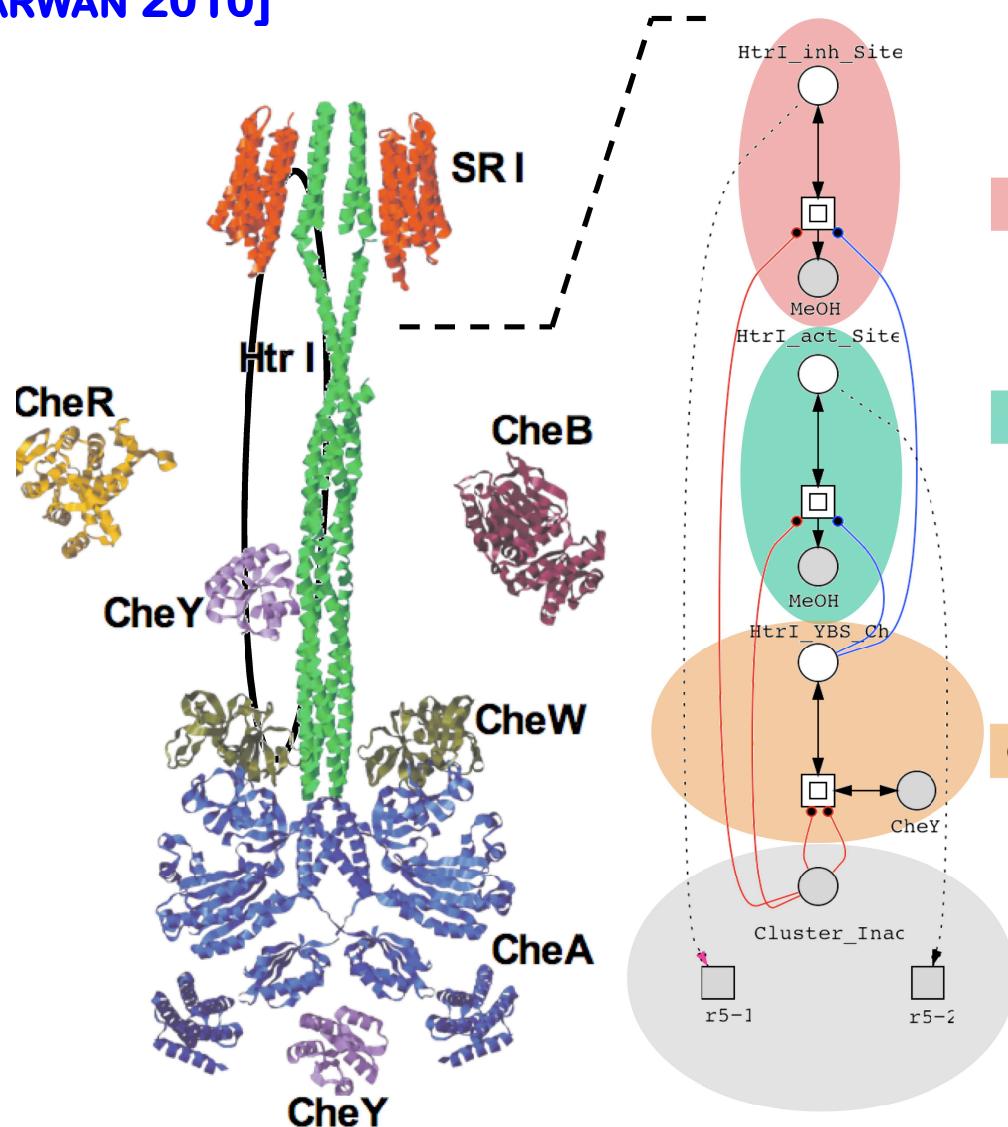
PN & BioModel Engineering



## Ex3 - HALOBACTERIUM SALINARUM

PN & BioModel Engineering

[MARWAN 2010]



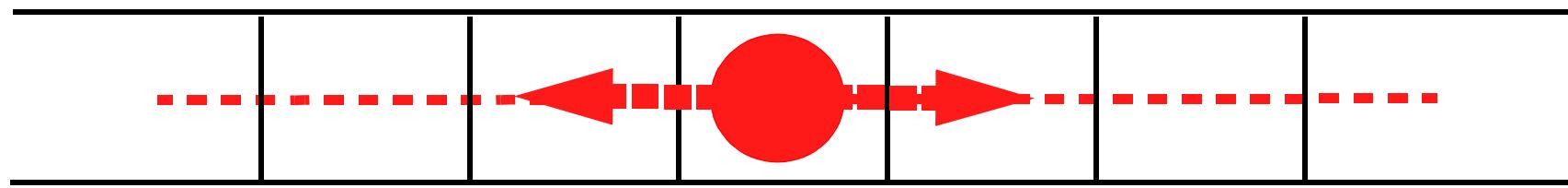
# **EXAMPLE: DIFFUSION IN SPACE**



*Richmond, 13/09/2011*

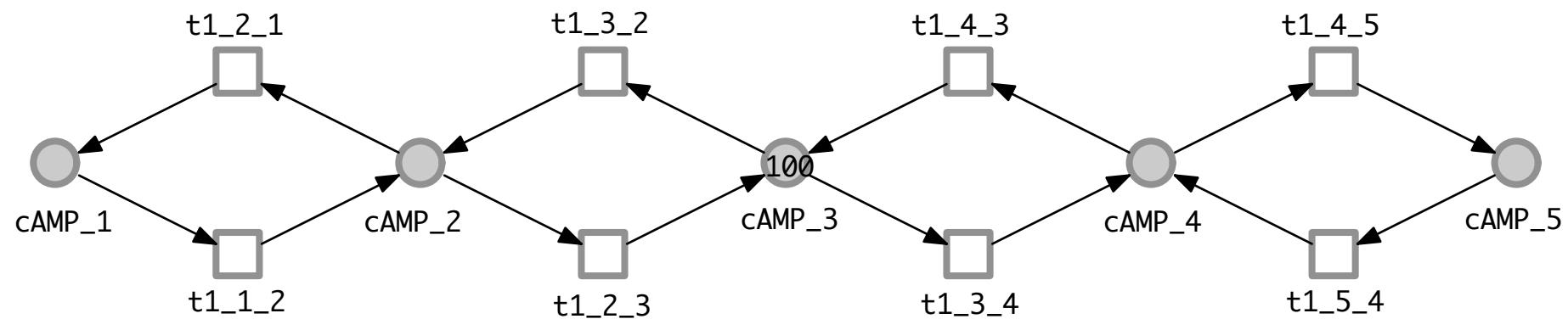
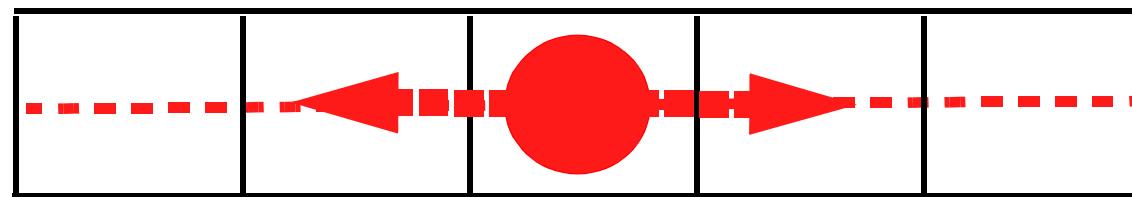
## Ex4: DIFFUSION - 1D

PN & BioModel Engineering



## Ex4: DIFFUSION - 1D

PN & BioModel Engineering

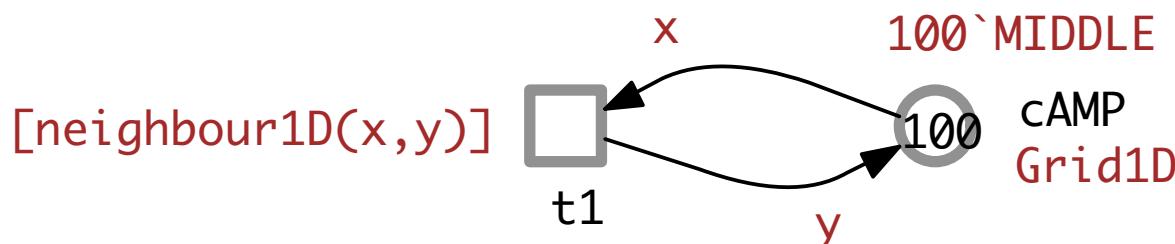


### □ definitions

```
const D1 = 5;           // grid size  
const MIDDLE = D1/2;  
colorset CS = 1-D1;    // grid positions  
var x,y : CS;
```

**function neighbour1D (CS x,a) bool:**

// a is neighbour of x  
( a=x-1 | a=x+1) & (1<=a) & (a<=D1);

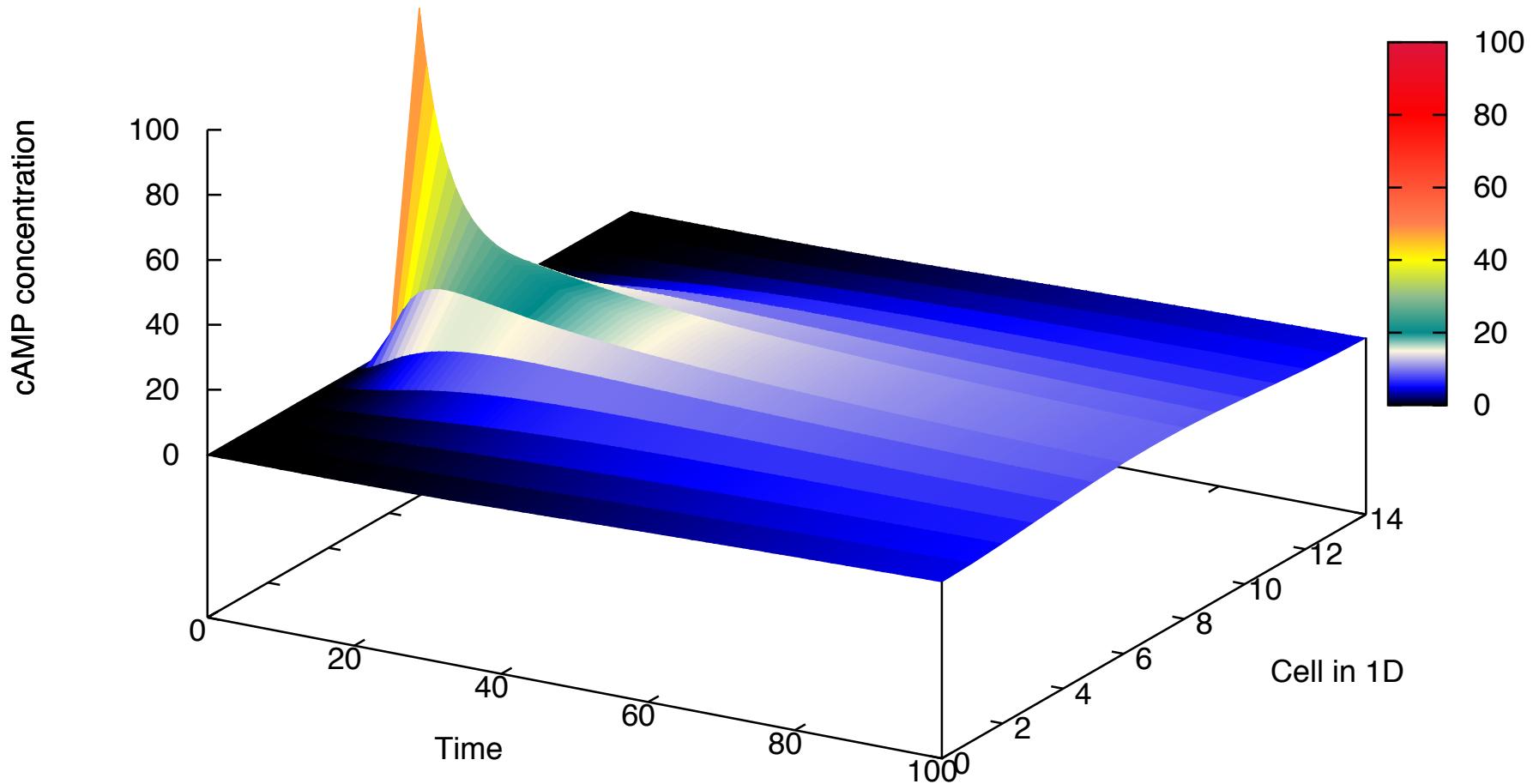


### □ movement = changing colour

$$\begin{aligned}\frac{dc_1}{dt} &= k \cdot c_2 - k \cdot c_1 \\ \frac{dc_2}{dt} &= k \cdot c_1 + k \cdot c_3 - 2 \cdot k \cdot c_2 \\ \frac{dc_3}{dt} &= k \cdot c_2 + k \cdot c_4 - 2 \cdot k \cdot c_3 \\ \frac{dc_4}{dt} &= k \cdot c_3 + k \cdot c_5 - 2 \cdot k \cdot c_4 \\ \frac{dc_5}{dt} &= k \cdot c_4 - k \cdot c_5\end{aligned}$$

## Ex4: DIFFUSION - 1D

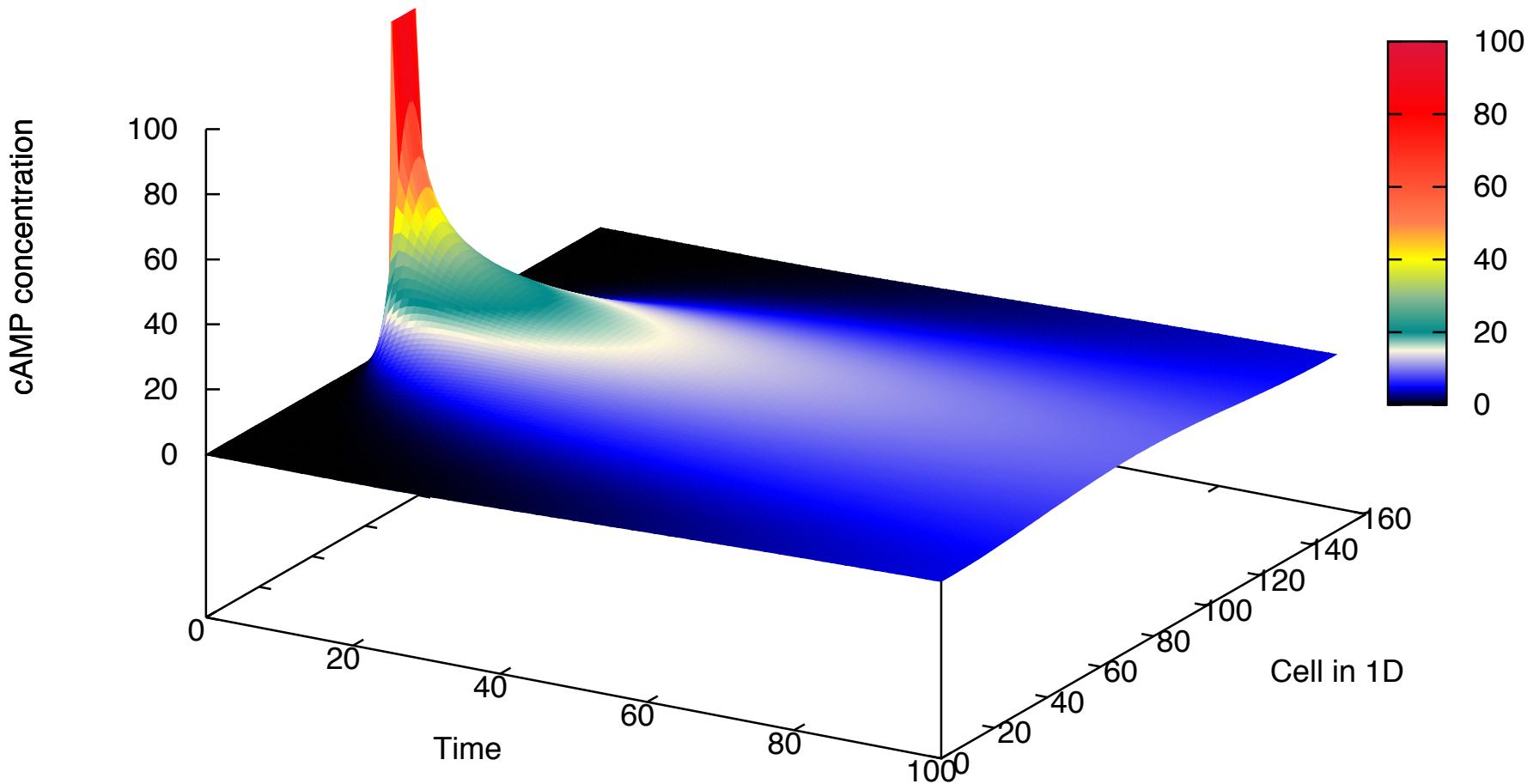
PN & BioModel Engineering



15 GRID POSITIONS

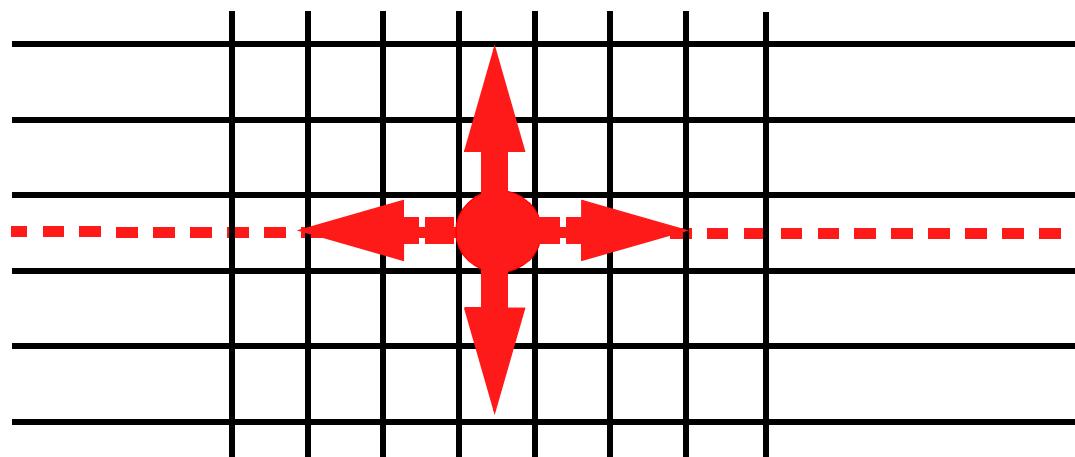
## Ex4: DIFFUSION - 1D

PN & BioModel Engineering

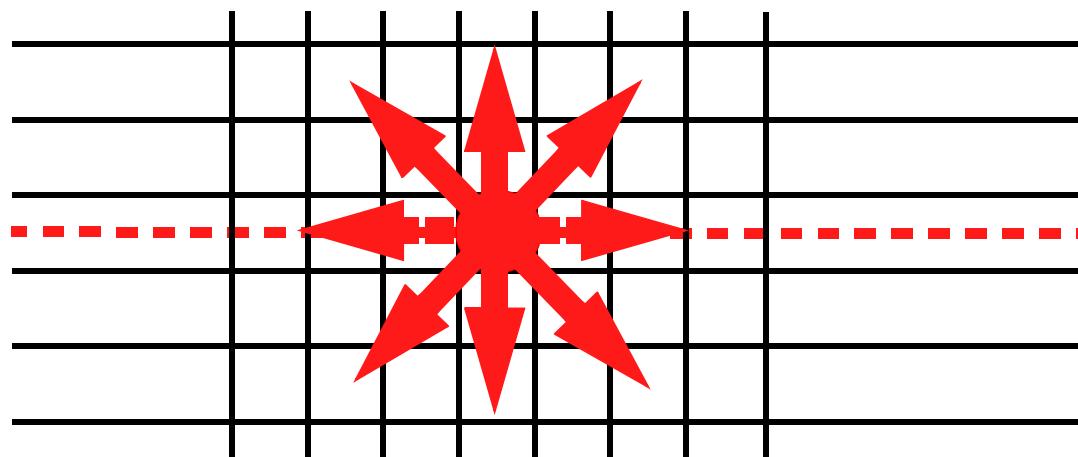


**150 GRID POSITIONS, SCALING OF INITIAL MARKING AND RATES**

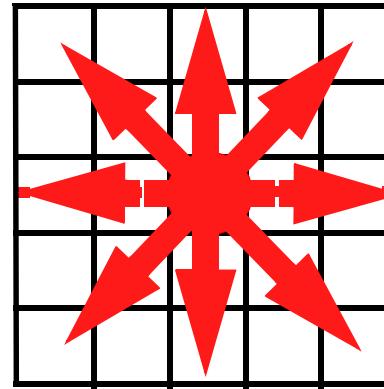
### □ SCHEME



### □ SCHEME



## □ SCHEME



## □ definitions

```
const D1 = 5;           // grid size first dimension
const D2 = 5;           // grid size second dimension
const MIDDLE = D1/2;
colorset CD1 = 1-D1;    // row index
colorset CD2 = 1-D2;    // column index
colorset Grid2D = CD1 x CD2; // 2D grid

var x, a : CD1;
var y, b : CD2;
```

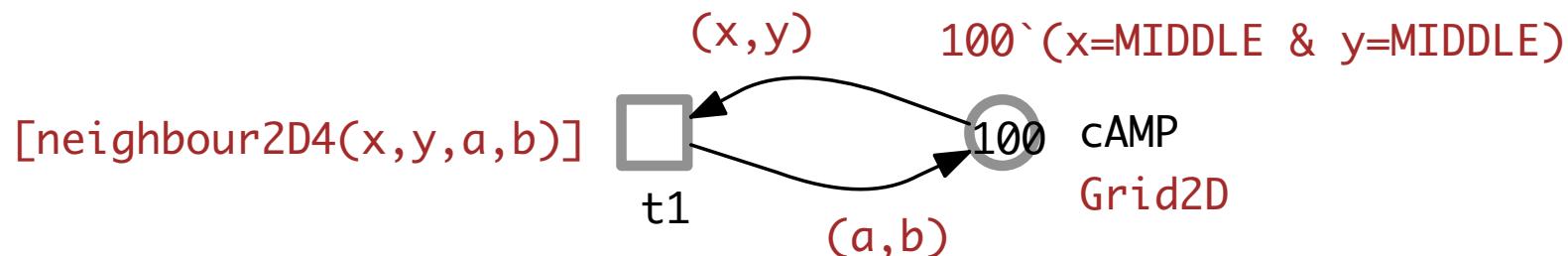
### □ four neighbours

**function** neighbour2D4 (CD1 x, CD2 y, CD1 a, CD2 b) **bool**:

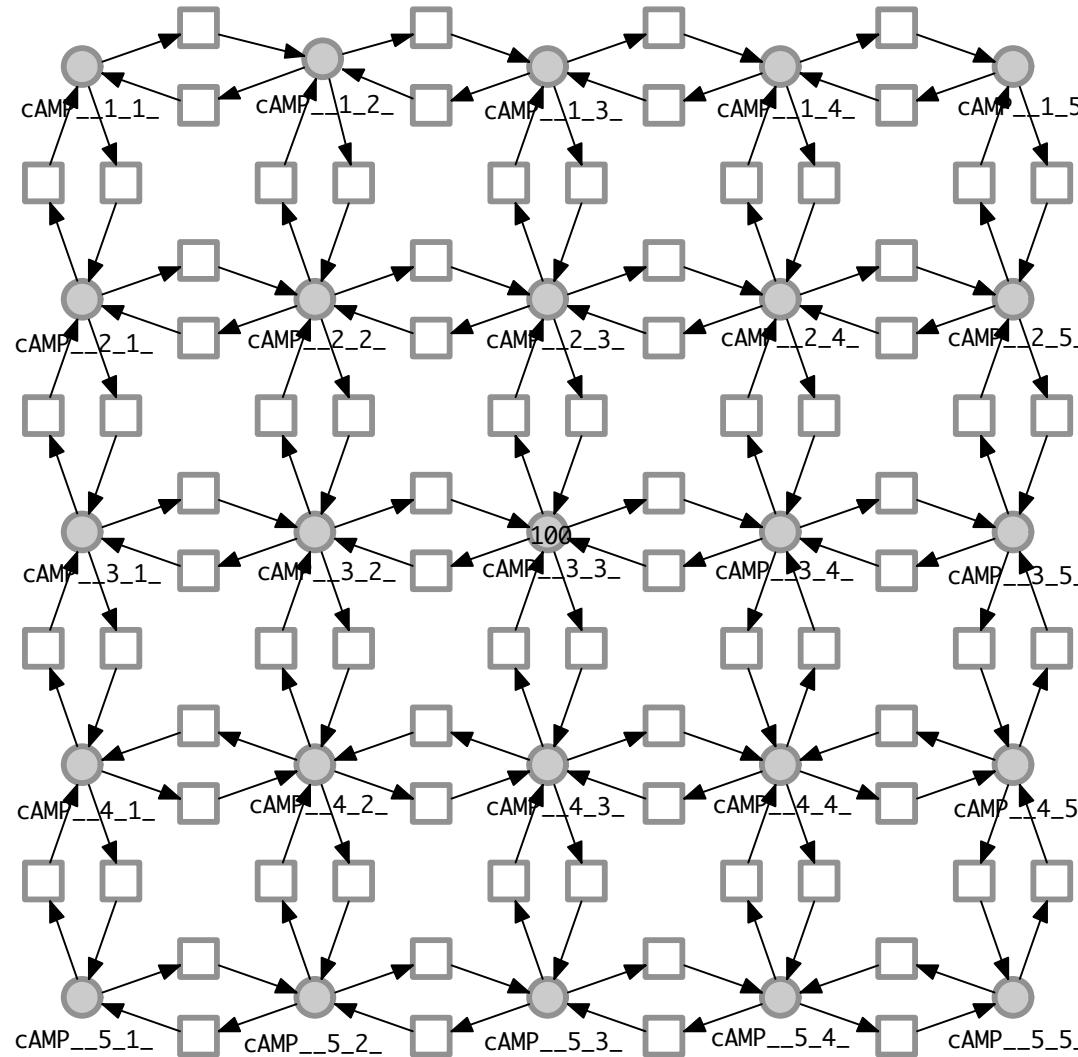
// (a,b) is one of the up to four neighbours of (x,y)

(a=x & b=y-1) | (a=x & b=y+1)

| (b=y & a=x-1) | (b=y & a=x+1);



## Ex4: DIFFUSION - 2D4 NEIGHBOURHOOD



### □ eight neighbours

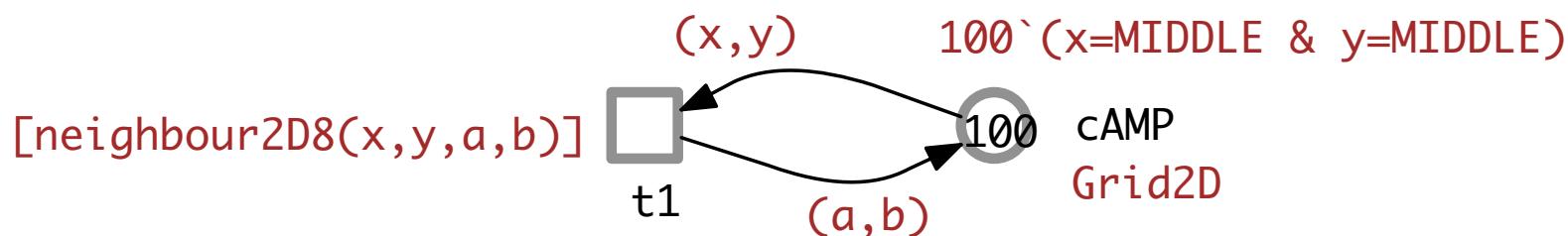
**function** neighbour2D8 (CD1 x, CD2 y, CD1 a, CD2 b) **bool**:

// (a,b) is one of the up to eight neighbours of (x,y)

(a=x-1 | a=x | a=x+1) & (b = y-1 | b=y | b=y+1)

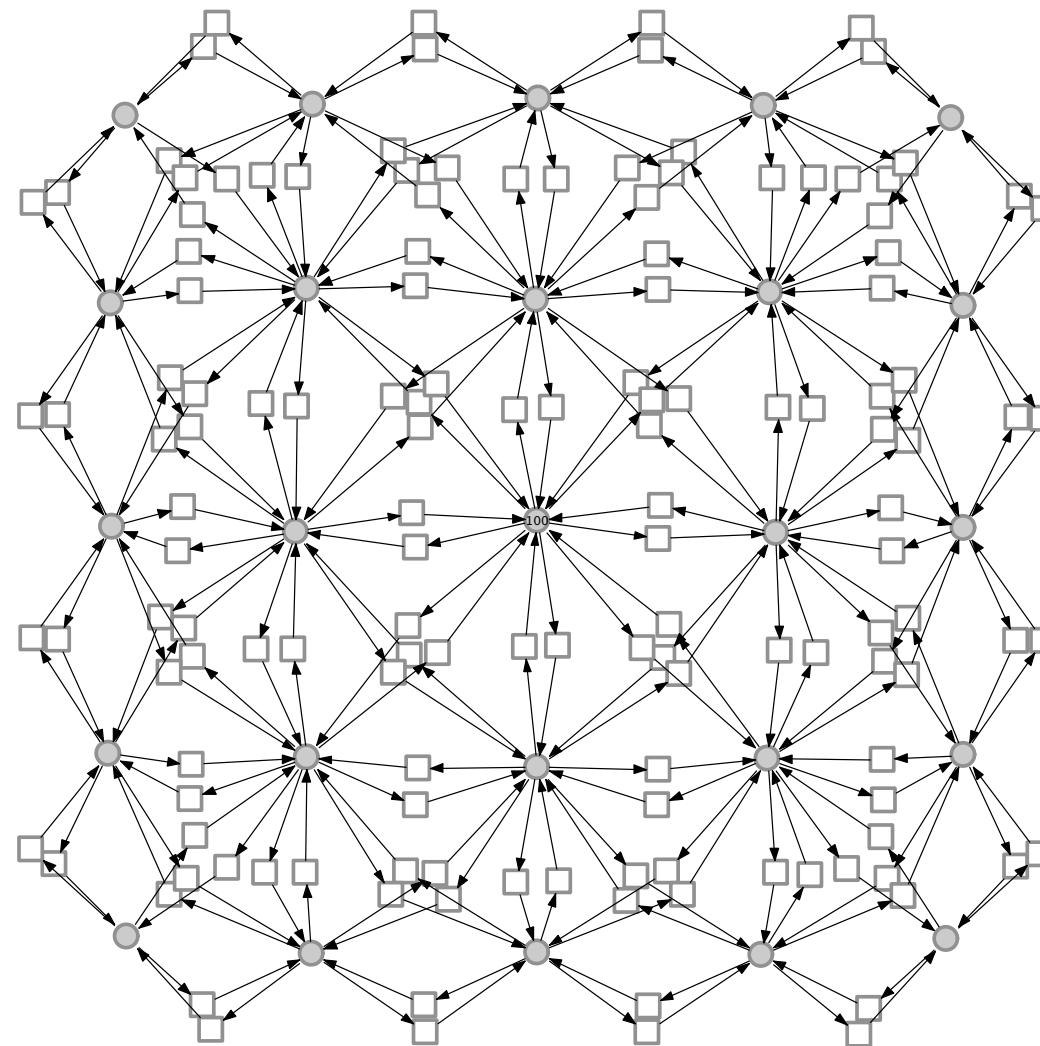
& !(a=x & b=y))

& (1<=a & a<=D1) & (1<=b & b<=D2);



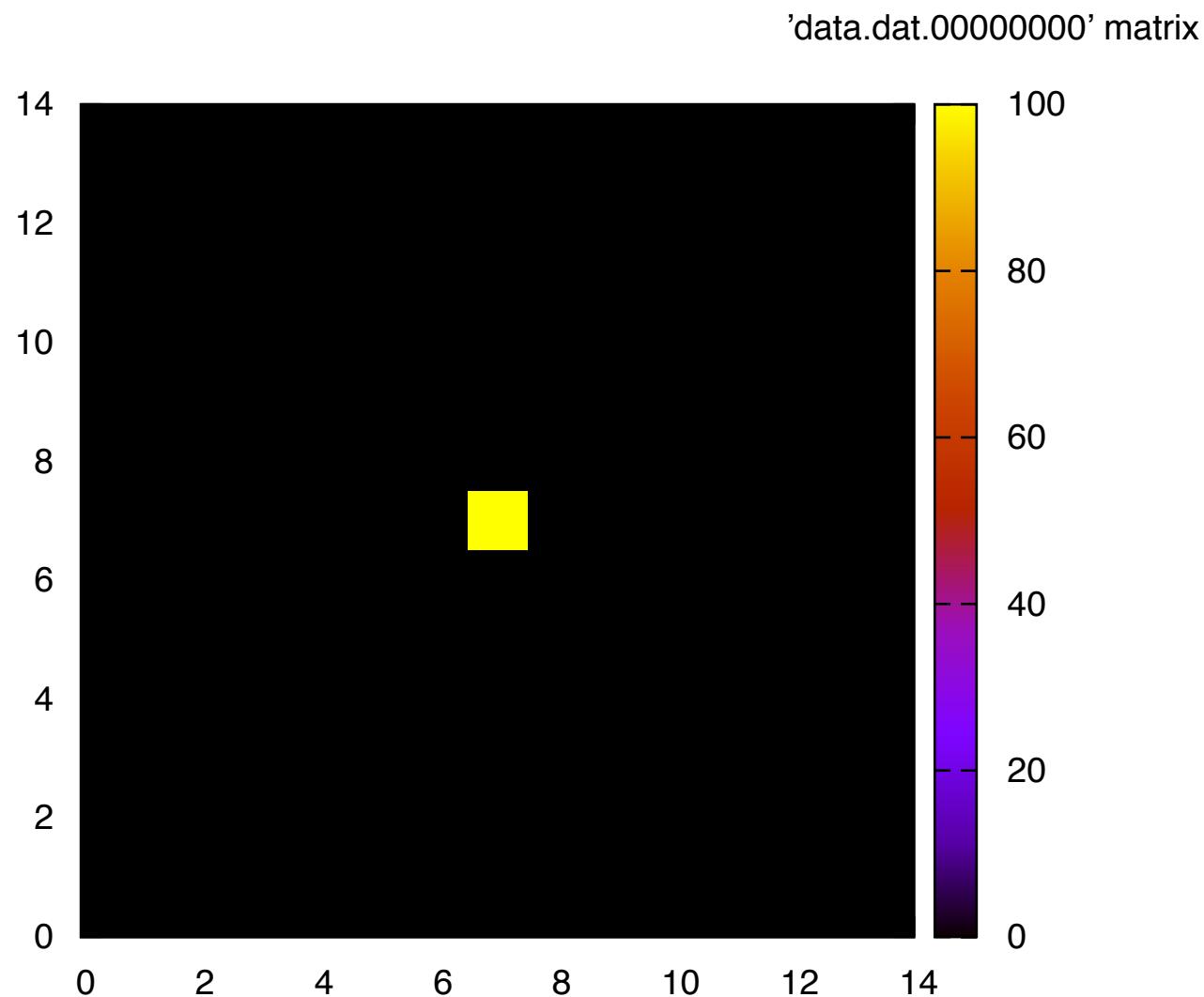
## Ex4: DIFFUSION - 2D8 NEIGHBOURHOOD

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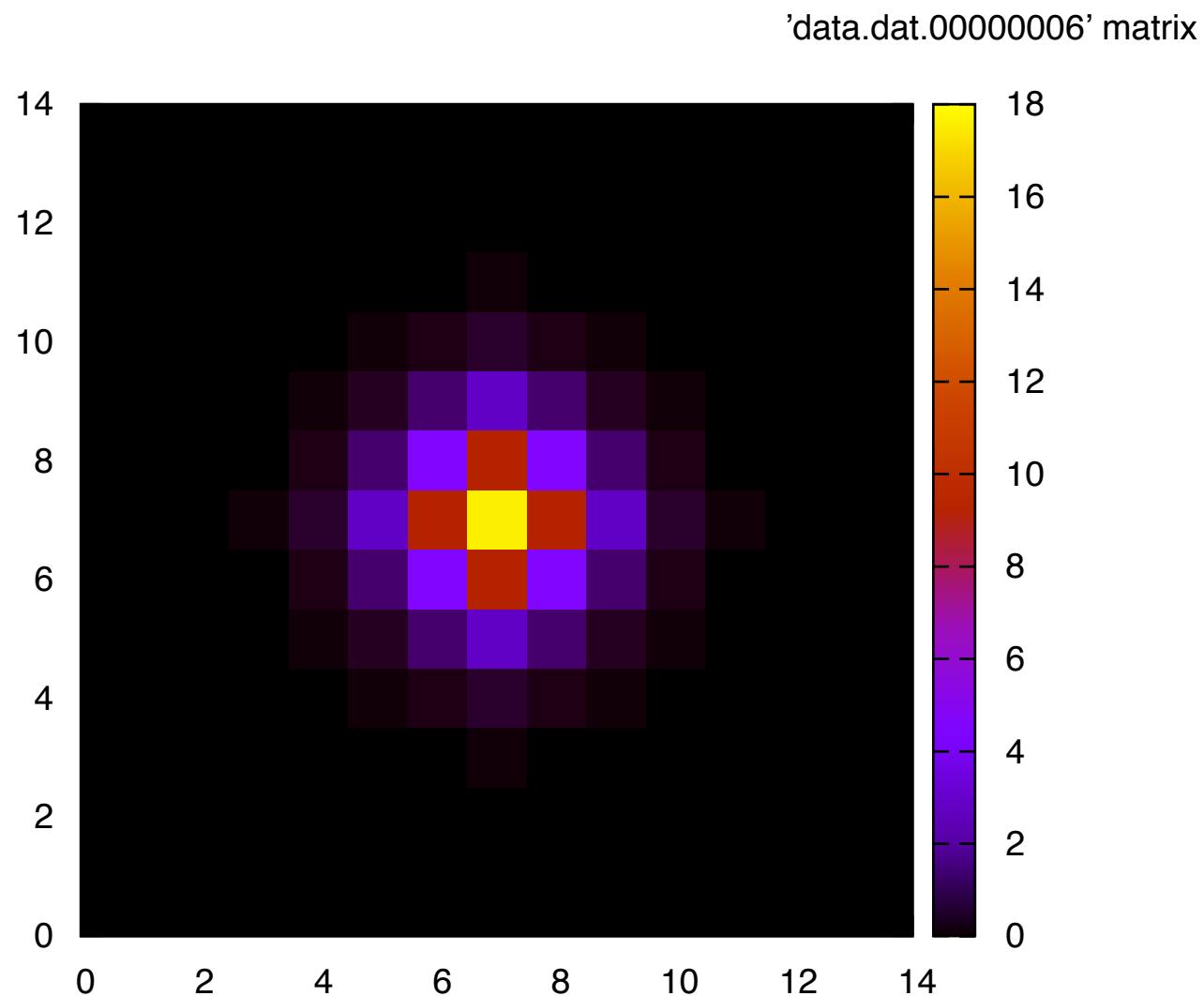
## Ex4: DIFFUSION - 2D4 NEIGHBOURHOOD, 15x15

PN & BioModel Engineering



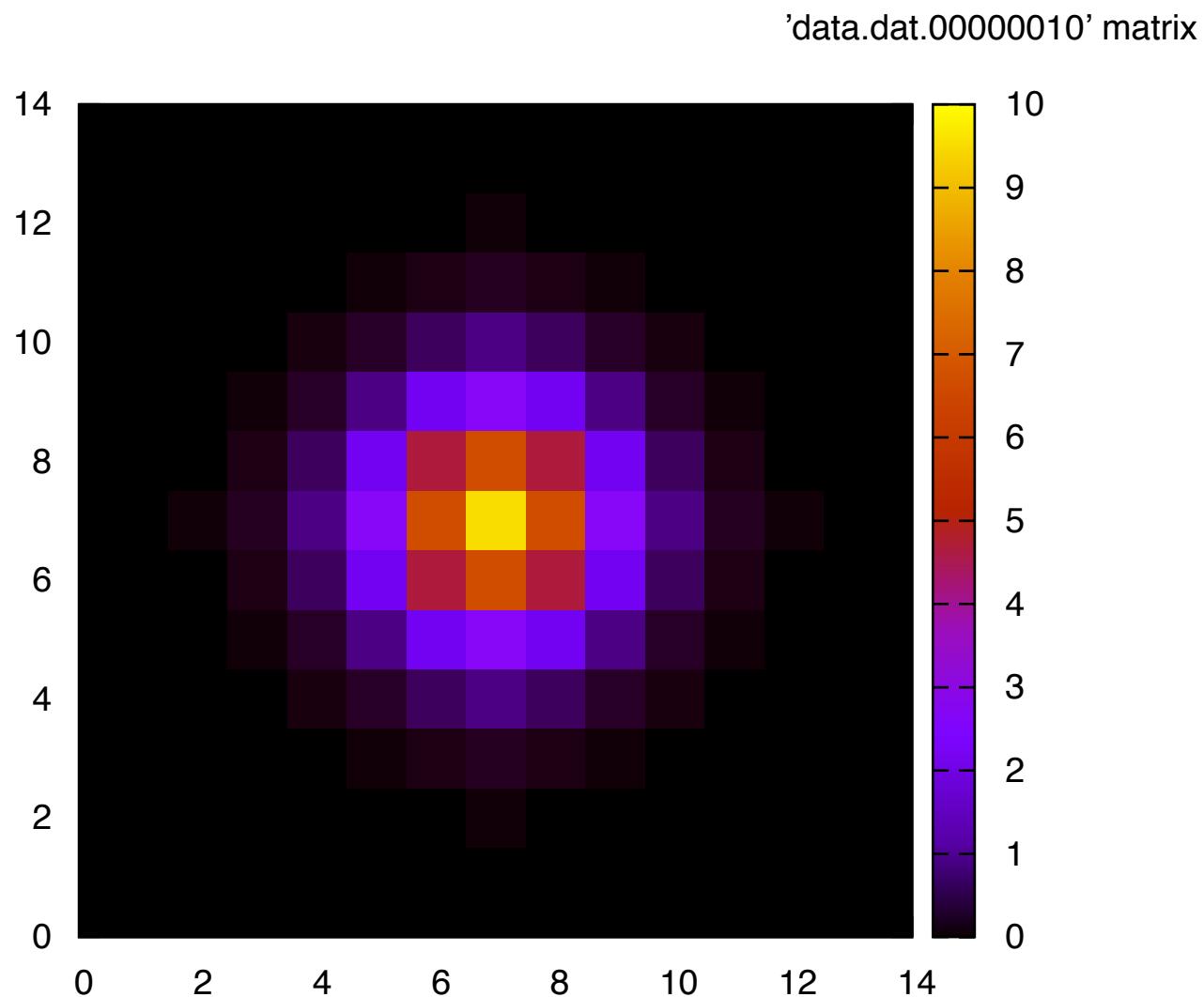
## Ex4: DIFFUSION - 2D4 NEIGHBOURHOOD, 15x15

PN & BioModel Engineering



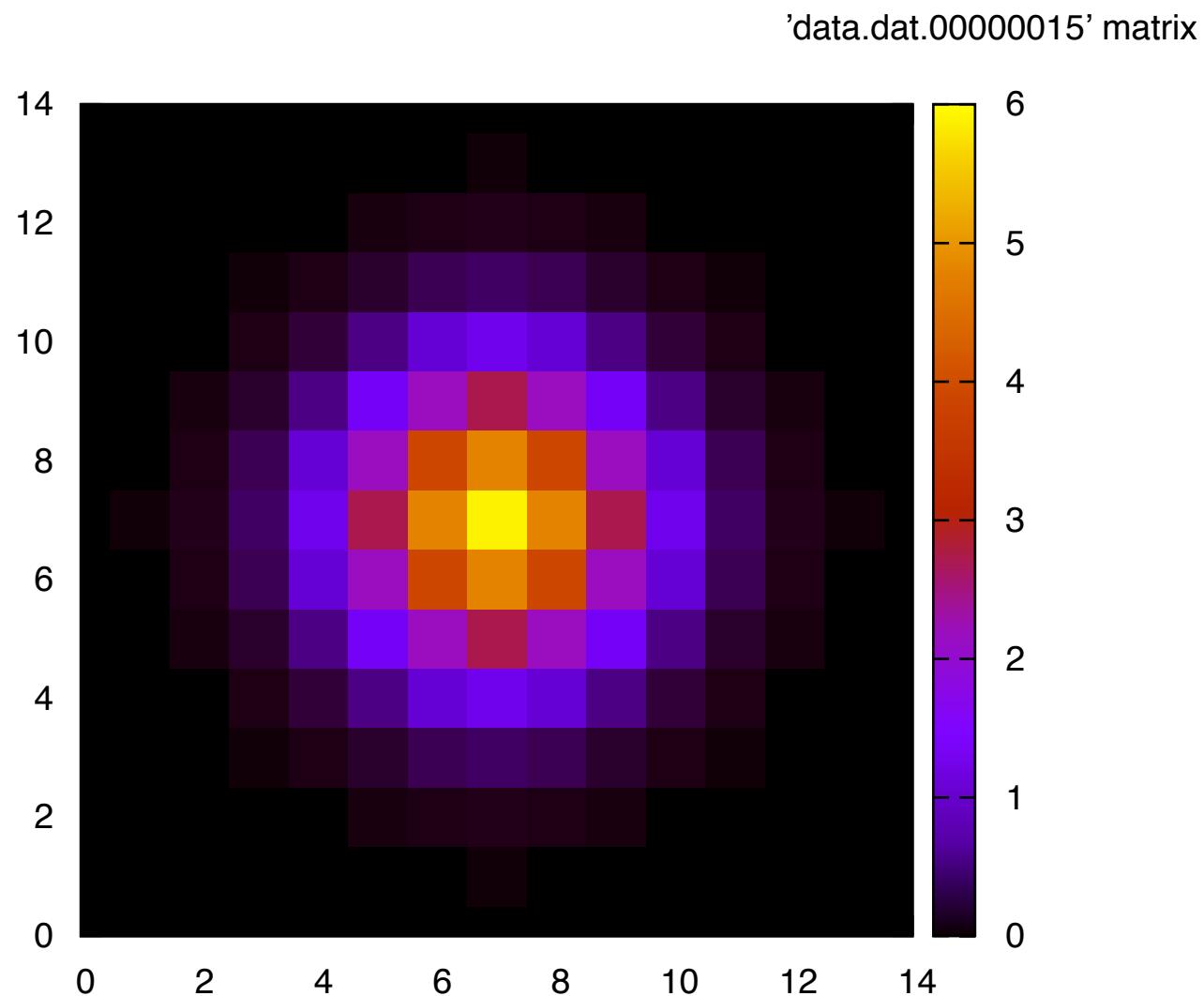
## Ex4: DIFFUSION - 2D4 NEIGHBOURHOOD, 15x15

PN & BioModel Engineering



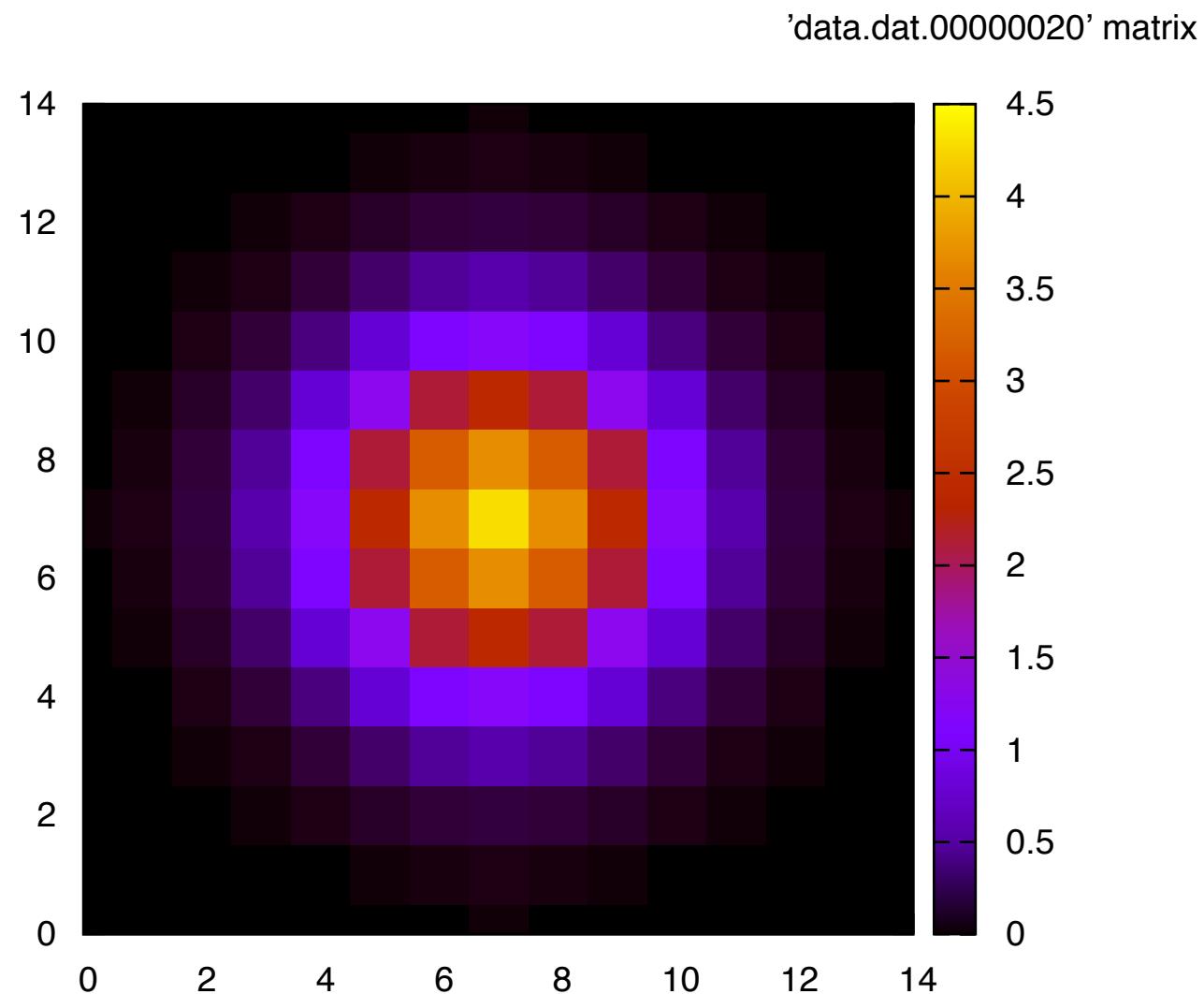
## Ex4: DIFFUSION - 2D4 NEIGHBOURHOOD, 15x15

PN & BioModel Engineering



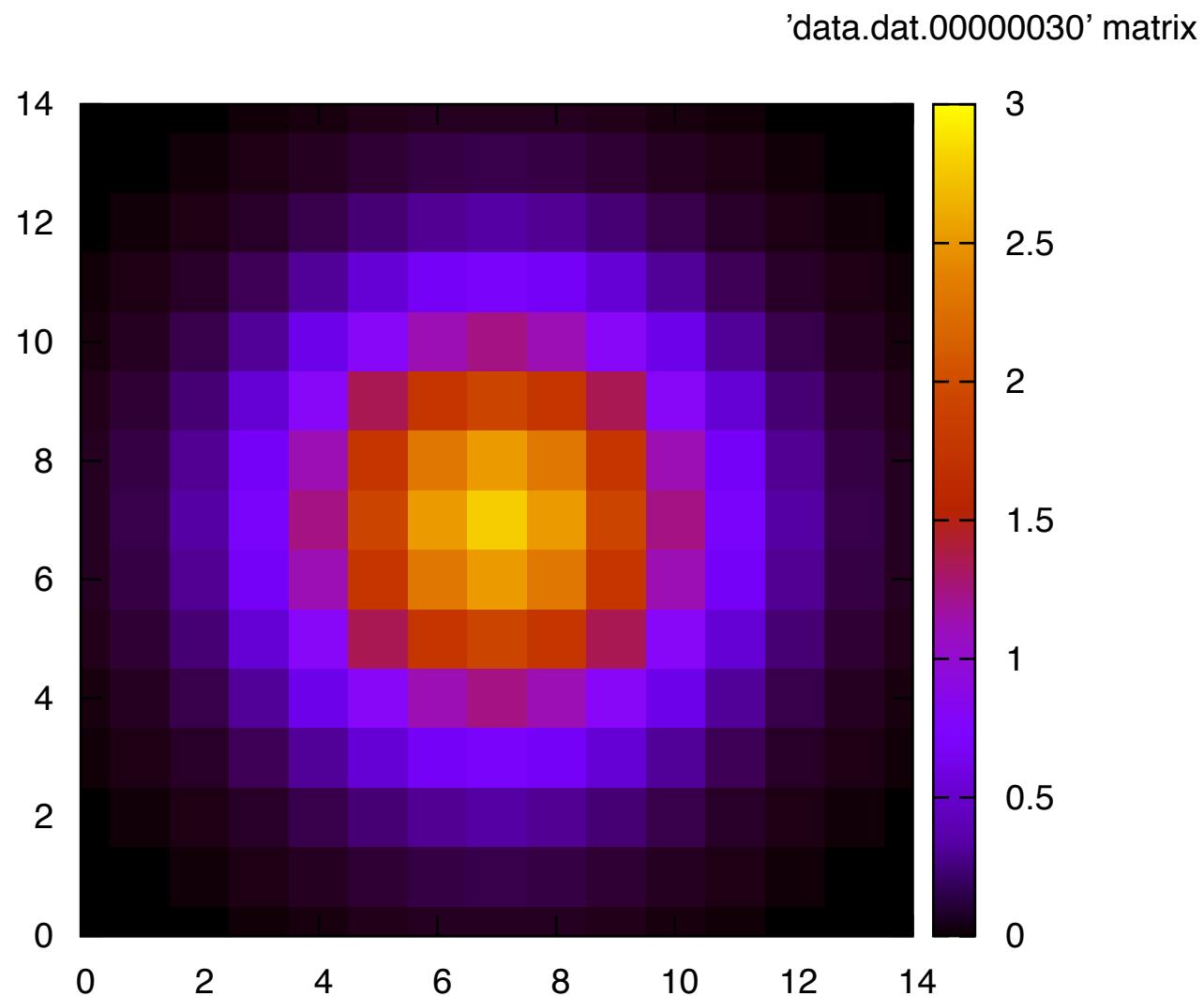
## Ex4: DIFFUSION - 2D4 NEIGHBOURHOOD, 15x15

PN & BioModel Engineering



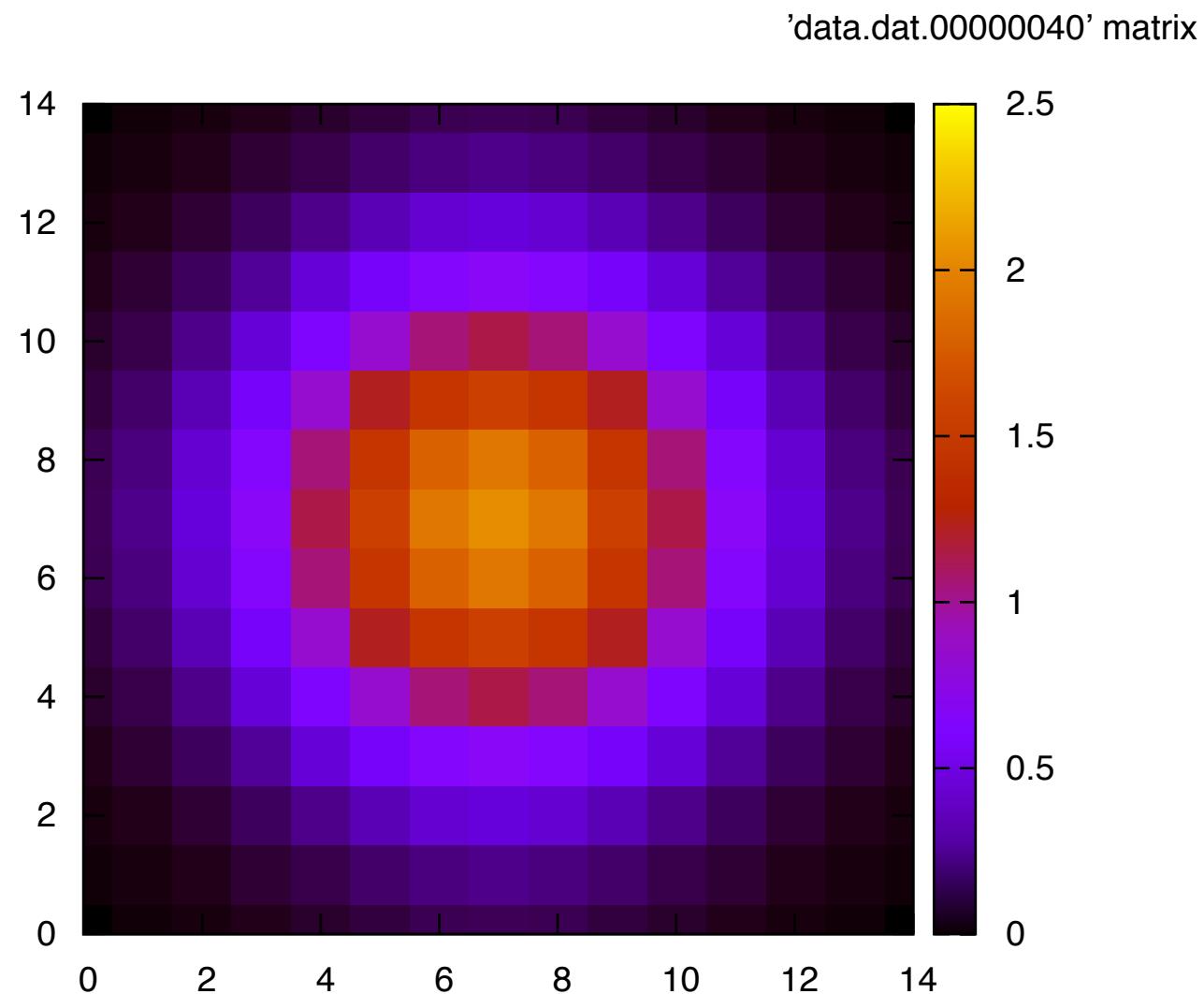
## Ex4: DIFFUSION - 2D4 NEIGHBOURHOOD, 15x15

PN & BioModel Engineering



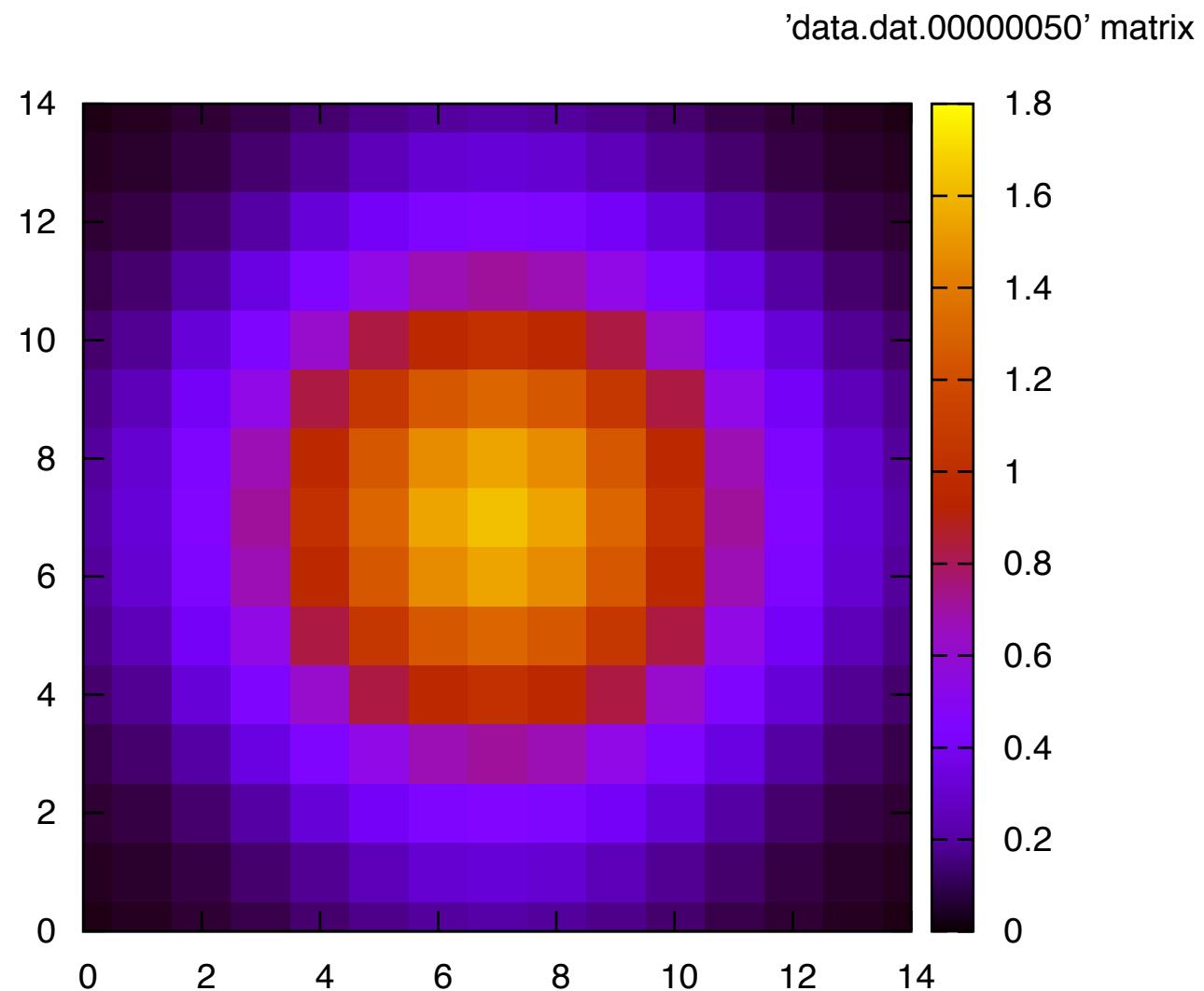
## Ex4: DIFFUSION - 2D4 NEIGHBOURHOOD, 15x15

PN & BioModel Engineering



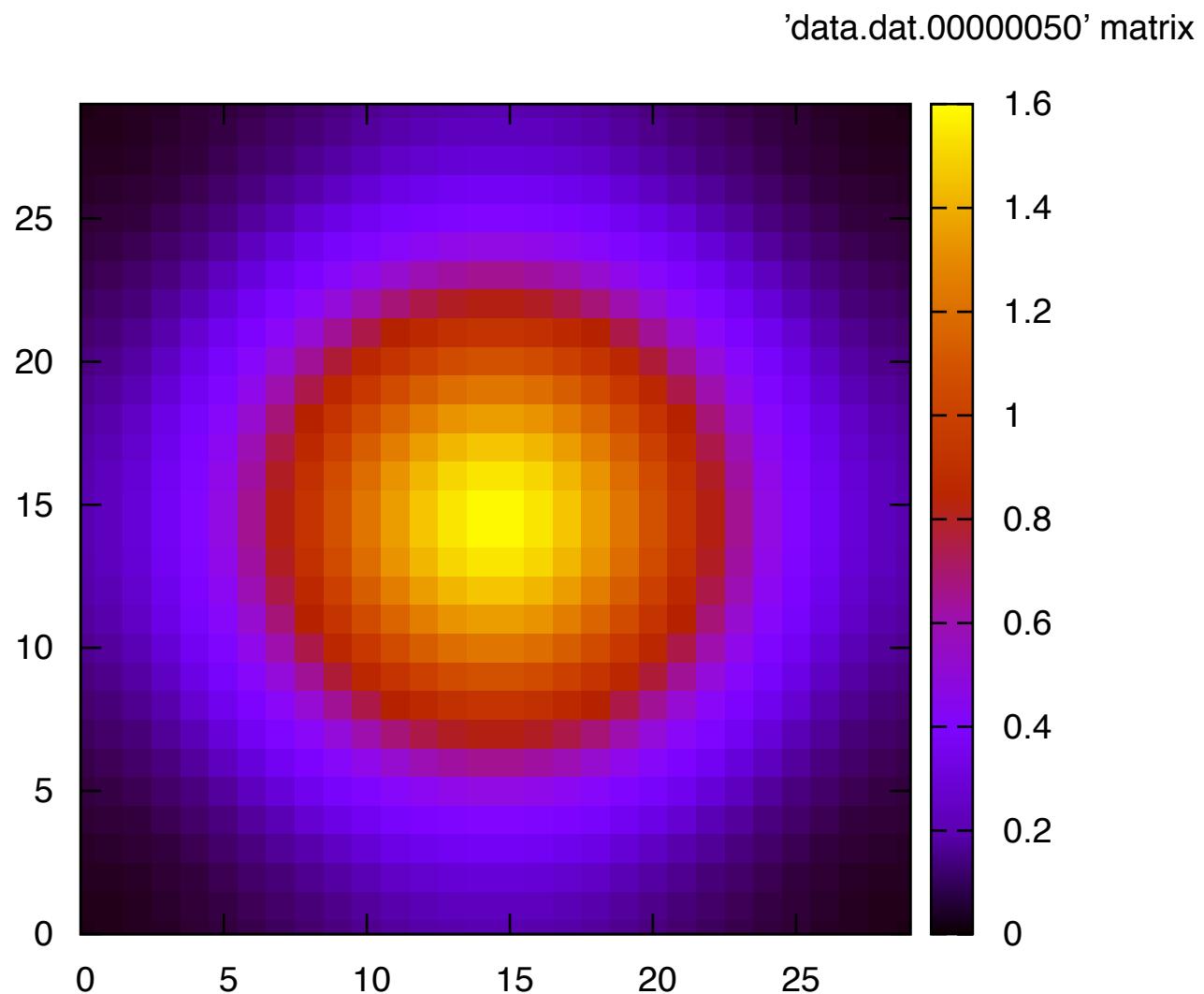
## Ex4: DIFFUSION - 2D4 NEIGHBOURHOOD, 15x15

PN & BioModel Engineering



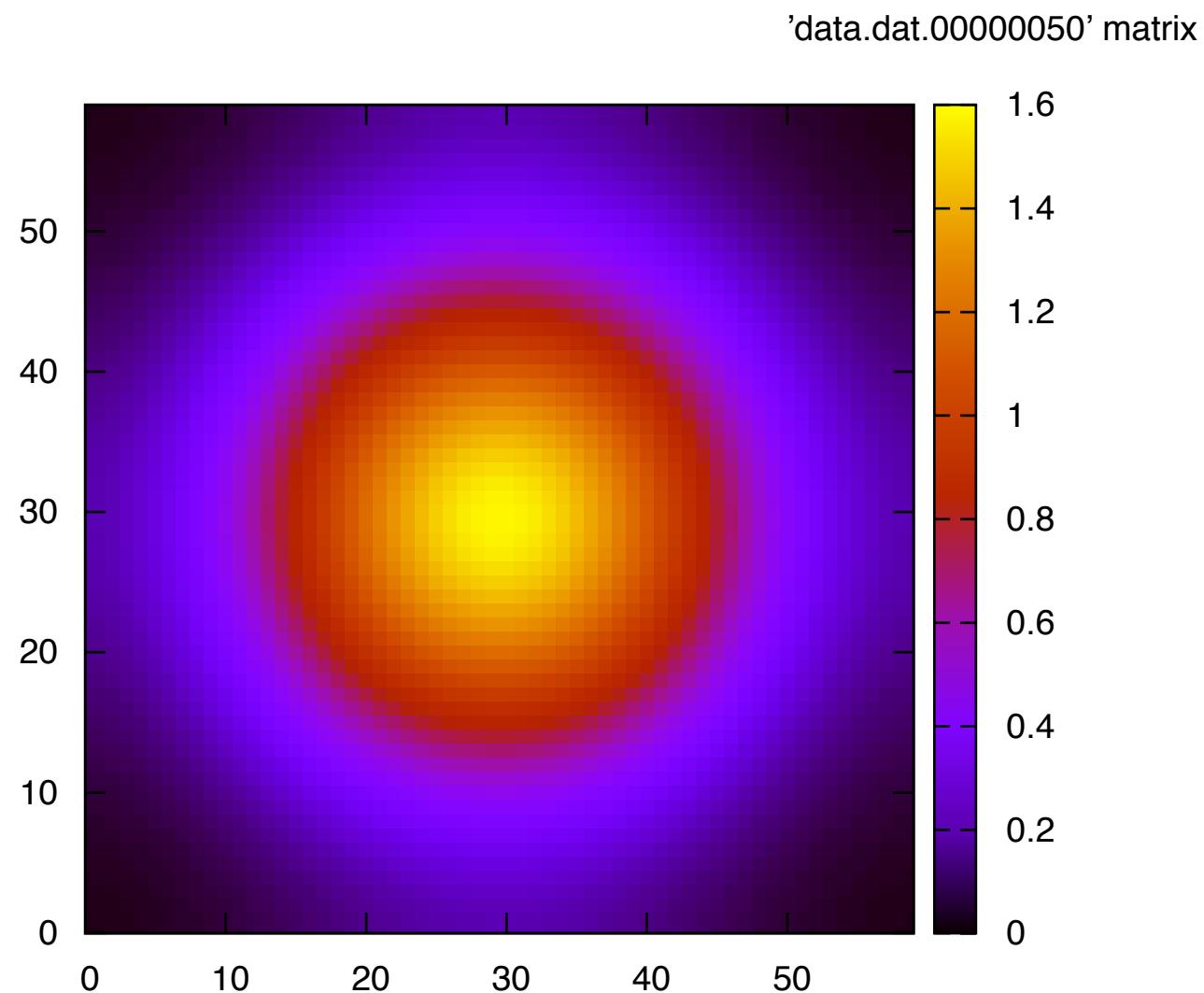
## Ex4: DIFFUSION - 2D4 NEIGHBOURHOOD, 30x30

PN & BioModel Engineering



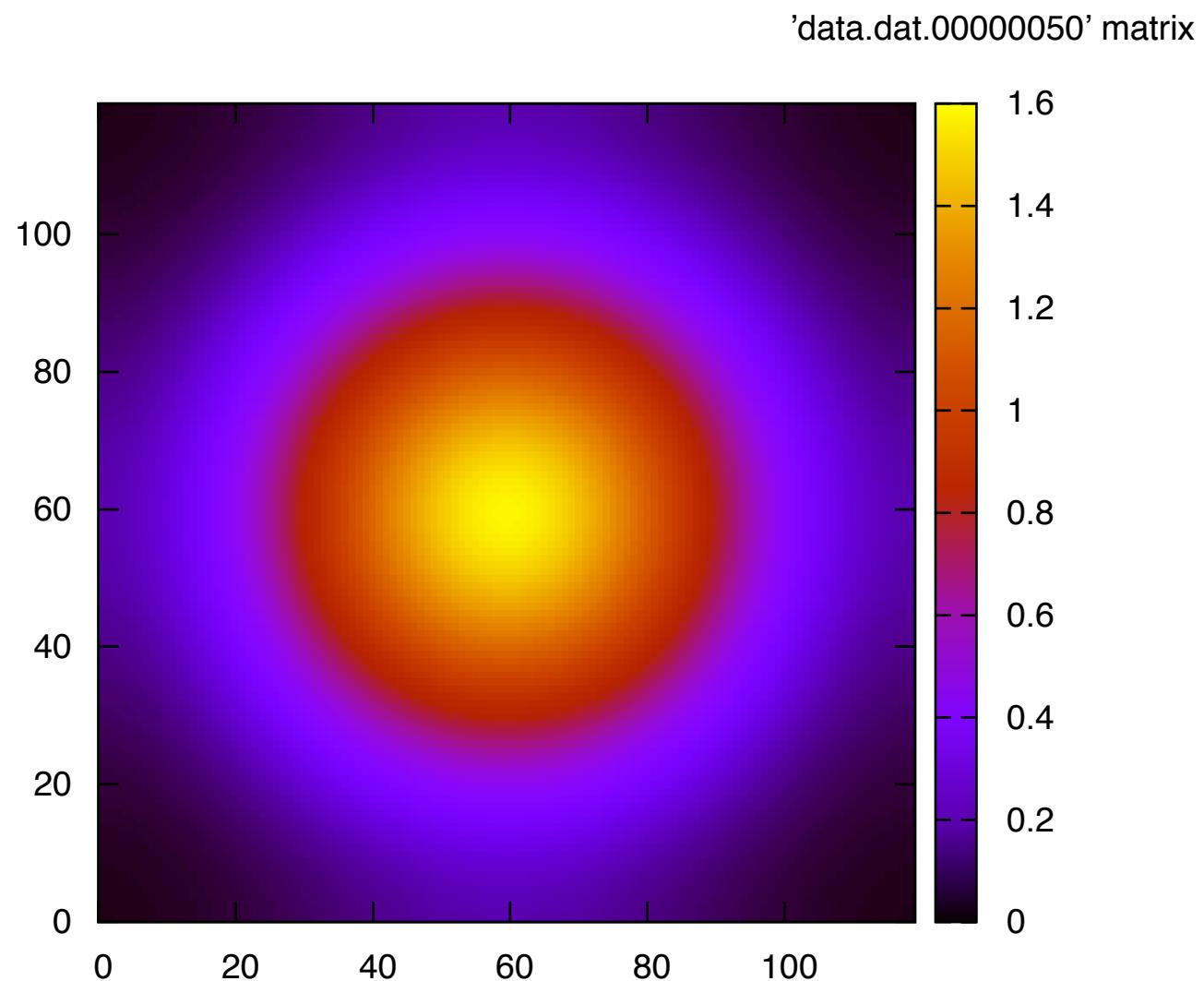
## Ex4: DIFFUSION - 2D4 NEIGHBOURHOOD, 60x60

PN & BioModel Engineering



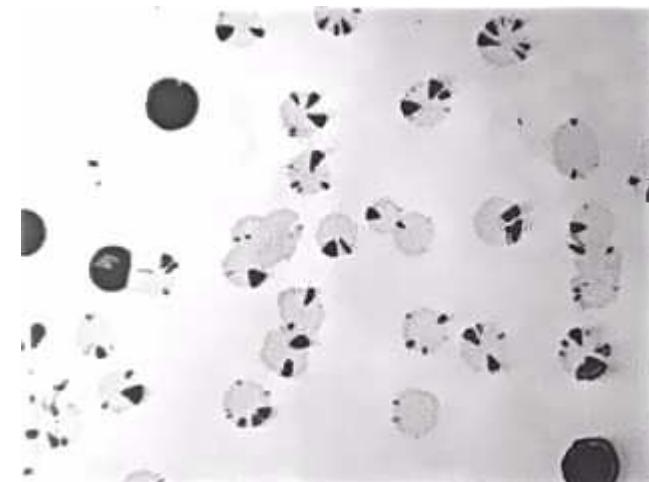
## Ex4: DIFFUSION - 2D4 NEIGHBOURHOOD, 120x120

PN & BioModel Engineering



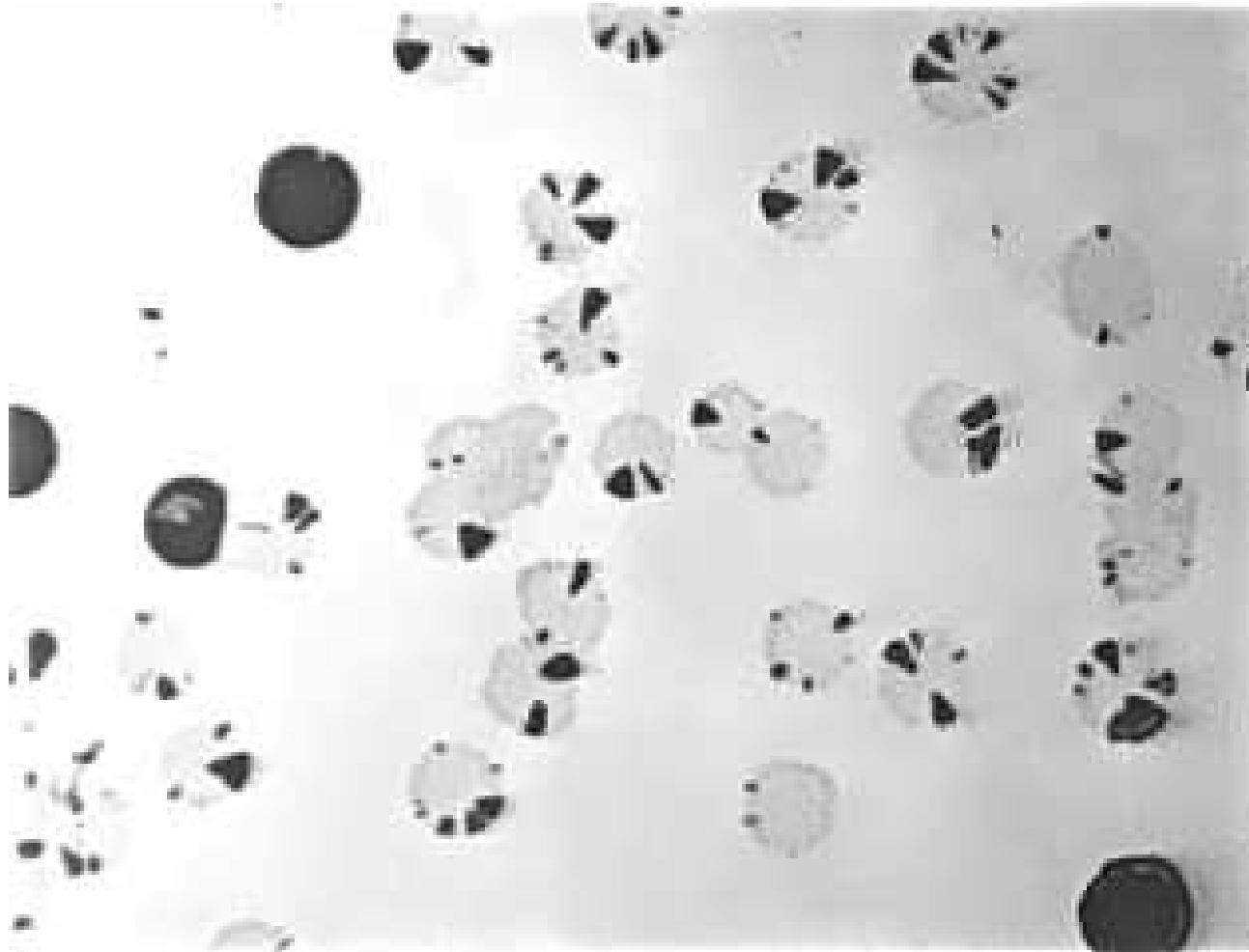
**EXAMPLE:**  
**PHASE VARIATION IN**  
**MULTISTRAIN CELL COLONIES**

- **method for dealing with rapidly varying environments without requiring random mutations**
  
- **contingency gene**
  - > *populations include variants adapted to “foreseeable” frequently encountered environmental or selective conditions*
  
- **stochastic gene switching process**
  - > *controlled by reversible gene mutations, inversions, or epigenetic modification*
  - > *e.g. switch between two phenotypes A, B*
  
- **colonial sectoring**
  - > *observable effect in cultures grown in vitro*



## Ex5: CELL COLONIES, WETLAB OBSERVATIONS

PN & BioModel Engineering



(courtesy of N Saunders)

*Microbiology* (2003), 149, 485–495

DOI 10.1099/mic.0.25807-0

# Mutation rates: estimating phase variation rates when fitness differences are present and their impact on population structure

Nigel J. Saunders,<sup>1†</sup> E. Richard Moxon<sup>1</sup> and Mike B. Gravenor<sup>2</sup>

Correspondence  
Nigel J. Saunders  
saunders@molbiol.ox.ac.uk

<sup>1</sup>Molecular Infectious Diseases Group, Institute of Molecular Medicine, University of Oxford,  
Headington, Oxford OX3 9DS, UK

<sup>2</sup>Institute for Animal Health, Compton, Berkshire RG20 7NN, UK

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Phase variation is a mechanism of ON–OFF switching that is widely utilized by bacterial pathogens.  
There is currently no standardization to how the rate of phase variation is determined experimentally.

Microbiology (2003), 149, 485–495

DOI 10.1093/mic/025807-0

Mutation rates: estimating phase variation rates when fitness differences are present and their impact on population structure

Nigel J. Saunders<sup>1</sup> E-mail: richard.Moxon<sup>1</sup> and Mike B. Gravenor<sup>2</sup>

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n.j.saunders@microbiol.ox.ac.uk

Molecular Infectious Diseases Group, Institute of Molecular Medicine, University of Oxford,  
Headington, Oxford OX3 9DS, UK

Institute for Animal Health, Compton, Berkshire RG20 7NN, UK

NO SPACE

Phase variation is a mechanism of ON-OFF switching that is widely utilized by bacterial pathogens. There is currently no standardization to how the rate of phase variation is determined experimentally.

- two cell types: phenotype A and B

- cell divide

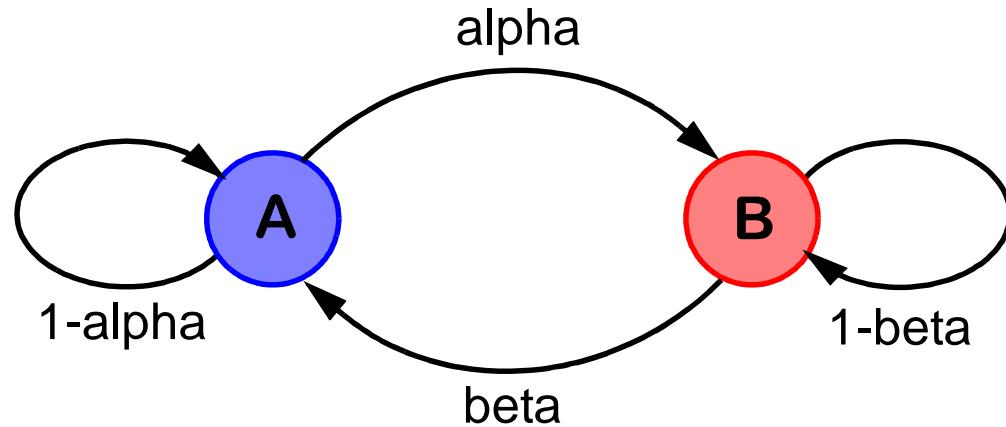
- > *cell division may involve mutation of the offspring*
- > *parent cell keeps its phenotype*

- model parameters

- > *alpha = beta - mutation rates*
- > *da, db - fitness of A, B*
- > *da/db - relative fitness*

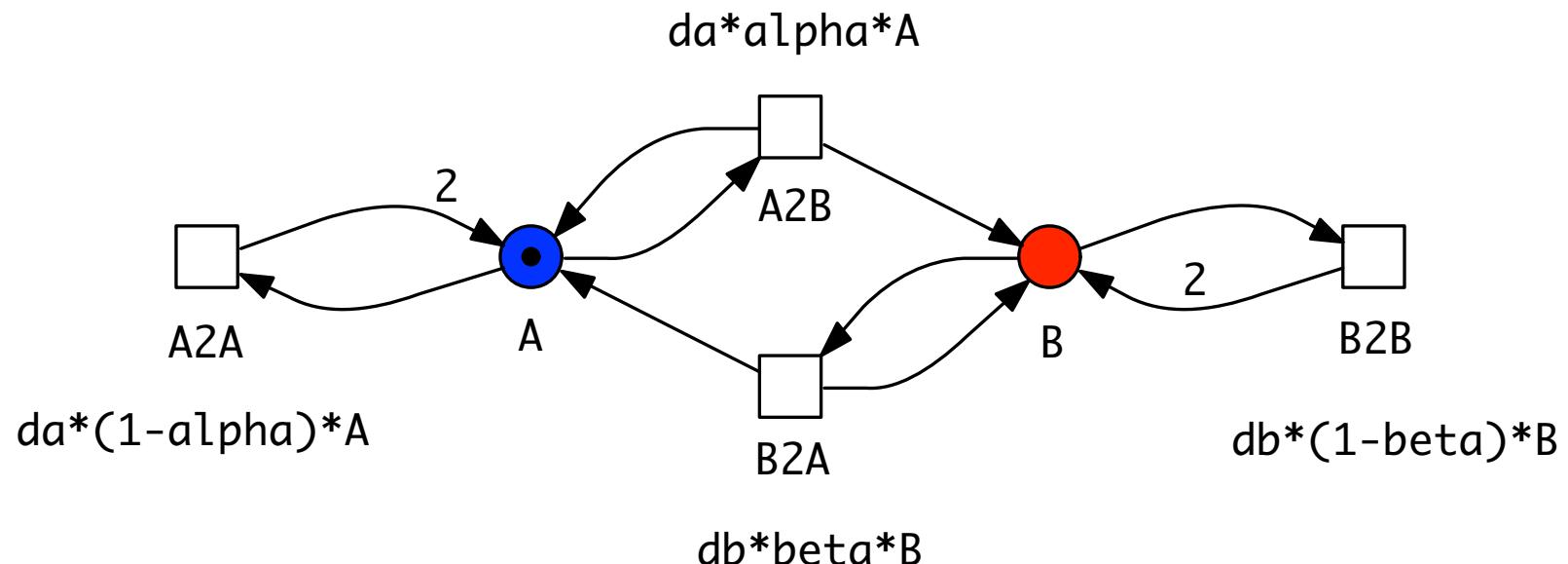
- output

- > *total number of cells*
- > *proportion of A = A / (A + B)*
- > *proportion of B = B / (A + B)*



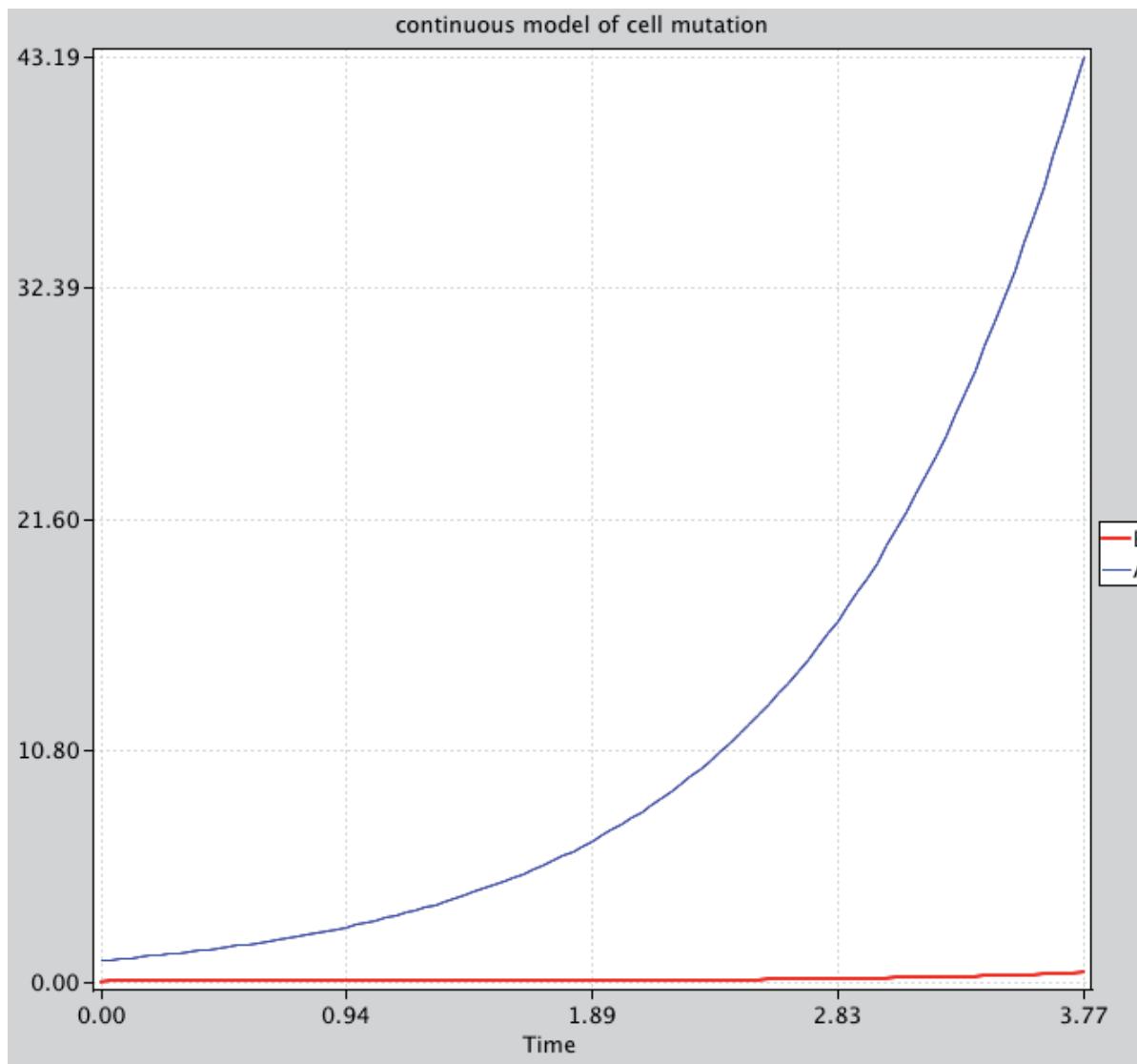
## Ex5: CELL COLONIES, PETRI NET

PN & BioModel Engineering



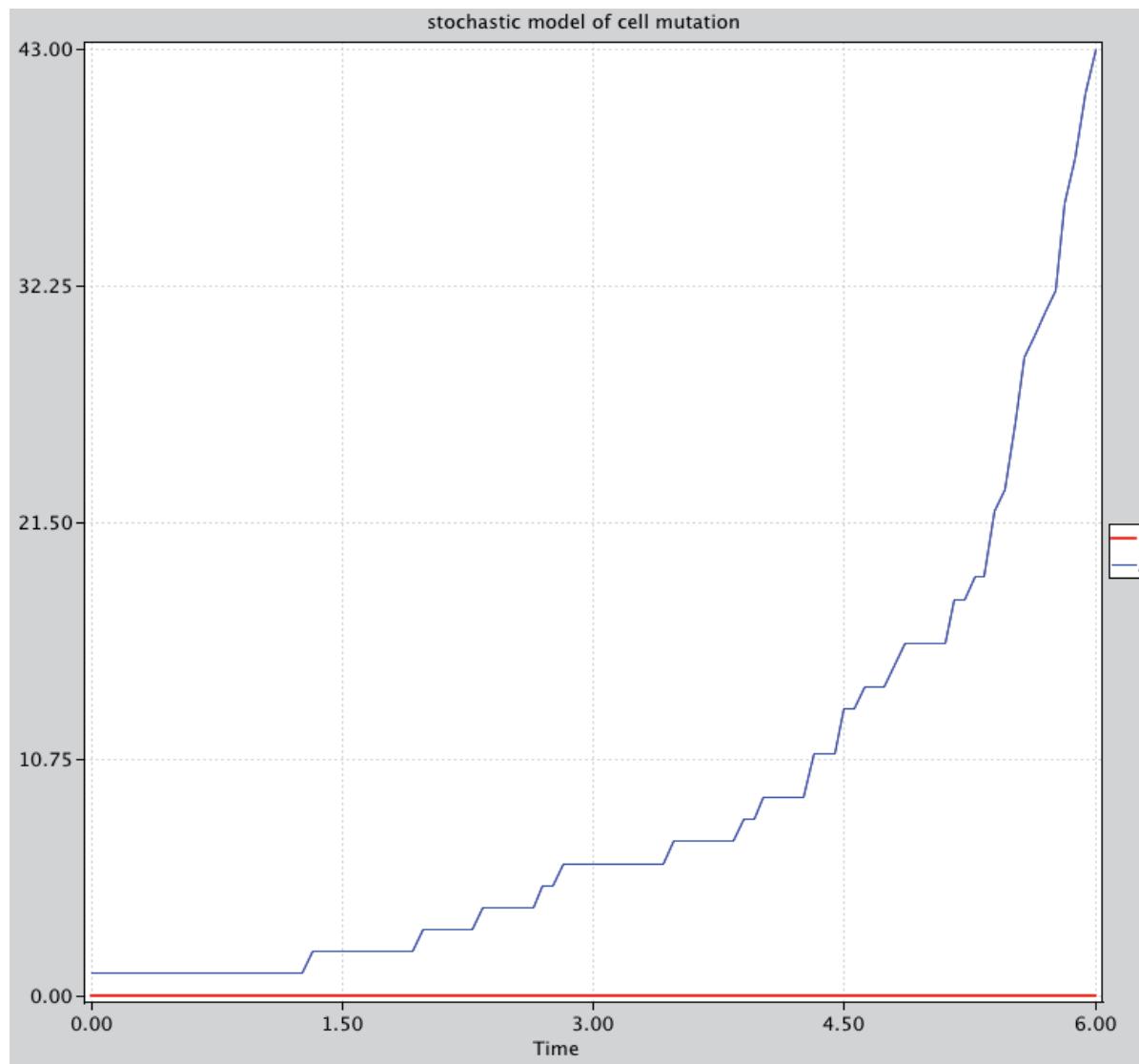
## Ex5: CELL COLONIES, CONTINUOUS PLOT

PN & BioModel Engineering



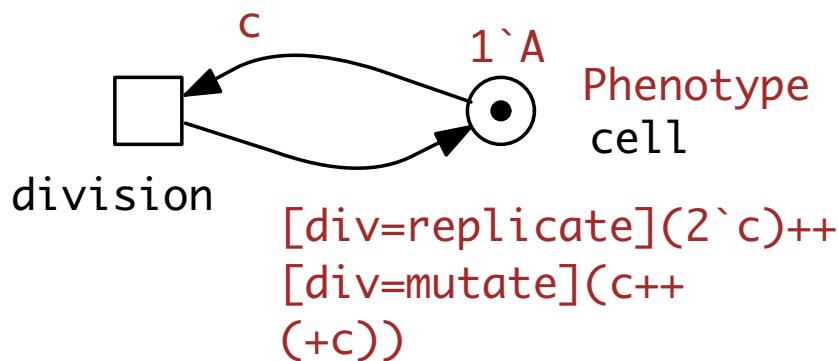
## Ex5: CELL COLONIES, STOCHASTIC PLOT

PN & BioModel Engineering



**colorset Phenotype = enum with A, B;**

**colorset DivisionType = enum with replicate , mutate ;**



$(c=A) \& (div=replicate) : cell * da * (1 - \alpha)$

$(c=A) \& (div=mutate) : cell * (da * \alpha)$

$(c=B) \& (div=replicate) : cell * (db * (1 - \beta))$

$(c=B) \& (div=mutate) : cell * (db * \beta)$

```
colorset Phenotype = enum with A, B;  
colorset DivisionType = enum with replicate , mutate ;
```

**ADDING SPACE  
CONTROLLING COLONY SPREADING**

**CONTROLLING THICKNESS**

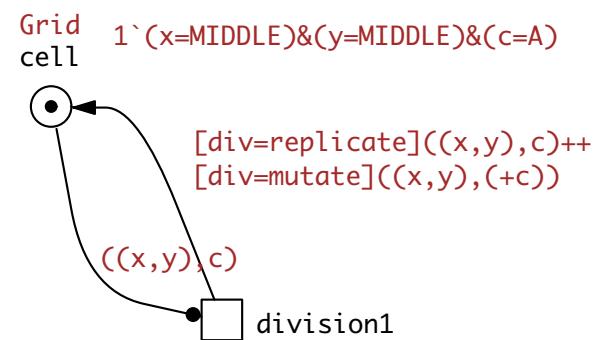
**CONTROLLING COLONY SIZE**

```
division [div=replicate](2`c)++  
[div=mutate](c- (+))  
  
(c=A) & (div=replicate) : cell*(da*(1-alpha))  
(c=A) & (div=mutate) : cell*(da*(alpha))  
(c=B) & (div=replicate) : cell*(db*(1-beta))  
(c=B) & (div=mutate) : cell*(db*beta)
```

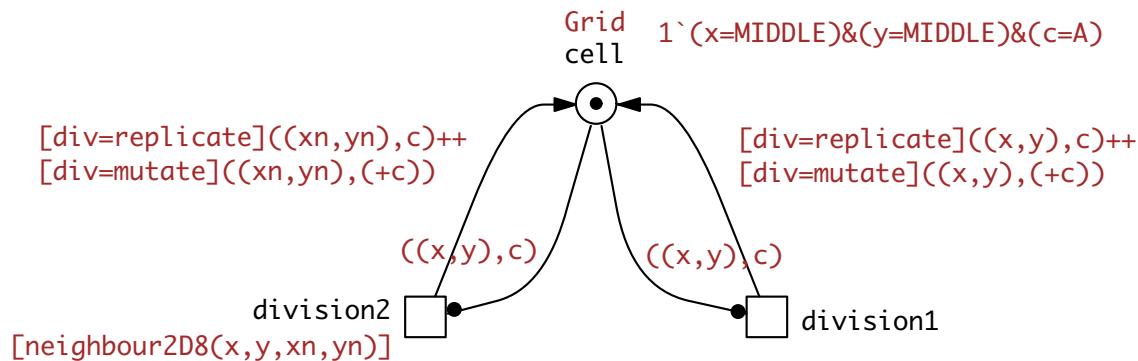
## Ex5: CELL COLONIES, ADDING SPACE

PN & BioModel Engineering

**colorset Grid = product with Grid2D x Phenotype;**



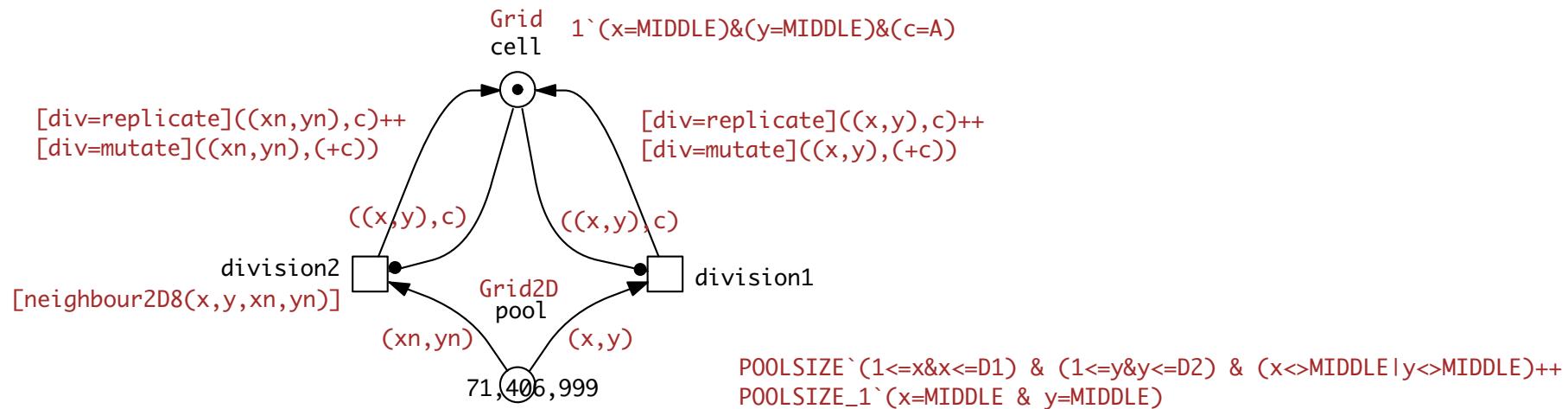
**colorset Grid = product with Grid2D x Phenotype;**



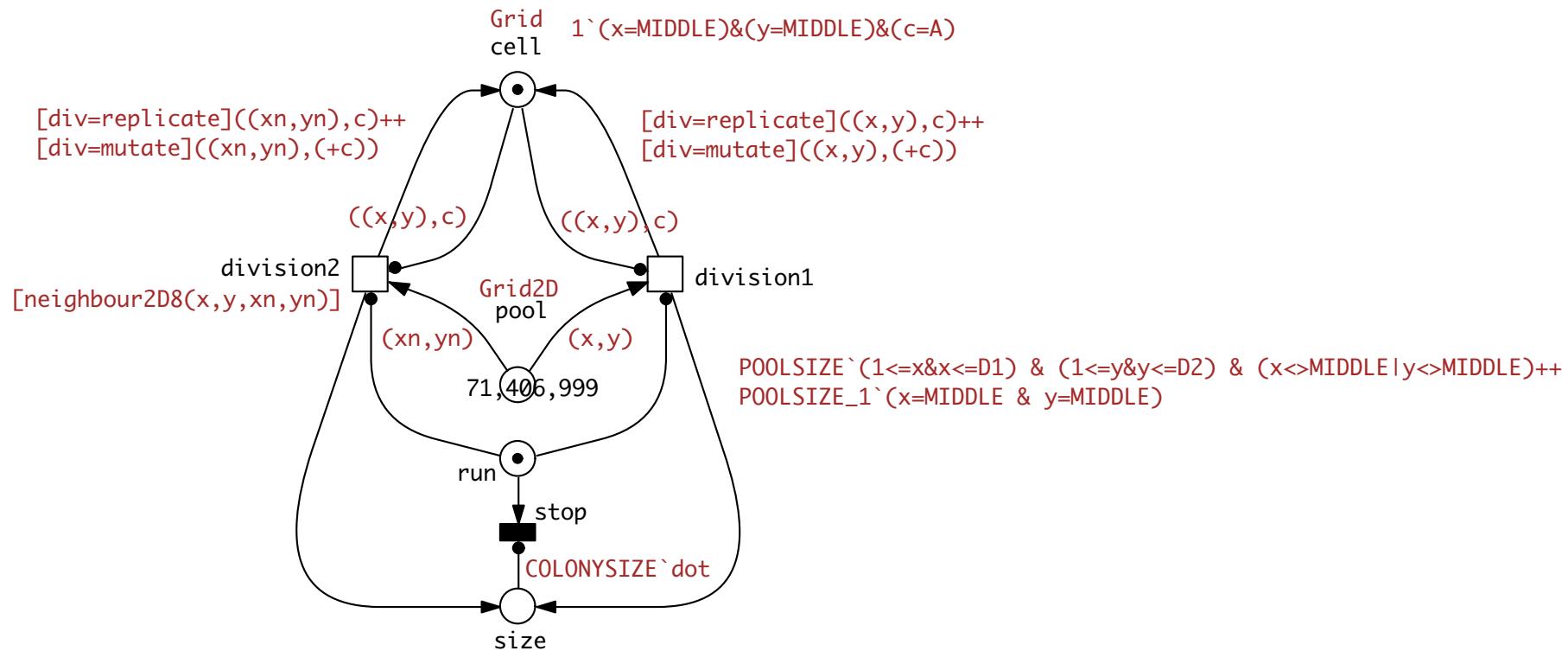
## Ex5: CELL COLONIES, CONTROLLING THICKNESS

PN & BioModel Engineering

**colorset Grid = product with Grid2D x Phenotype;**



**colorset Grid = product with Grid2D x Phenotype;**



### □ model assumptions

- > “If phase variation occurs, the progeny consists of one A and one B”  
(Saunders 2003)
- > It is always the mutant who goes to a neighbouring position, if any.
- > constant biofilm thickness (so far)

### □ colony size - 24 h

- > 25 generations:  $33.5 E+06$
- > 26 generations:  $67 E+06$
- > COLONYSIZE = 70,000,000

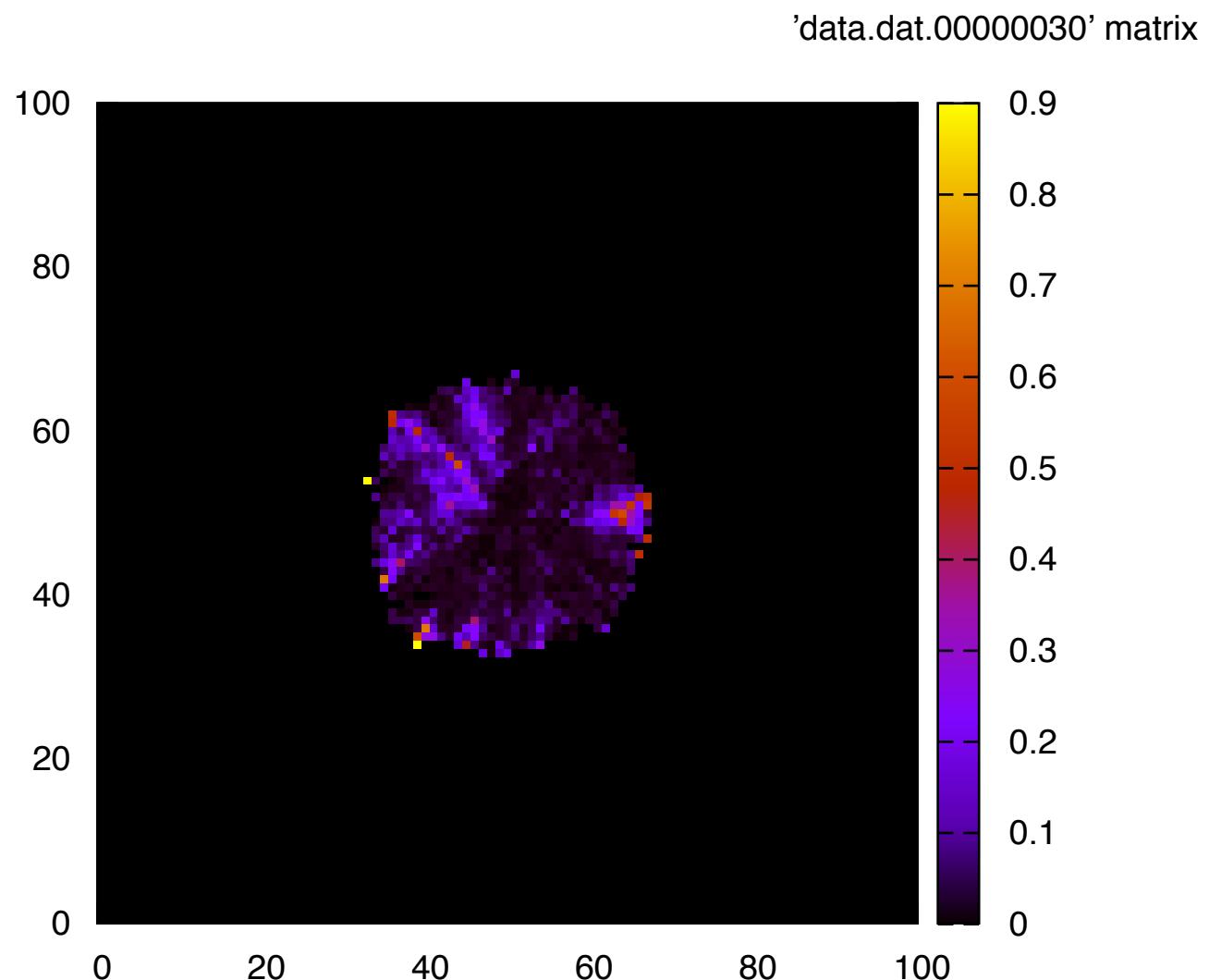
### □ grid size

- > 61 x 61 grid:  $11,163 P / 131,044 T$ ; unfolding: 152 sec;
- > 101 x 101 grid:  $30,603 P / 362,404 T$ ; unfolding: 9 min;  
-> runtime 1 stoch. simulation: 35-40 minutes

## **. . . SOME EXPERIMENTS**

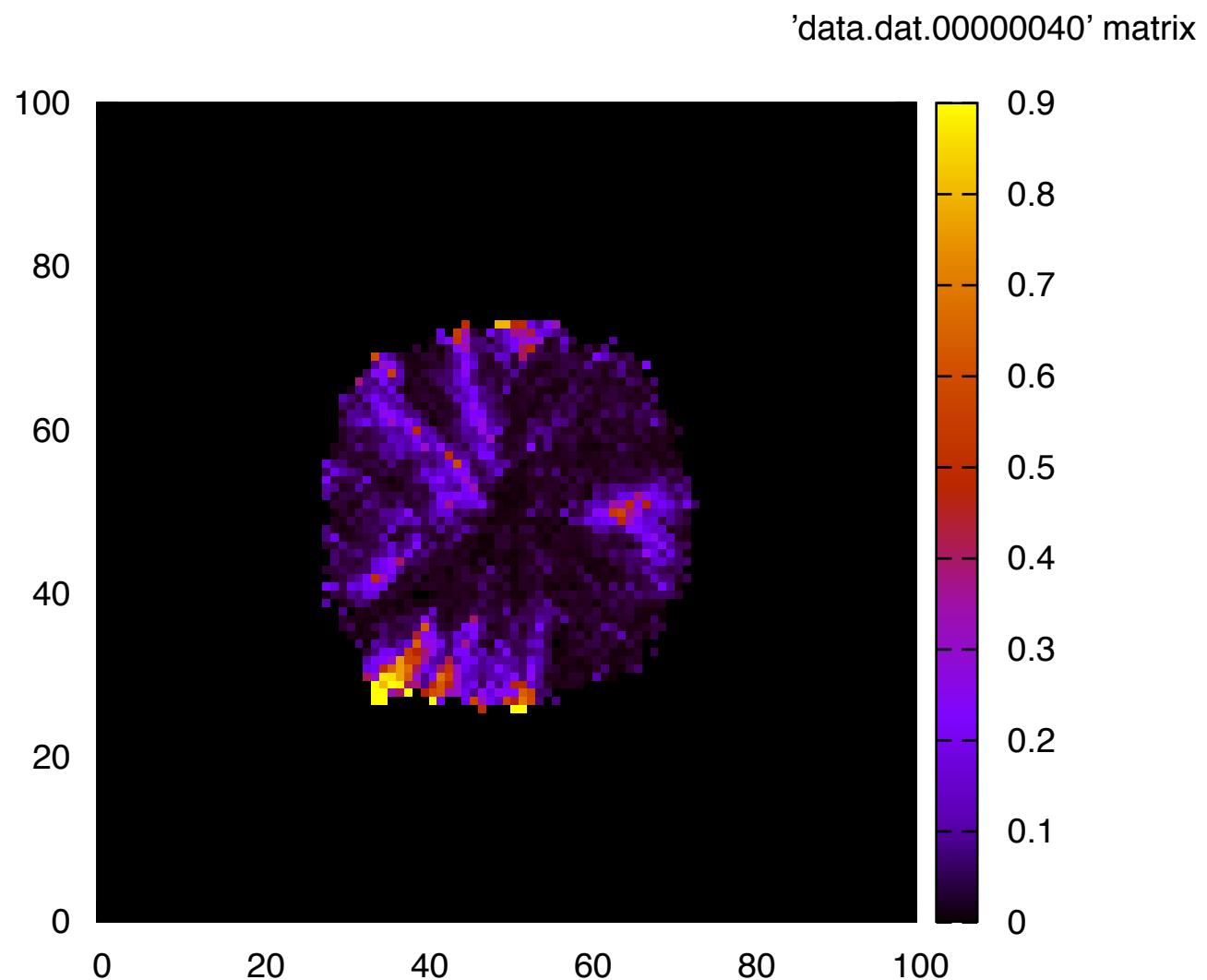
## Ex5: 2D - TRACE 1 (HIGH, F=1)

PN & BioModel Engineering



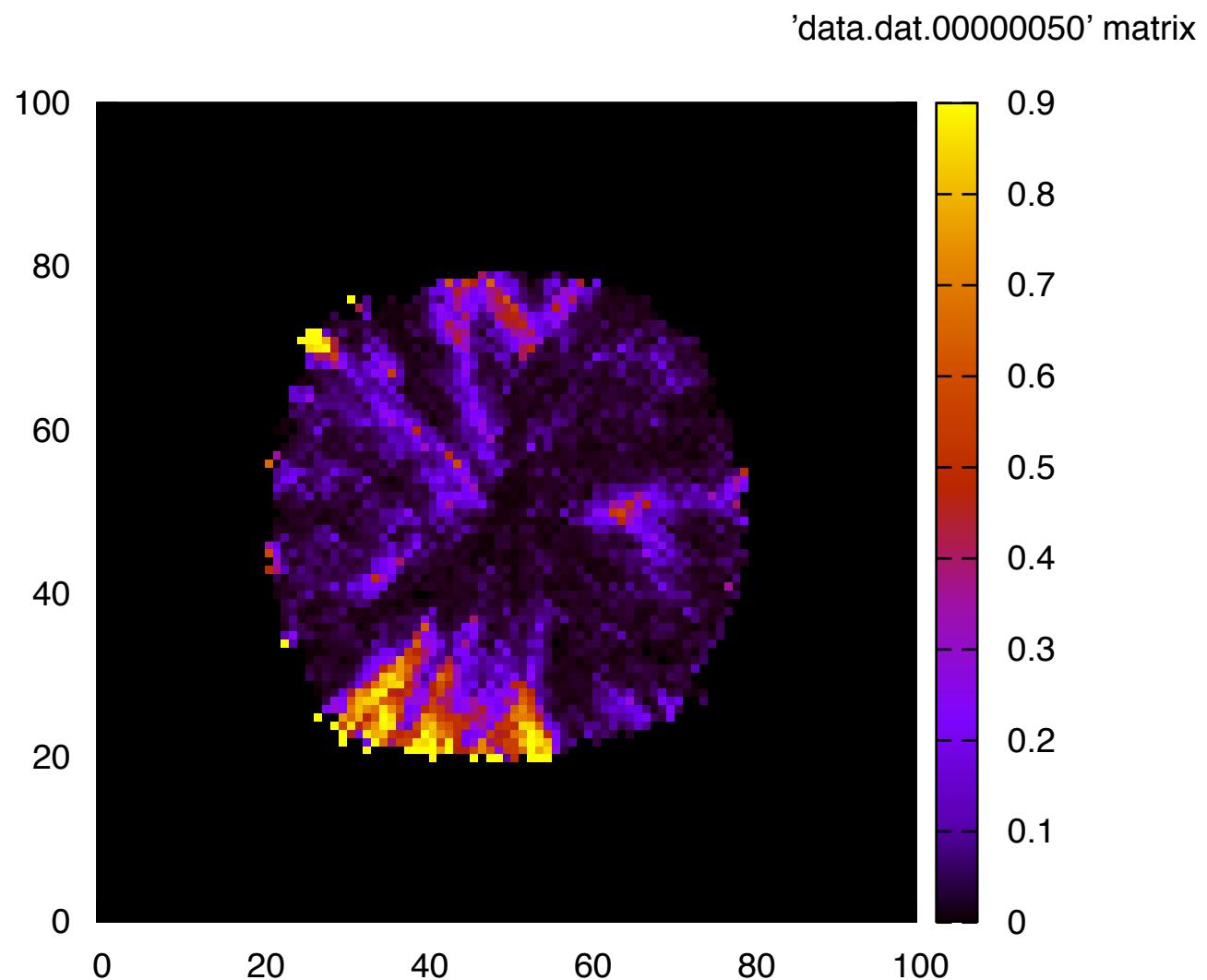
## Ex5: 2D - TRACE 1 (HIGH, F=1)

PN & BioModel Engineering



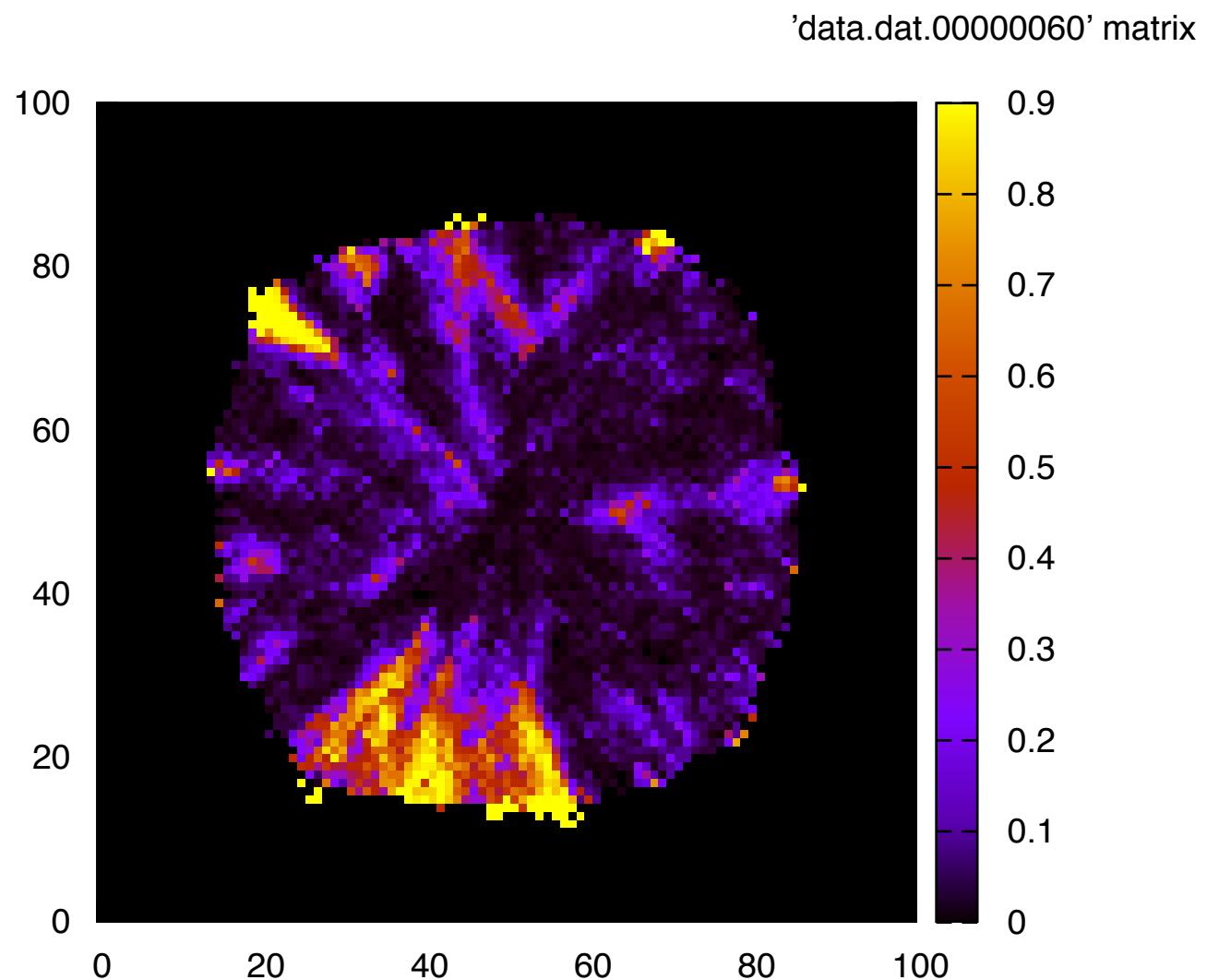
## Ex5: 2D - TRACE 1 (HIGH, F=1)

PN & BioModel Engineering



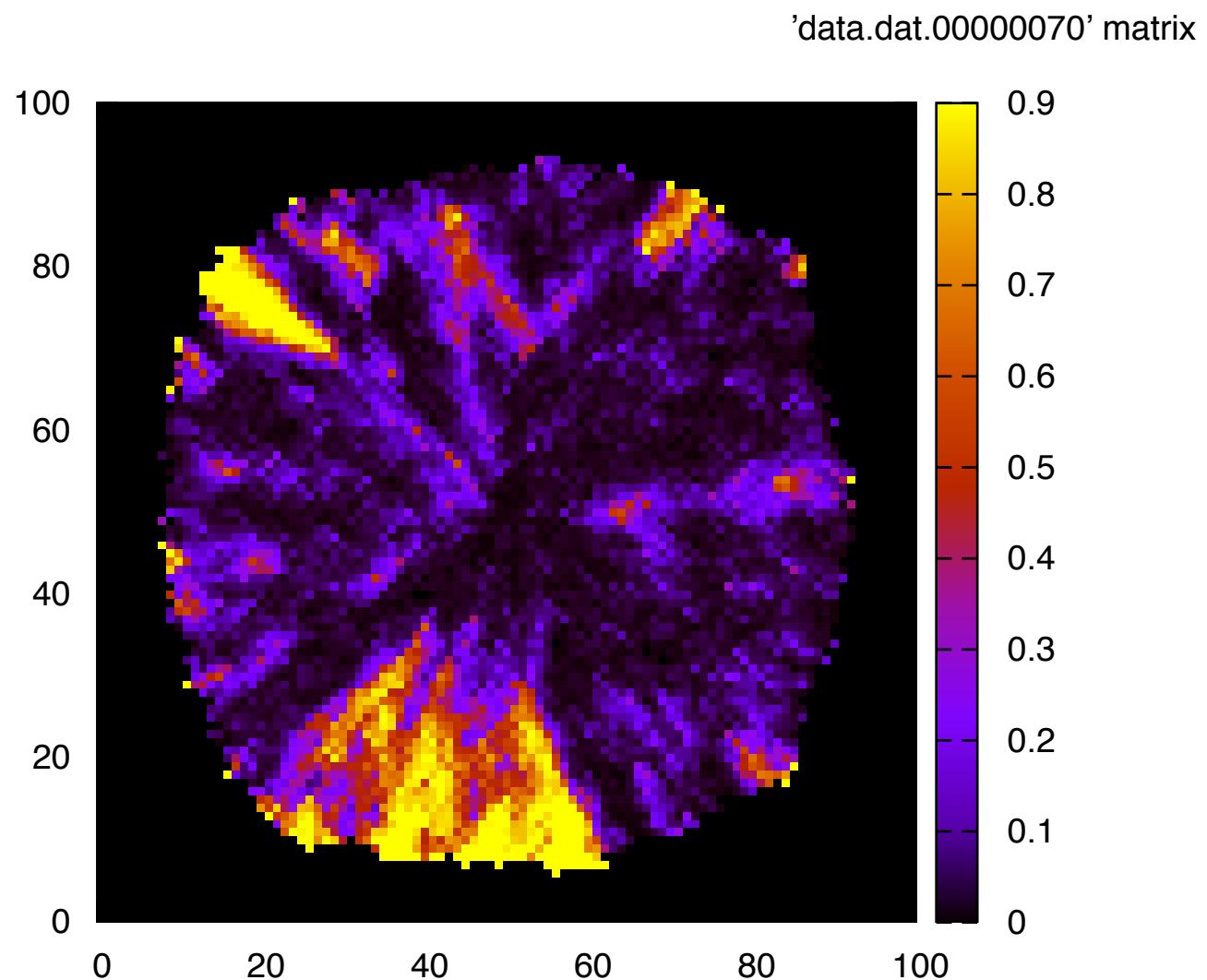
## Ex5: 2D - TRACE 1 (HIGH, F=1)

PN & BioModel Engineering



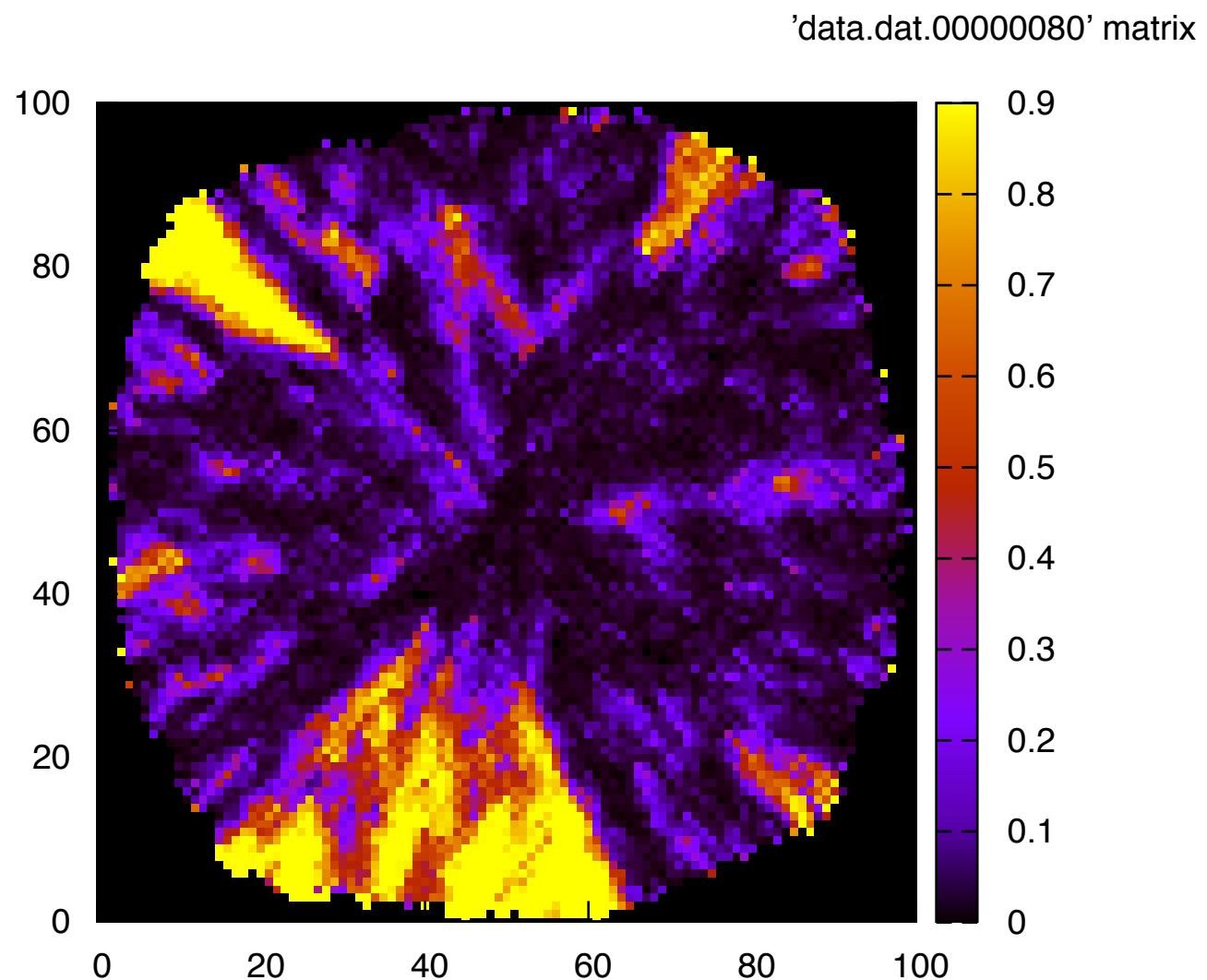
## Ex5: 2D - TRACE 1 (HIGH, F=1)

PN & BioModel Engineering



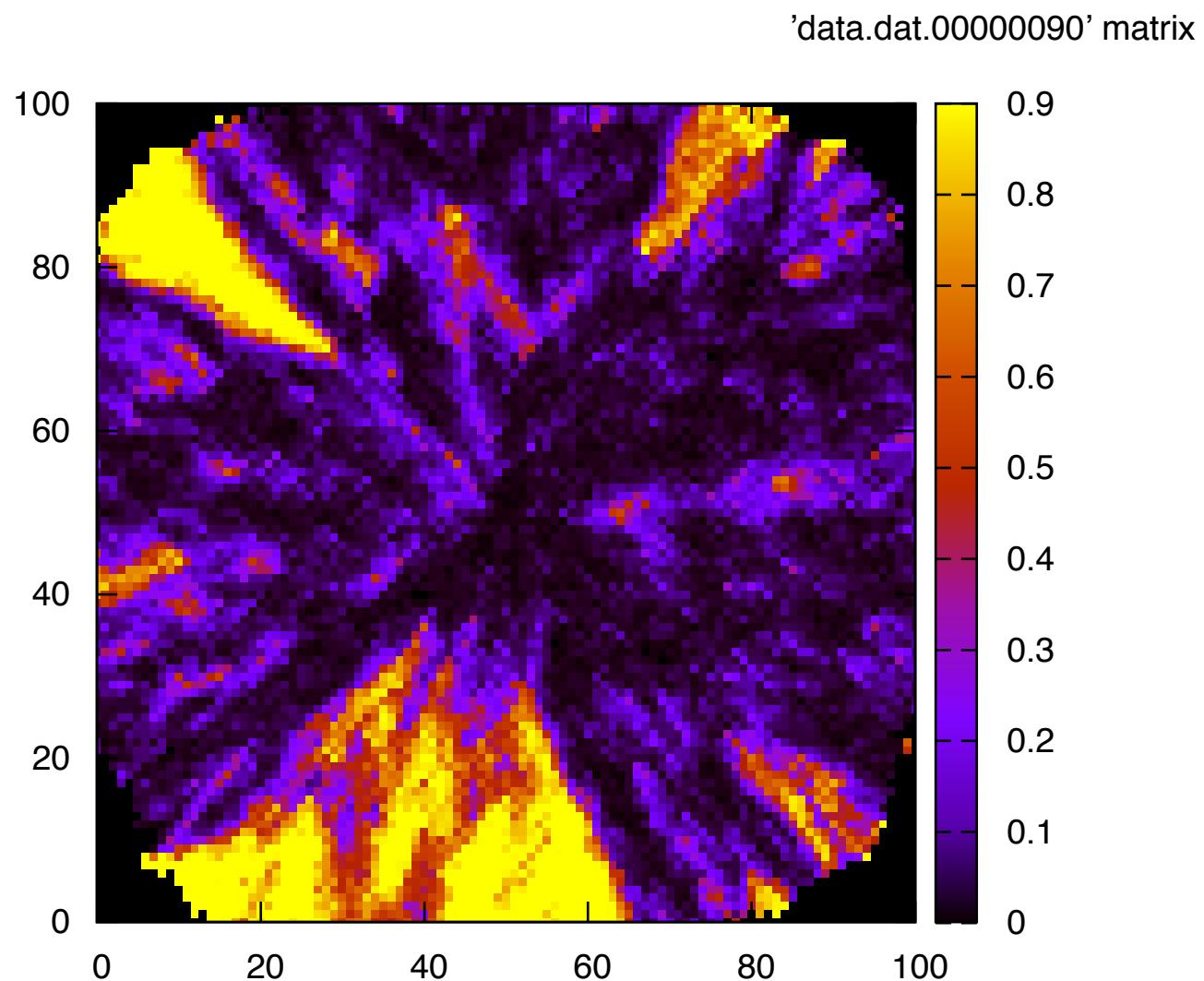
## Ex5: 2D - TRACE 1 (HIGH, F=1)

PN & BioModel Engineering



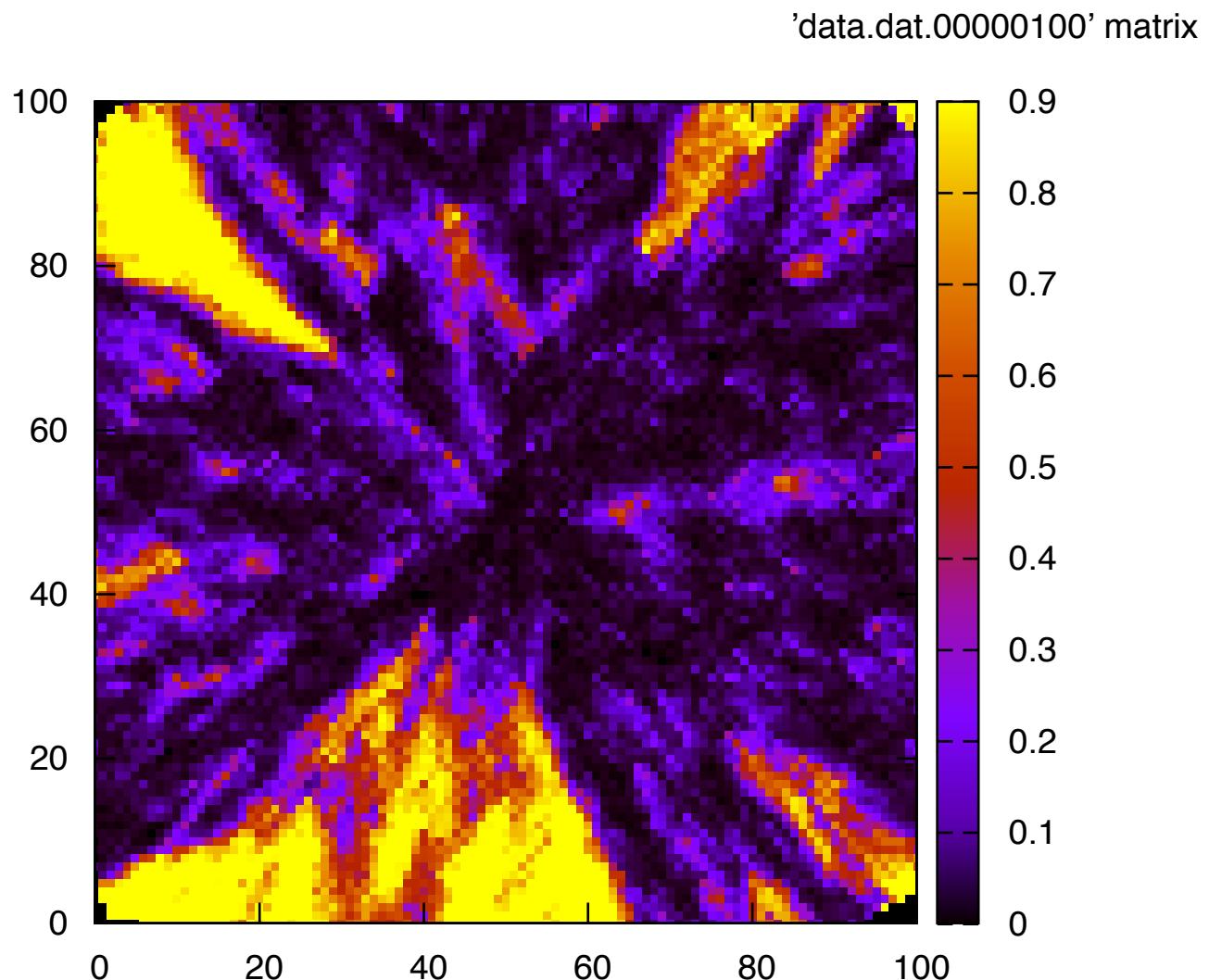
## Ex5: 2D - TRACE 1 (HIGH, F=1)

PN & BioModel Engineering



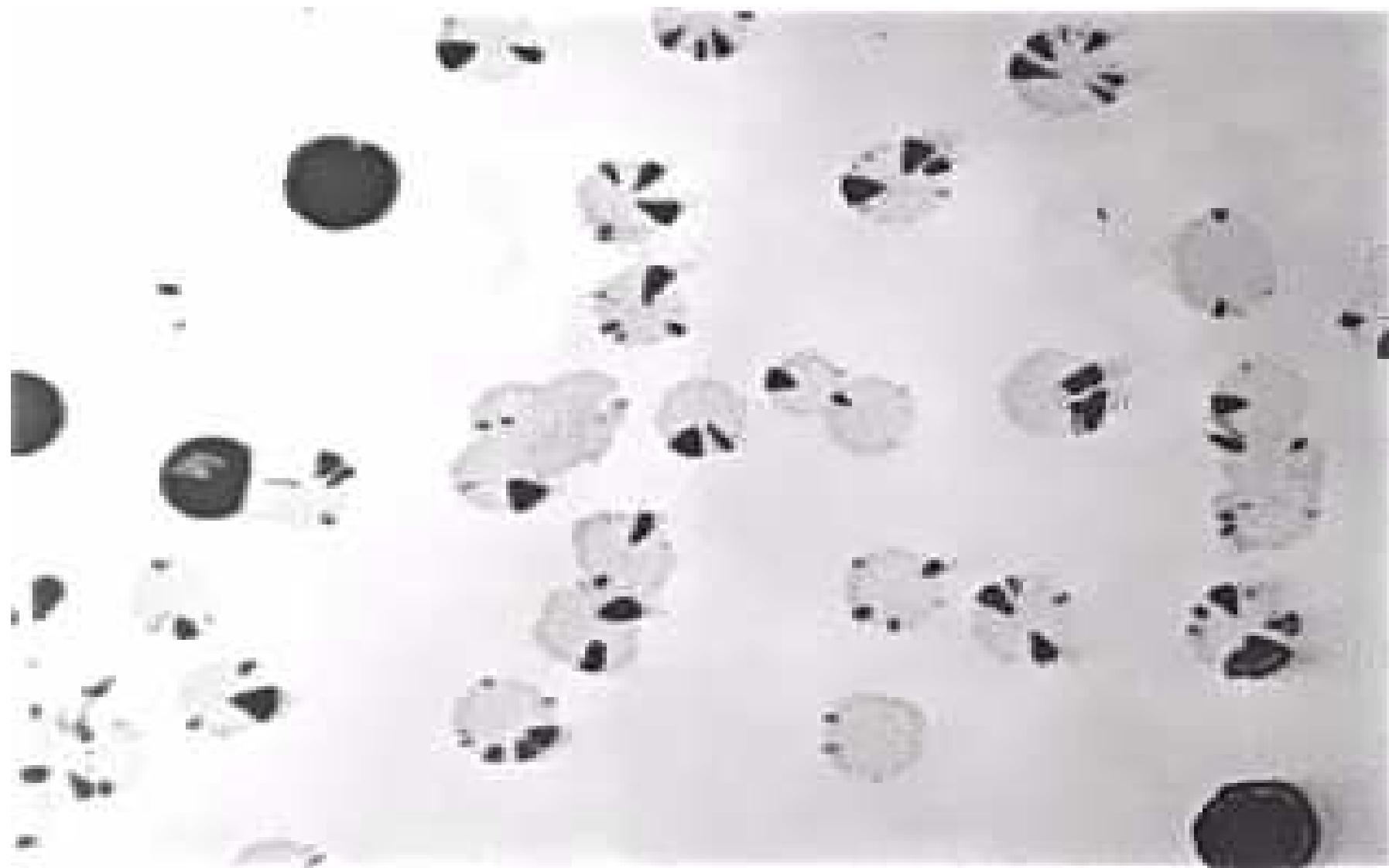
## Ex5: 2D - TRACE 1 (HIGH, F=1)

PN & BioModel Engineering



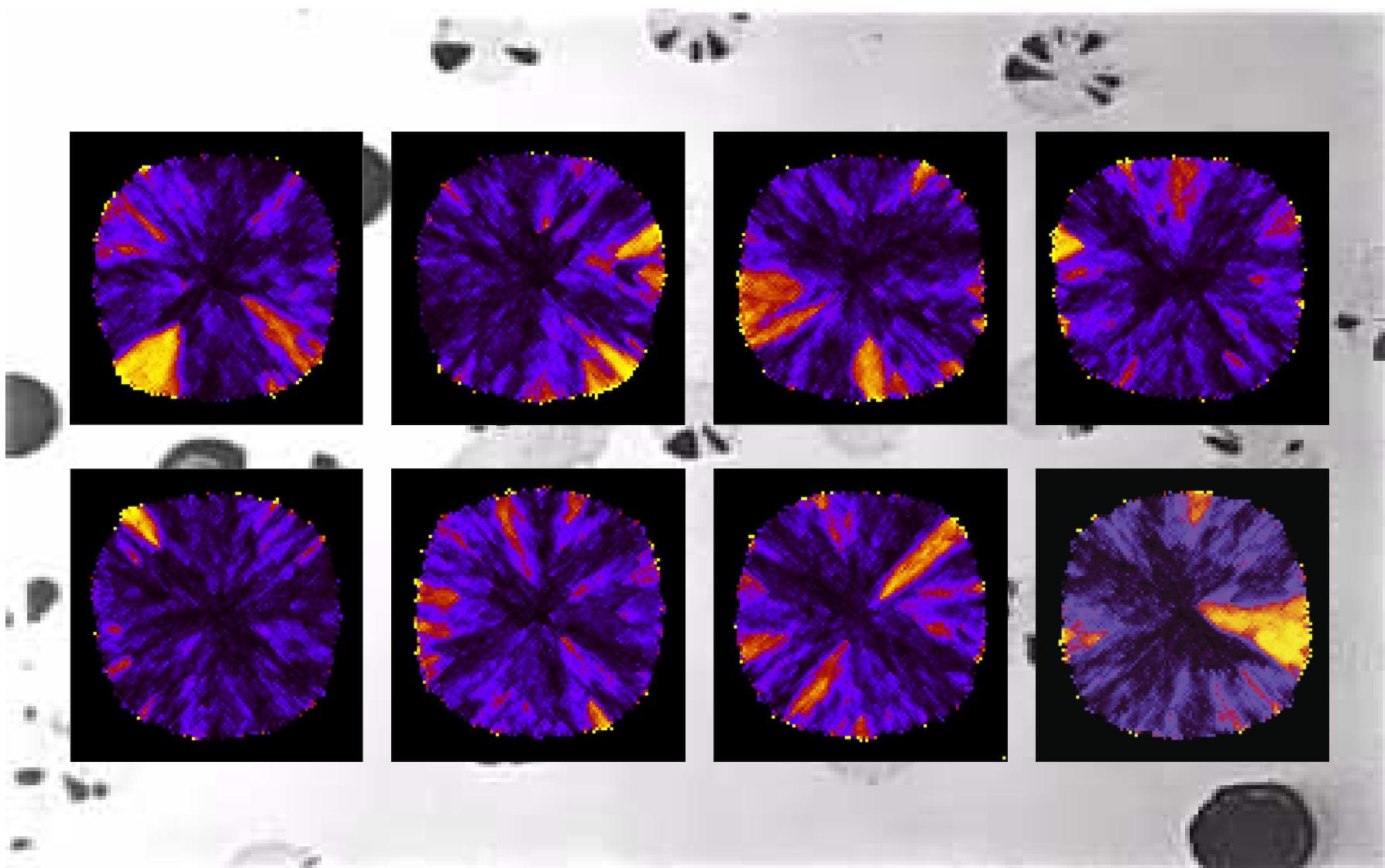
## Ex5: SOME FINAL STATES (HIGH, F=1)

PN & BioModel Engineering



## Ex5: SOME FINAL STATES (HIGH, F=1)

PN & BioModel Engineering

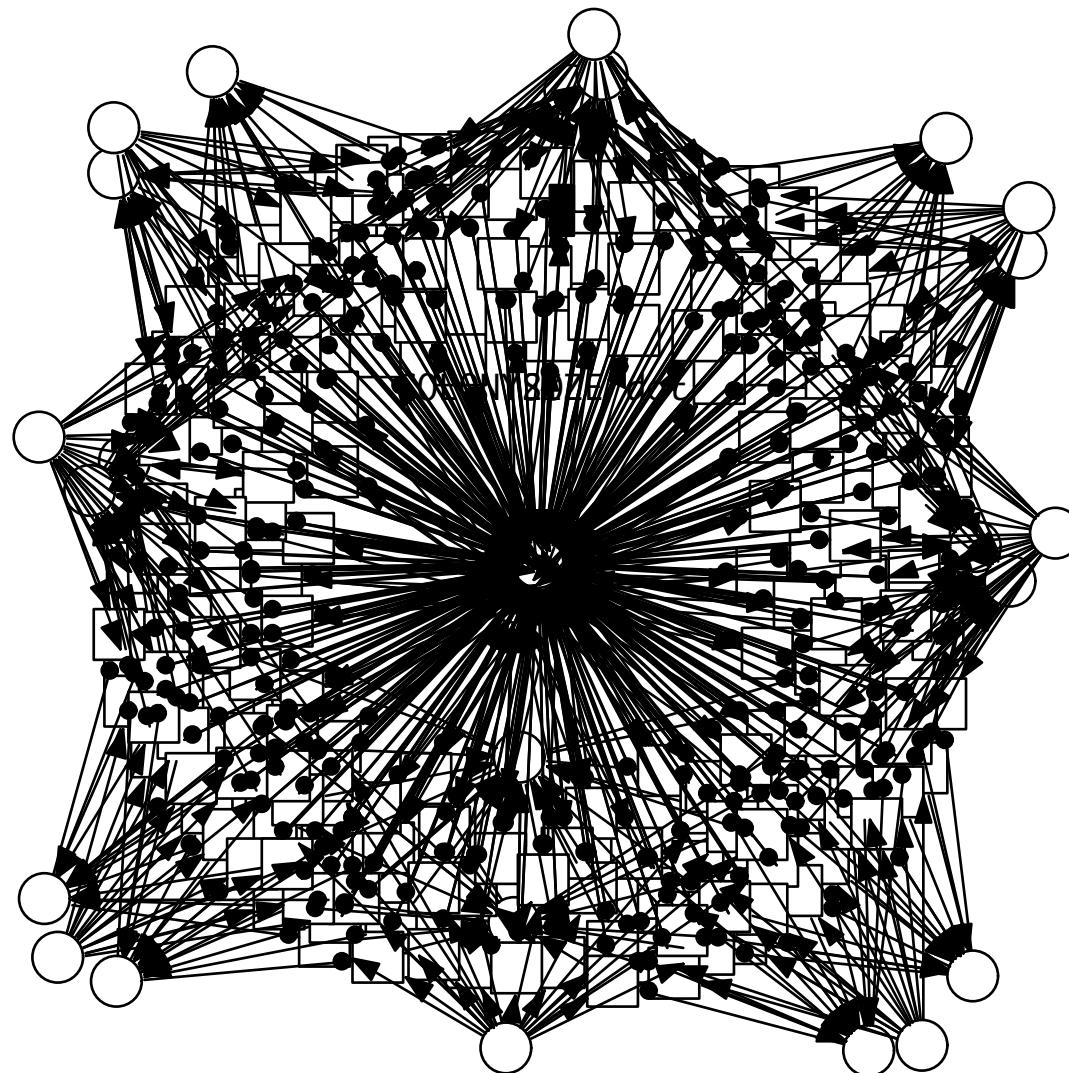


- **the spatial modelling principle can be equally applied to all paradigms**
  - > *qualitative, stochastic, continuous, and hybrid*
  - > *model transformations preserve all spatial attributes*
- **all space-related information is encoded in colour**
  - > *reuse in other models*
- **changing the notion of space**
  - > *adapt colour-related definitions*
  - > *net structure itself needs not to be touched.*
- **use of a priori finitely discretised space preserves model analysability**

----
- **automatic unfolding**
  - > *resue of all analysis and simulation techniques of uncoloured Petri nets*

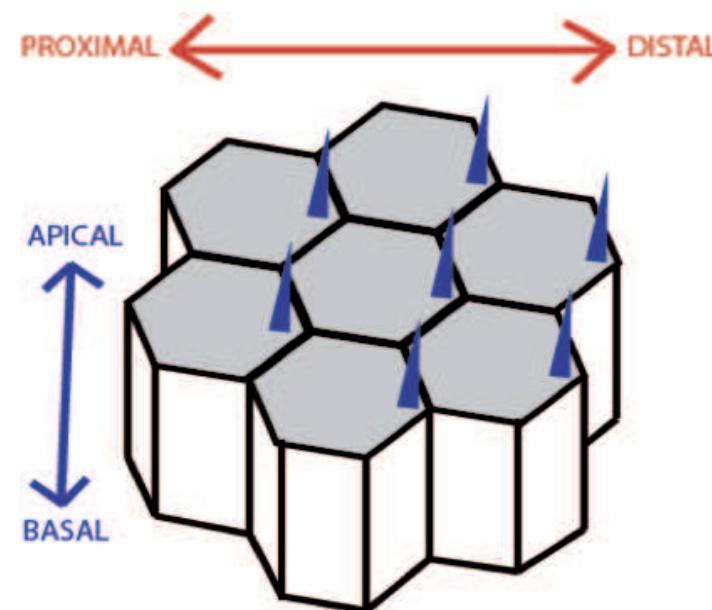
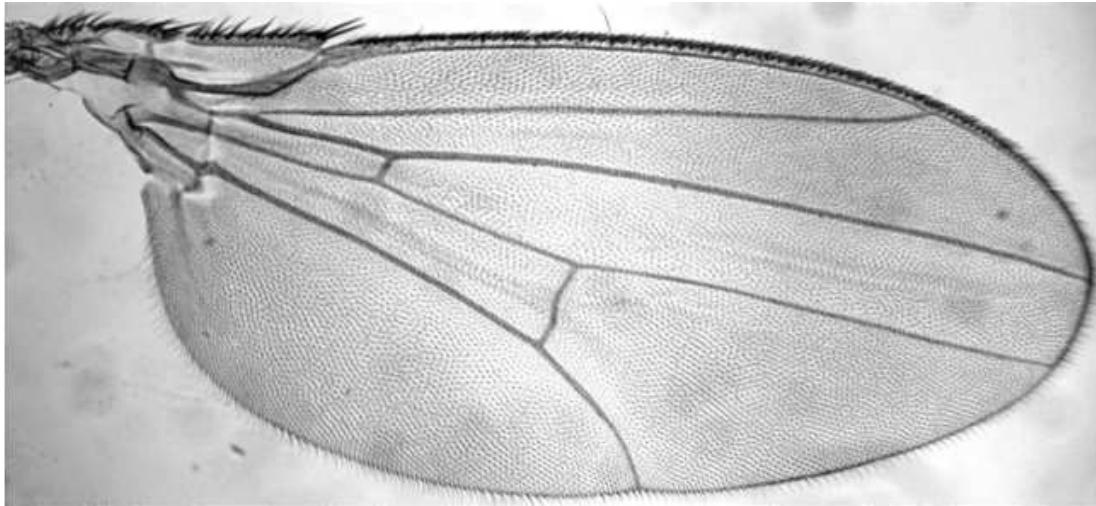
# PHASE VARIATION, PLAIN MODEL (3x3)

PN & BioModel Engineering



## Ex6 - PLANAR CELL POLARITY

PN & BioModel Engineering

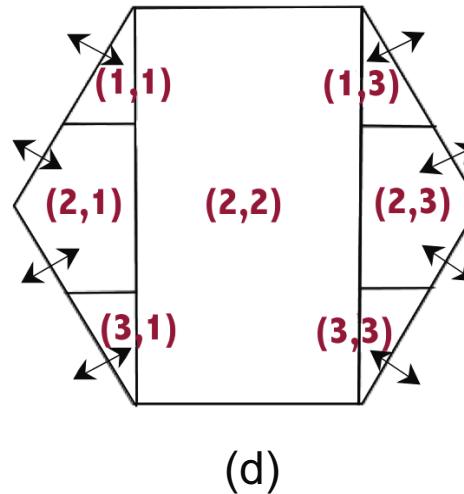
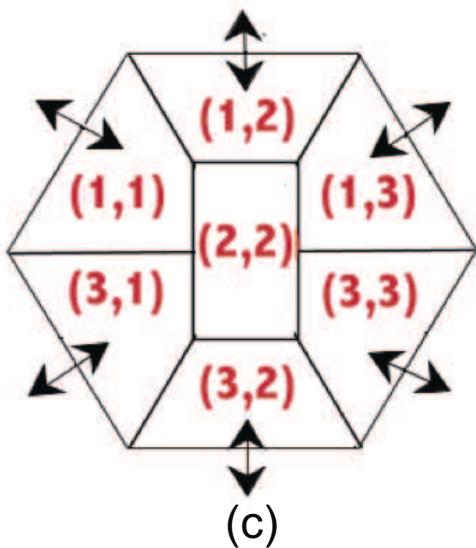
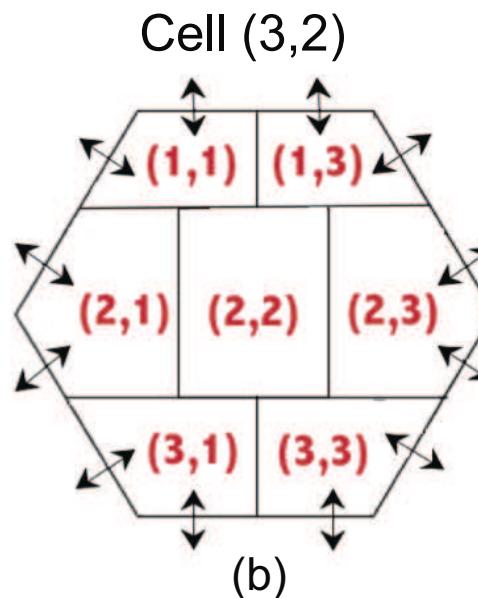
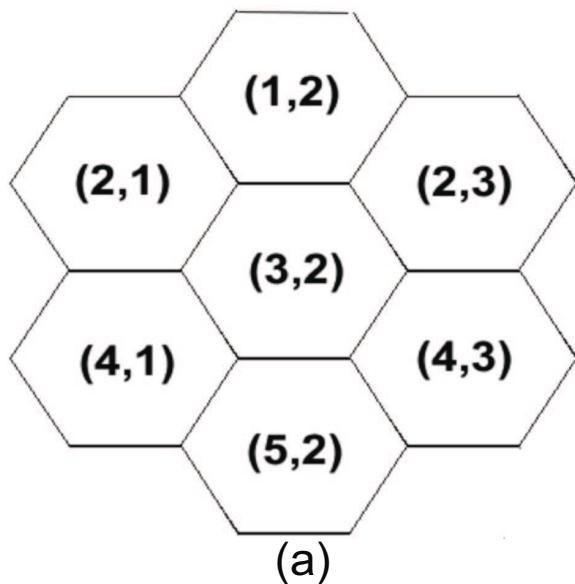


[BioPPN 2011]  
[CMSB 2011]



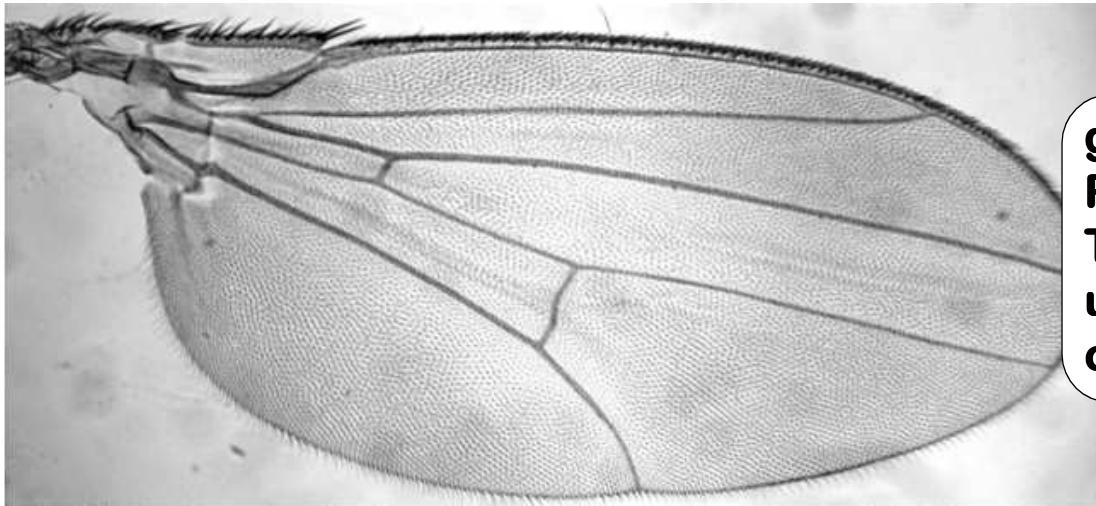
## Ex6 - PLANAR CELL POLARITY

PN & BioModel Engineering

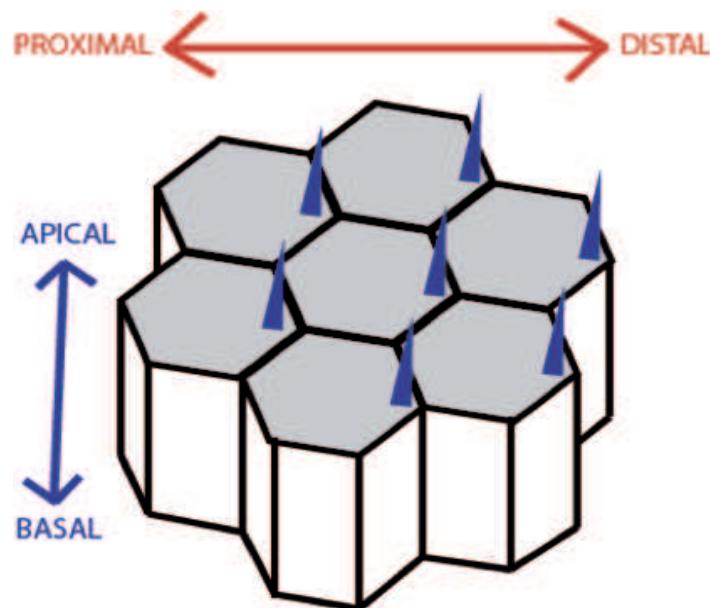


## Ex6 - PLANAR CELL POLARITY

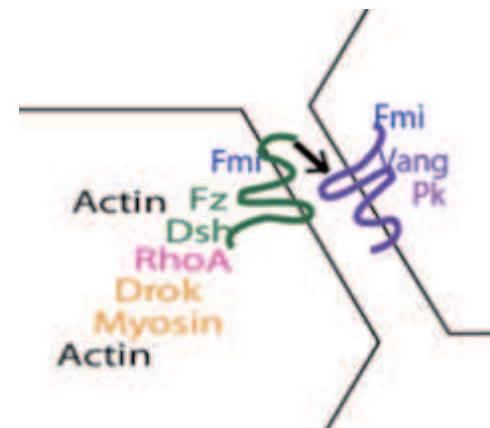
PN & BioModel Engineering



grid size: 40 x 40  
PLACES: 164,000  
TRANSITIONS: 229,686  
unfolding: 2 min  
cont. simulation: 2 h

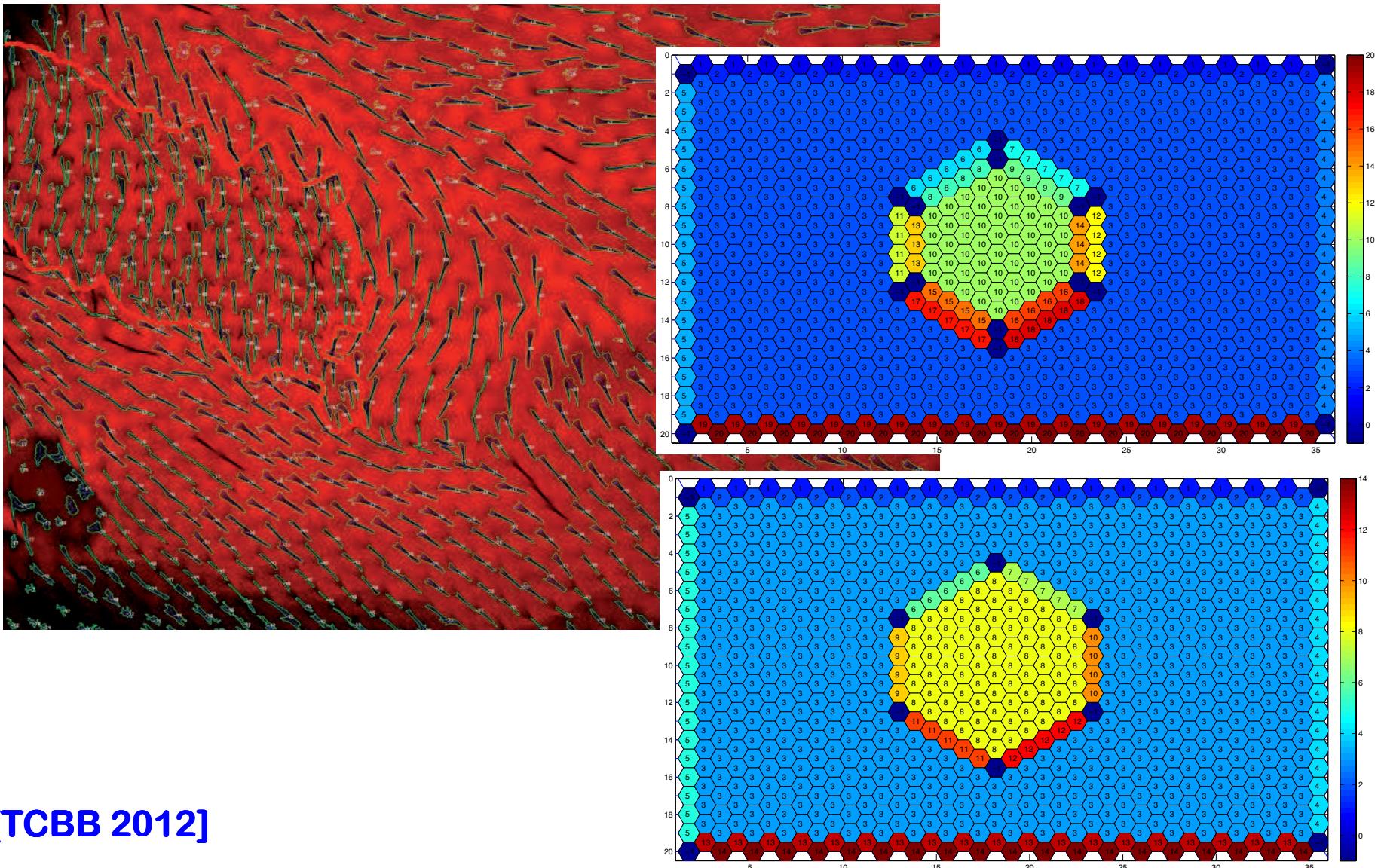


[BioPPN 2011]  
[CMSB 2011]



## Ex6 - PLANAR CELL POLARITY

PN & BioModel Engineering



[TCBB 2012]

# **SUMMARY & OUTLOOK**

## □ SNOOPY

- > *modelling and animation/simulation of hierarchical graphs,*  
e.g. (extended) fault trees,  
various Petri net classes, e.g. QPN, XQPN, SPN, XSPN, CPN, TPN,  
....,  
*free style graphs*

## □ CHARLIE

- > QPN, XQPN, Time/Timed Petri nets (TPN)
- > mostly standard analysis techniques of Petri net theory

## □ MARCIE

- > XQPN, SPN, XSPN, SRN
- > *symbolic and simulative model checking*

## □ Patty

- > *animation via web browser*

- SNOOPY

- > *modelling and animation/simulation of hierarchical graphs,*  
e.g. (extended) fault trees,  
various Petri net classes, e.g. QPN, XQPN, SPN, XSPN, CPN, TPN,



- SBML import/export

- > QPN, XQPN, Time/Timed Petri nets (TPN)
- > mostly standard analysis techniques of Petri net theory

- MARCIE

- > XQPN, SPN, XSPN, SRN
- > *symbolic and simulative model checking*

- Patty

- > *animation via web browser*

**EXPORT TO MATLAB AND  
MANY OTHER TOOLS**

## □ representation of bio networks by Petri nets

- > *partial order representation*
- > *formal semantics*
- > *unifying view*
- > *better comprehension*
- > *sound analysis techniques*

## □ purposes

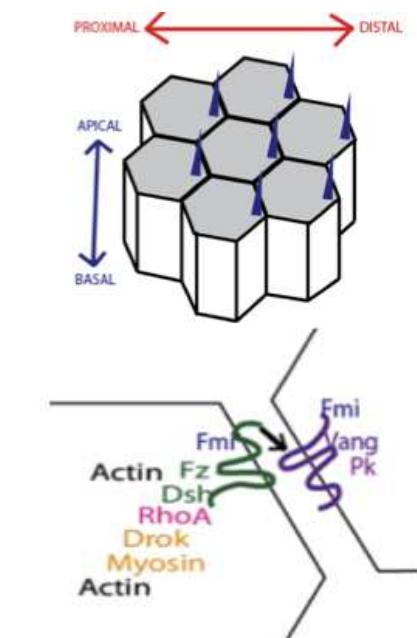
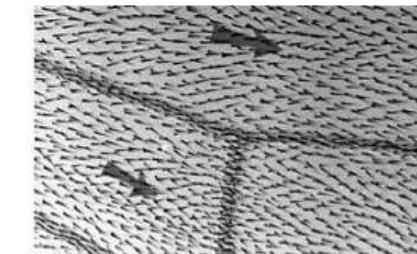
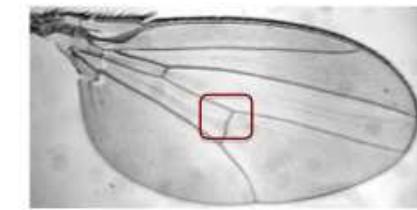
- > *animation*
- > *model validation against consistency criteria*
- > *qualitative / quantitative behaviour prediction*
- > *to experience the model*
- > *to increase confidence*
- > *experiment design, new insights*

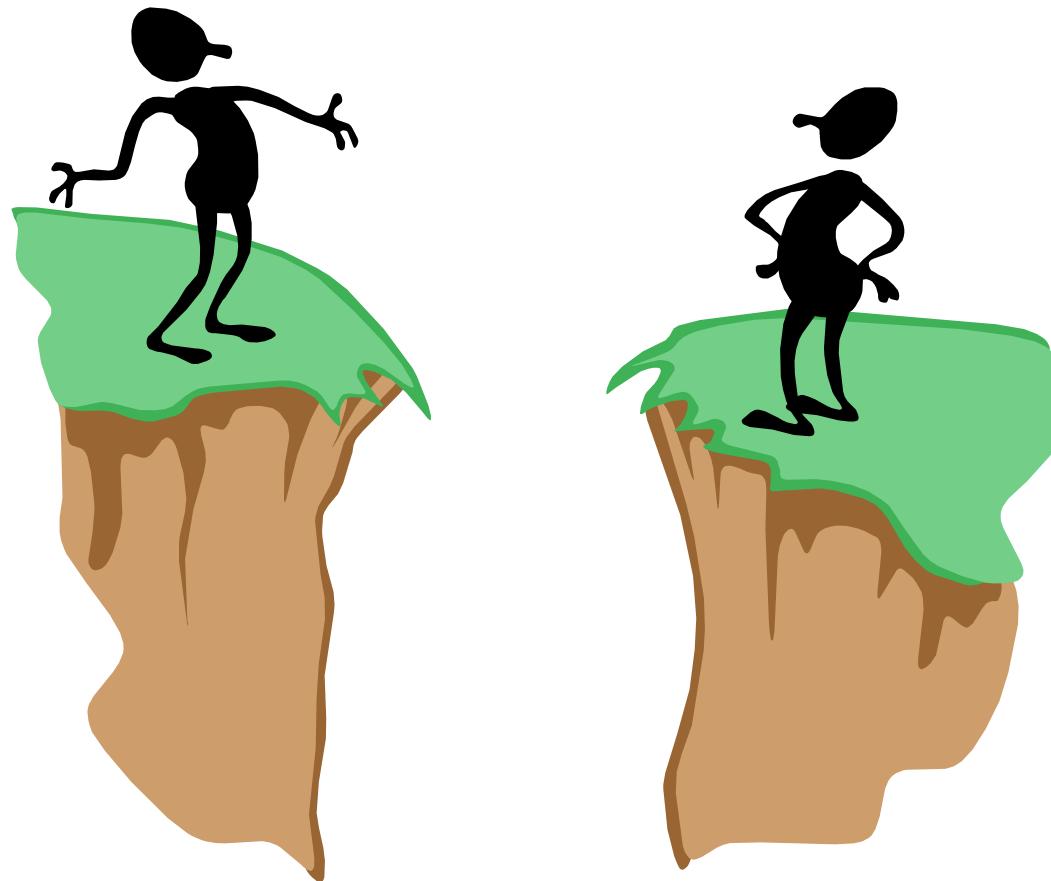
## □ step-wise model development

- > *qualitative model*
- > *discrete quantitative model*
- > *continuous quantitative model*
- > *locality and space*
- > *discrete Petri nets*
- > *stochastic Petri nets*
- > *continuous Petri nets = ODEs, hybrid models*
- > *coloured Petri nets*

- **hierarchical organisation of components -> model variables**  
*genes, molecules, organelles, cells, tissues, organs, organisms*
- **functionality of atomic events**  
*chemical reactions with/out stoichiometry, conformational change, transport, . . .*
- **time**  
*qualitative versus quantitative models*
- **individual vs population behaviour**      **-> hybrid**
- **(hierarchical) space**
- **observables**
- **shape and volume of components**
- **biosystem development**

- repetition of components
- variation of components
- organisation of components
- communication between components
- mobility / motility
- replication / deletion of components
- hierarchical organisation of components
- dynamic grid size
- irregular / semi-regular organisation of components





THANKS !

**[HTTP://WWW-DSSZ.INFORMATIK.TU-COTTBUS.DE](http://www-dssz.informatik.tu-cottbus.de)**

# APPENDIX



**C. A. PETRI, NOVEMBER 2006**



C. A. PETRI

INTERPRETATIONS OF NET THEORY

GMD, INTERNAL REPORT 75-07, 2ND IMPROVED EDITION 1976

places	transitions
state elements	transitional elements
conditions	events/facts
statements	dependencies
model domains	specifications
chemical compounds	chemical reactions
open one-point sets	closed one-point sets
channels	offices
languages	translators
products	production activities

[Peterson 1981]

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Chap. 3 Modeling with Petri Nets

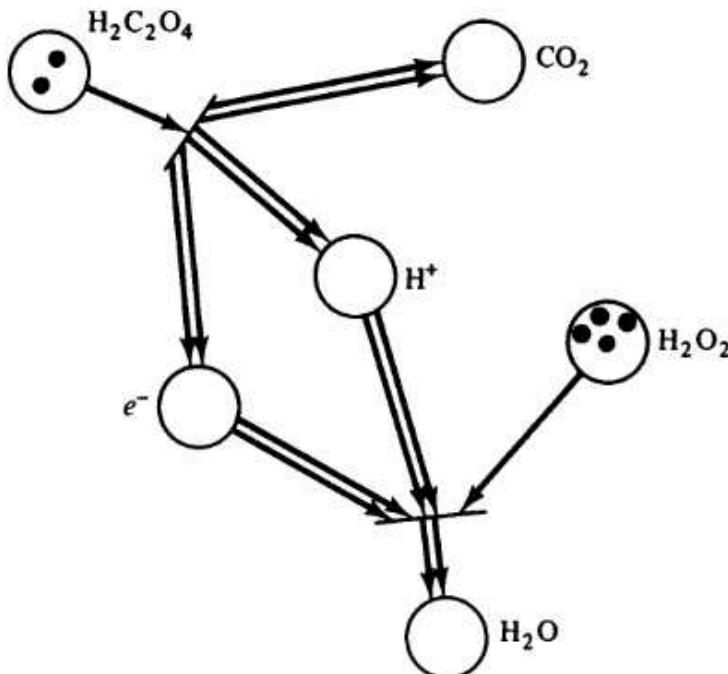
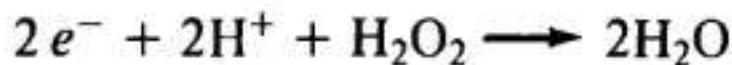
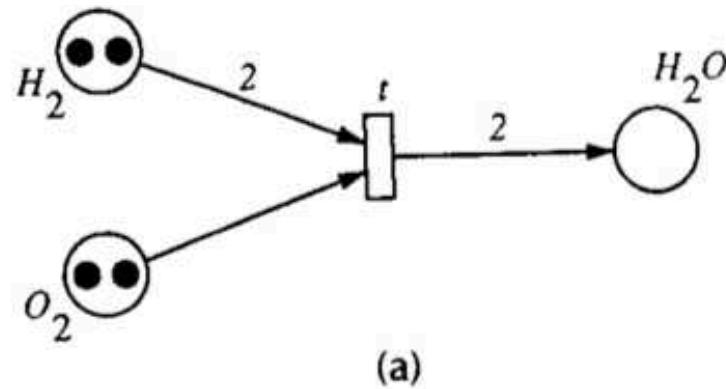


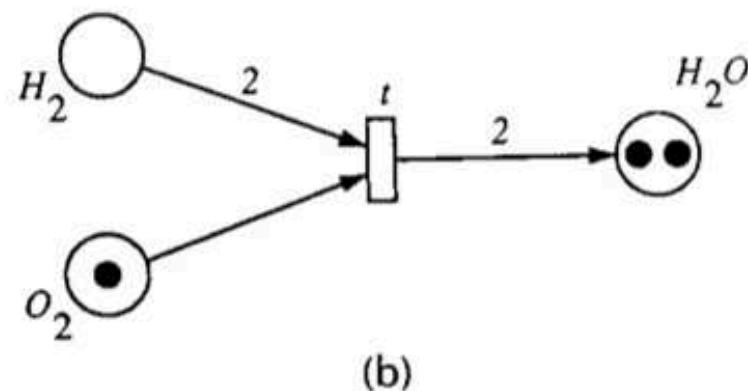
Figure 3.38 A Petri net representing the oxidation-reduction of oxalic acid and hydrogen peroxide into carbon dioxide and water.



[Murata 1989]



(a)



(b)

**Fig. 1.** Example 1: An illustration of a transition (firing) rule:  
(a) The marking before firing the enabled transition  $t$ . (b) The marking after firing  $t$ , where  $t$  is disabled.

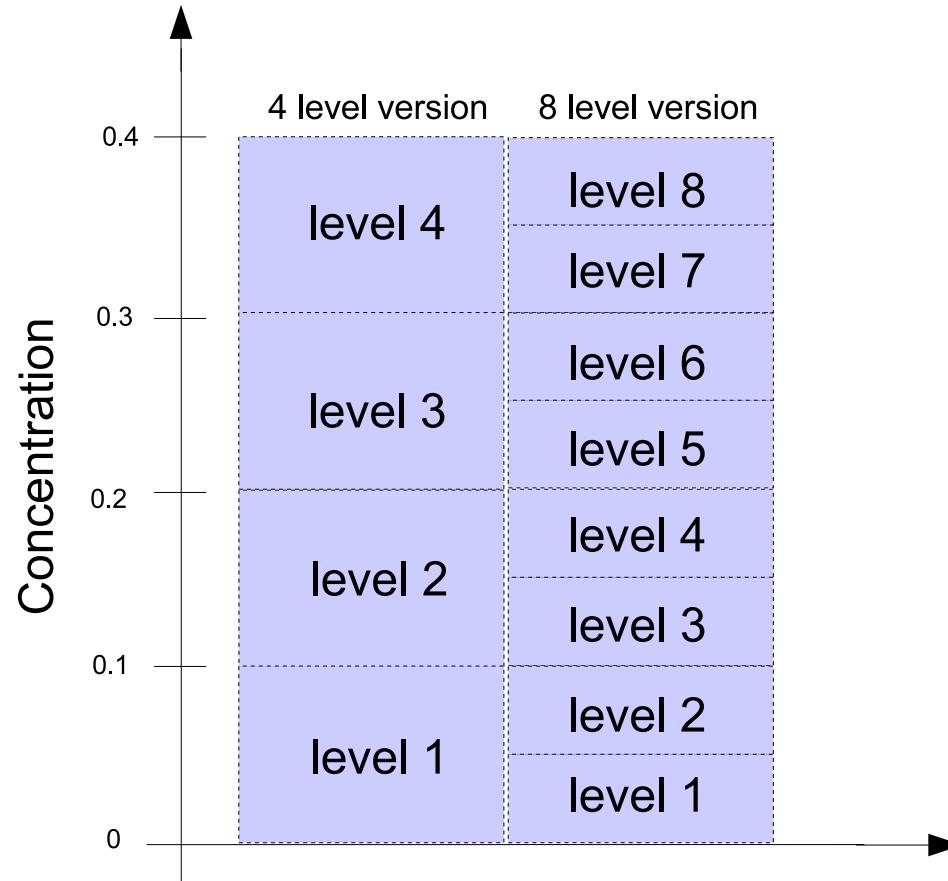
- **transitions  $r_i$  get a stochastic waiting time**
  - > *exponential distribution with parameter lambda*
- **state-dependent lambda defined by rate function  $v_i(r_i)$** 
  - > *any arithmetic function including  
the transition's pre-places as integer variables and  
user-defined real-valued parameters*
  - > *modifier arcs*
  - > *popular kinetics:*
    - mass-action semantics, level semantics*
- **semantics: Continuous Time Markov Chain (CTMC)**
  - > *reachability graph + state transition rates*
- **analysis**
  - > *standard Markov analysis techniques: transient, steady state*
  - > *stochastic simulation algorithms (SSA), e.g. Gillespie's SSA*

- mass-action semantics

$$h_t := \textcolor{red}{c}_t \cdot \prod_{p \in \bullet t} \binom{m(p)}{f(p, t)}$$

- level semantics

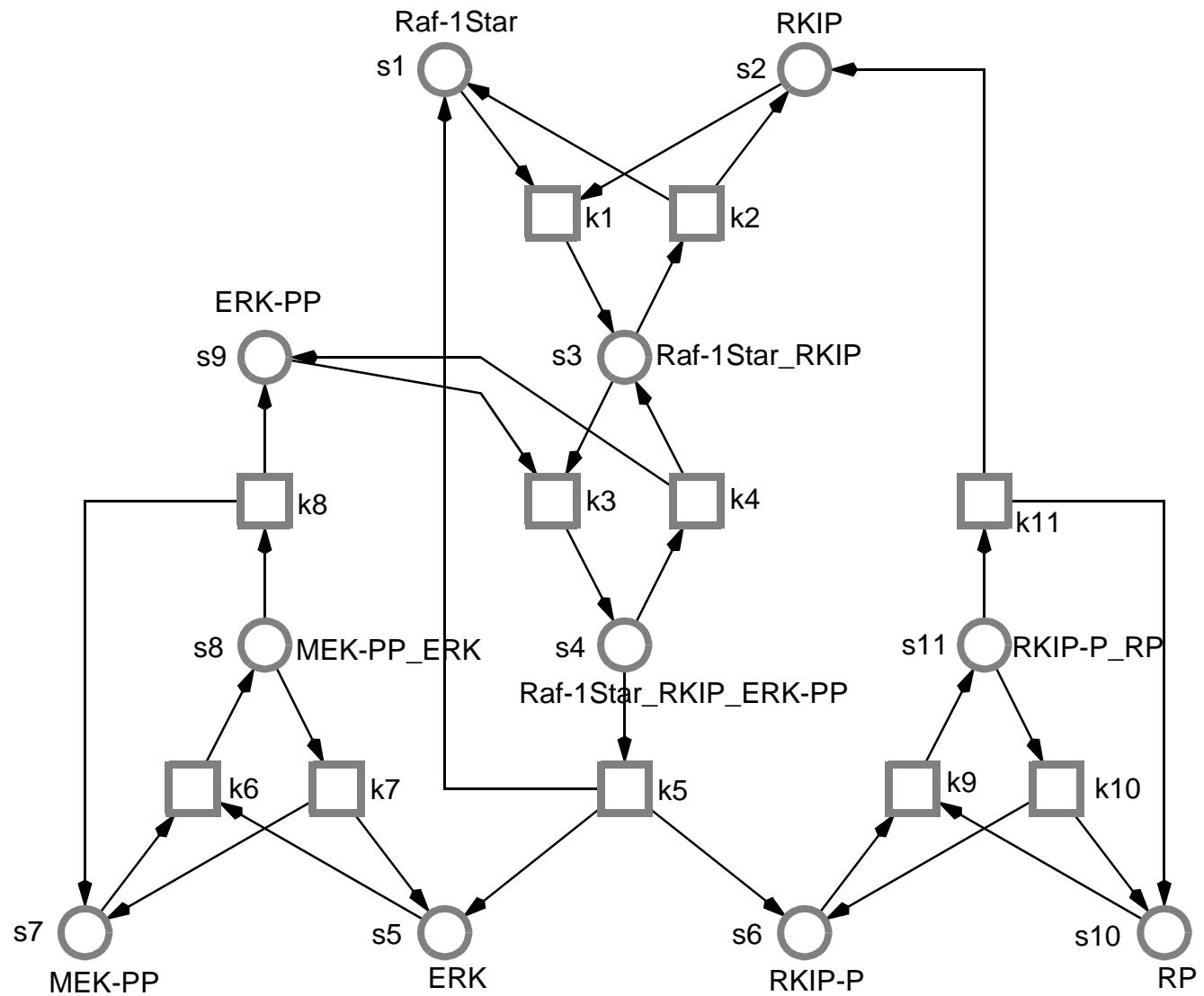
$$h_t := \textcolor{red}{k}_t \cdot N \cdot \prod_{p \in \bullet t} \left( \frac{m(p)}{N} \right)$$



- **transitions  $r_i$  fire continuously**
  
- **rate functions  $v_i(r_i)$** 
  - > *any arithmetic function including  
the transition's pre-places as real-valued variables and  
user-defined real-valued parameters*
  
- **real-valued tokens**
  - > *concentrations*
  
- **semantics: set of Ordinary Differential Equations (ODEs)**
  - > *uniquely defined, but not vice versa*
  - > [SOLIMAN, HEINER 2010]
  - > *typically non-linear*
  
- **simulation (numerical integration)**
  - > *stiff / unstiff solvers*

# CONTINUOUS PETRI NET DEFINES ODEs

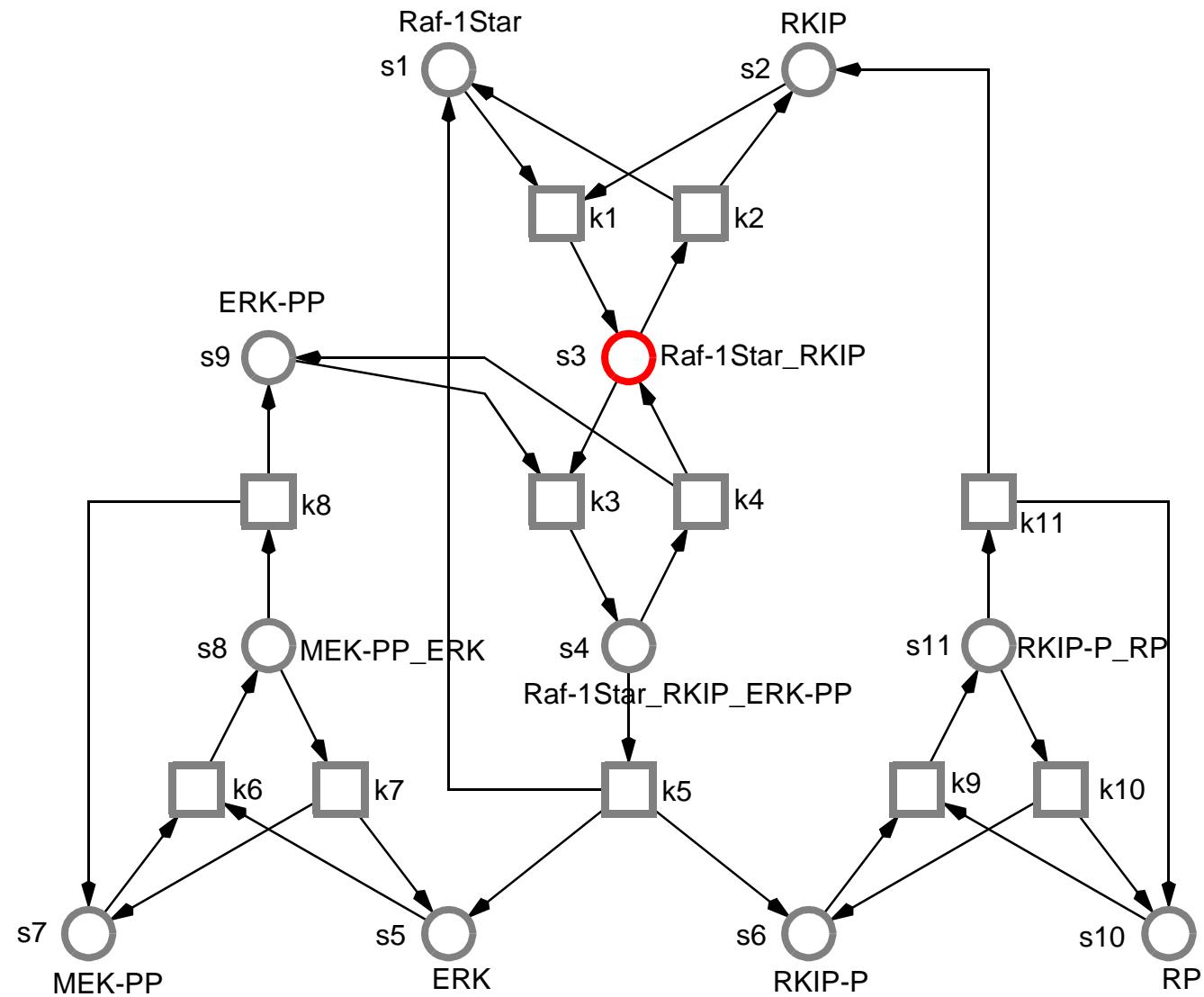
PN & BioModel Engineering



# CONTINUOUS PETRI NET DEFINES ODEs

PN & BioModel Engineering

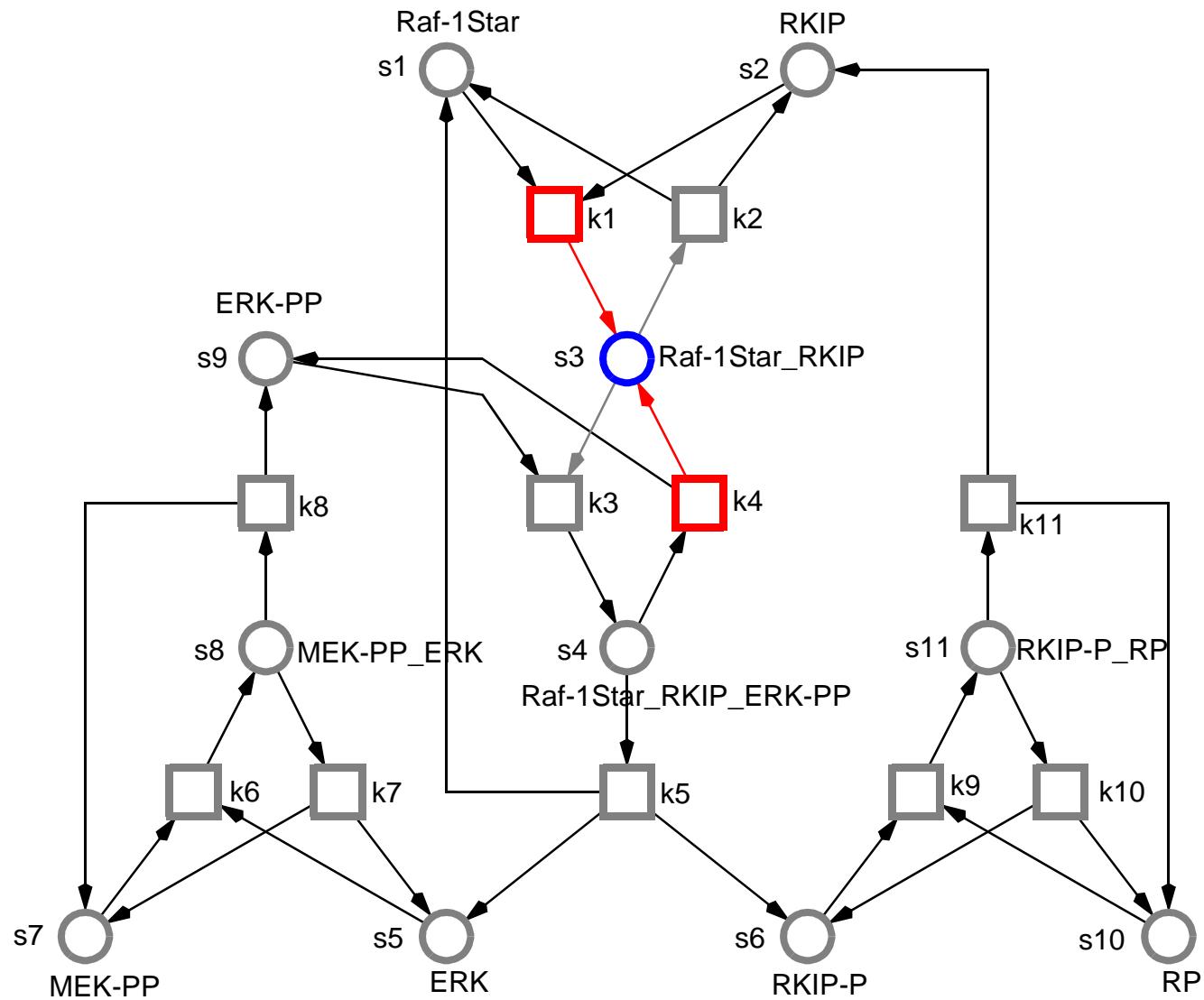
$$\frac{ds_3}{dt} =$$



# CONTINUOUS PETRI NET DEFINES ODEs

PN & BioModel Engineering

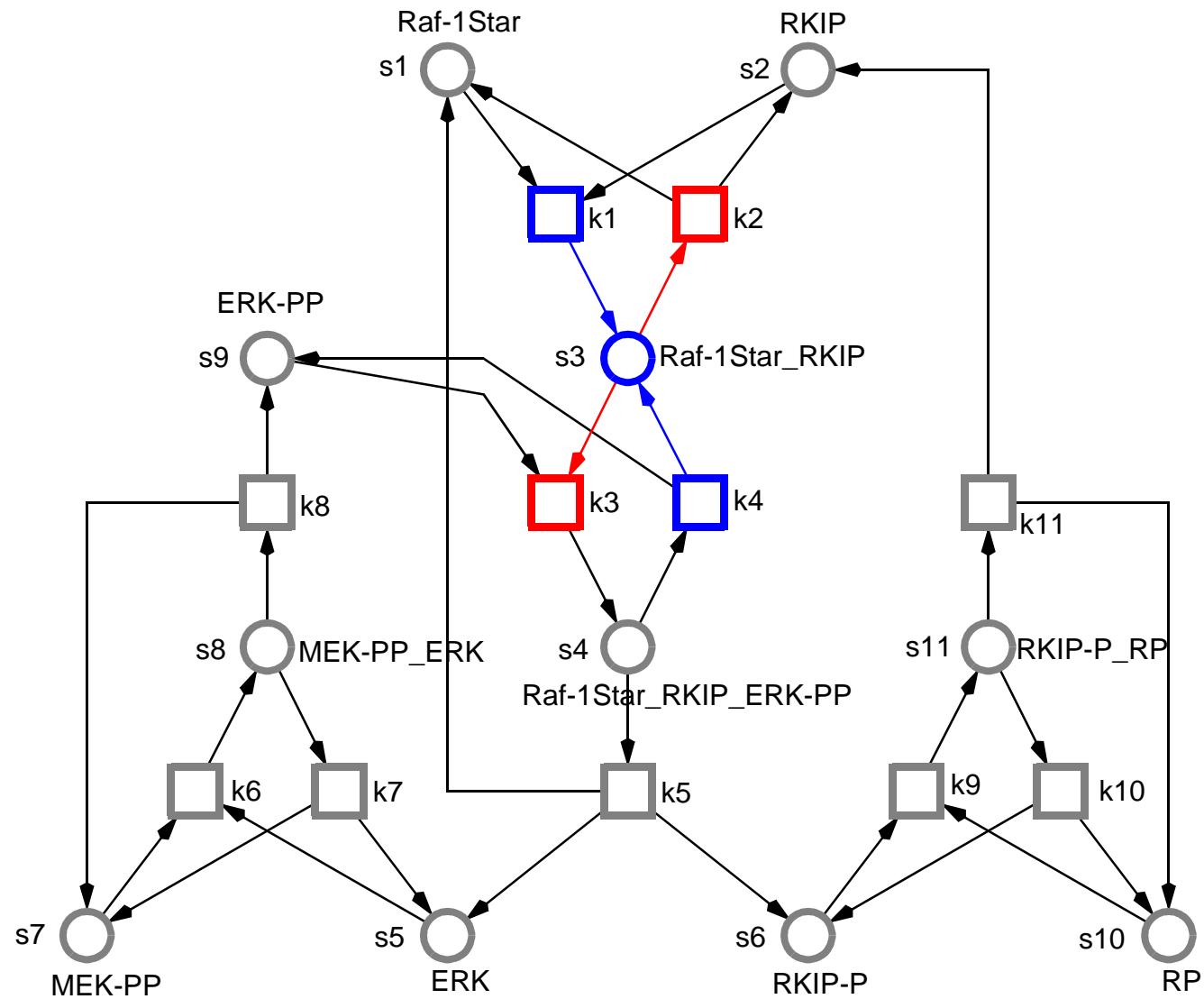
$$\frac{ds_3}{dt} = +v_1 \\ +v_4$$



# CONTINUOUS PETRI NET DEFINES ODEs

PN & BioModel Engineering

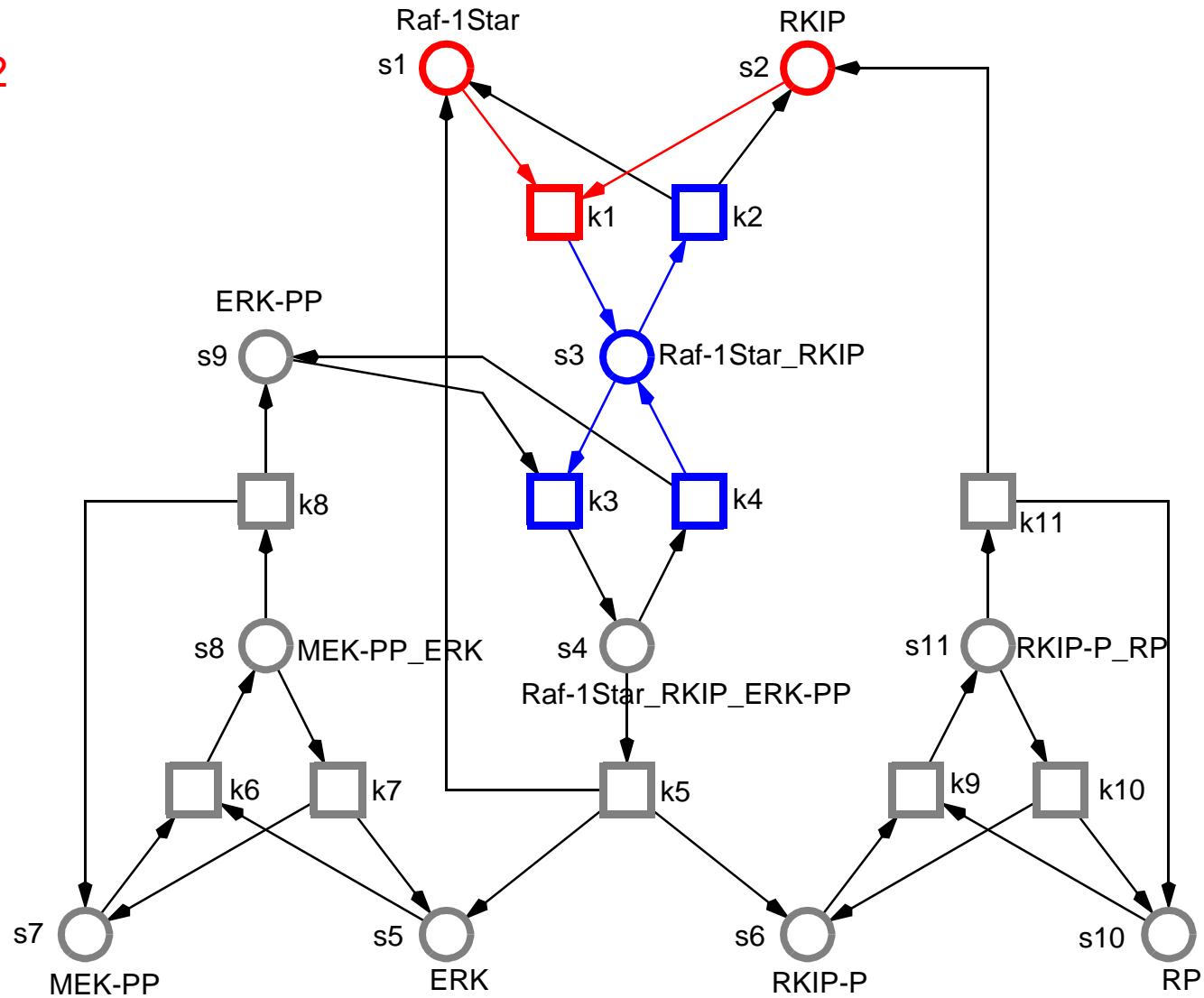
$$\frac{ds_3}{dt} = +v_1 \\ +v_4 \\ -v_2 \\ -v_3$$



# CONTINUOUS PETRI NET DEFINES ODEs

PN & BioModel Engineering

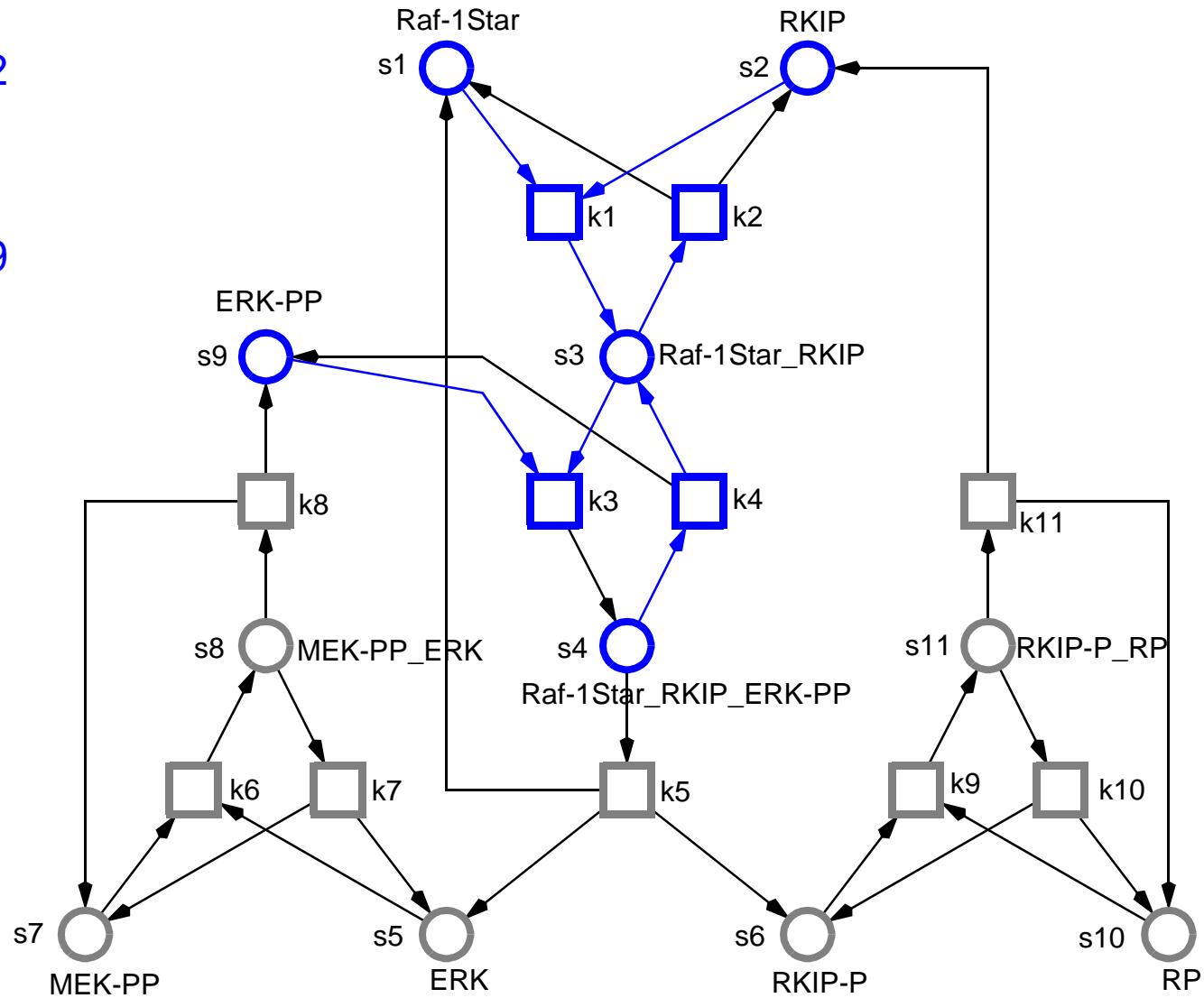
$$\frac{ds_3}{dt} = + k_1 * s_1 * s_2 \\ + v_4 \\ - v_2 \\ - v_3$$



# CONTINUOUS PETRI NET DEFINES ODEs

PN & BioModel Engineering

$$\frac{ds_3}{dt} = + k_1 * s_1 * s_2 \\ + k_4 * s_4 \\ - k_2 * s_3 \\ - k_3 * s_3 * s_9$$





**GHPN = XSPN + CPN**

[HERAJY, HEINER 2010]

□ **XSPN - Extended Generalized Stochastic Petri Nets**

- > *discrete places*
- > *discrete transitions: stochastic, immediate, deterministically delayed, scheduled*
- > *special arcs: read, inhibitor, equal, reset*

□ **CPN - Continuous Petri Nets**

- > *continuous places*
- > *continuous transitions*
- > *special arcs: read, inhibitor*

□ **hybrid simulation engine**

- > *static partitioning*
- > *dynamic partitioning*

